

## Towards a Modular Multi-Conformance (Meta-)Modelling Framework

By Andrei Bondarenko

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## **About Me**

#### 2<sup>nd</sup> year master's student at the UA specialising in Data Science and Artificial Intelligence





## Outline

- Why?
- What?
- How?
  - (Modular) Meta-Modelling
  - Framework
  - Implementation/Bootstrapping
- Summary of Contributions
- Future Work





#### What is the problem?





#### Modelling complex systems

- Systems are growing in:
  - Size

4

- Complexity
- Context diversity is increasing



[1]



#### Encapsulated Petrinets :Encapsulated Petrinets :CombinePN :Petrinets Petrinets :Encapsulated Petrinets :ToSafetyReg :BuildRG :Encapsulated Reachability Petrinets Graph :Reachability CTL Graph :CTL :Network Formalism :CheckReachable State :Requirements :Boolean Diagram Boolean [1]

#### Modelling complex systems

- Systems are growing in:
  - Size
  - Complexity
- Context diversity is increasing

#### Models

- Number of models increases
- Size of models increases
- Heterogeneity of models increases
  - Storage
  - Algorithms
  - Domain-specific implementations





#### Modelling complex systems

- Systems are growing in:
  - Size
  - Complexity
- Context diversity is increasing

#### Models

Number of models increases

CTL

Boolean

Encapsulated Petrinets

Petrinets

Reachability

Graph

<u>Encapsulated</u> Petrinets

Encapsulated Petrinets

:Encapsulated

Petrinets

:Network Formalism

:Requirements

Diagram

- Size of models increases
- Heterogeneity of models increases
  - Storage
  - Algorithms
  - Domain-specific implementations

#### Framework

:ToSafetyRed

:CTL

Uniform and efficient access/interaction

:CombinePN

Check Reachable State :Petrinets

:Reachability

Graph

:Boolean

[1]

:BuildRG

- Does not exist
- Reimplementation of domain-specific storage and algorithms
- Inefficient storage
- Hit in performance
- Impossible if proprietary
- Communication with external services not transparent



[1] Lúcio, Levi & Amrani, Moussa & Dingel, Juergen & Lambers, Leen & Salay, Rick & Selim, Gehan & Syriani, Eugene & Wimmer, Manuel. (2014). Model Transformation Intents and Their Properties. Software & Systems Modeling. 15. 10.1007/s10270-014-0429-x.

# What?

#### What do we need to solve the problem?







#### Scalability

 Harmonise heterogeneous models **FRAMEWORK** 

- Management
- Interaction
- Easy extension with new model types
  - Efficient development
- Transparent to users

# FRAMEWORK

#### Scalability

- Harmonise heterogeneous models
  - Management
  - Interaction
- Easy extension with new model types
  - Efficient development
- Transparent to users

- Allow for integration of existing implementations/services
  - Efficient storage

Reuse

- Optimised performance
- Proprietary implementations
- Decreased development time

#### **Scalability**

- Harmonise heterogeneous models
  - Management
  - Interaction
- Easy extension with new model types
  - Efficient development
- Transparent to users

#### Reuse

 Allow for integration of existing implementations/services

FRAMEWORK

- Efficient storage
- Optimised performance
- Proprietary implementations
- Decreased development time

#### **Explicit development process**

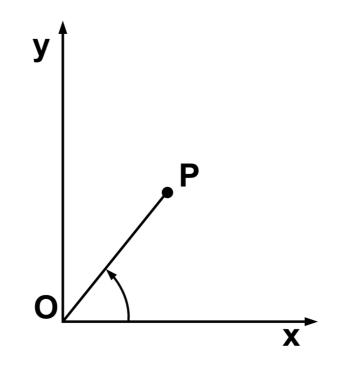
- Explicitly documented development process
  - Less time spent reverse engineering
  - Interested readers are up to speed quickly
  - Starting point for future contributions



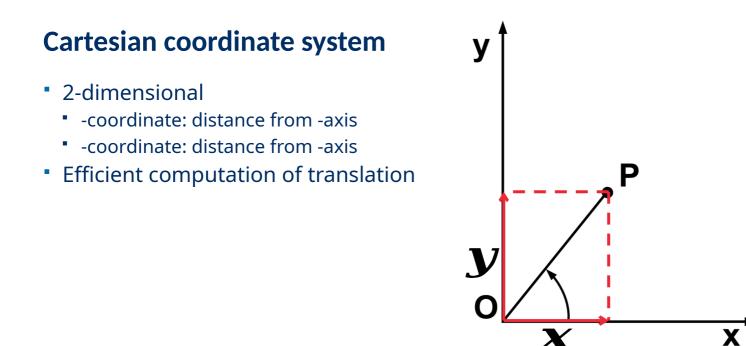


#### How did we solve the problem?







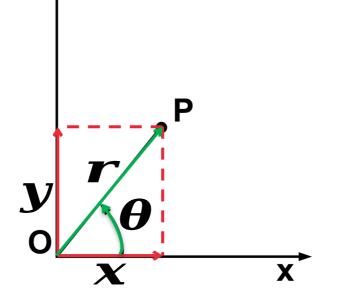




V

#### Cartesian coordinate system

- 2-dimensional
  - -coordinate: distance from -axis
  - -coordinate: distance from -axis
- Efficient computation of translation



#### Polar coordinate system

- 2-dimensional
  - -coordinate: distance from pole/origin
  - -coordinate: angle between ray and polar axis
- Efficient computation of rotation

V

Ρ

 $\mathbf{x} = \mathbf{r} \cdot \mathbf{cos}(\boldsymbol{\theta})$  $\mathbf{v} = \mathbf{r} \cdot \mathbf{sin}(\boldsymbol{\theta})$ 

Χ

#### Cartesian coordinate system

- 2-dimensional
  - -coordinate: distance from -axis
  - -coordinate: distance from -axis
- Efficient computation of translation

## $r = \sqrt{x^2 + y^2}$ $\theta = \arctan\left(\frac{y}{x}\right)$

#### **Polar coordinate system**

- 2-dimensional
- -coordinate: distance from pole/origin
- -coordinate: angle between ray and polar axis
- Efficient computation of rotation

#### Meta-Modelling (Language Engineering)

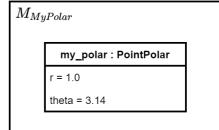
#### Define linguistic type model (LTM)

- Concepts
- Concept structures
- Interrelationships

LTI	$M_{Cartesian}$		$L_{2}^{\prime}$
	PointCartesian : Class		
	x: Float		
	y: Float		

PointPolar :	Class
: Float	
theta: Float	

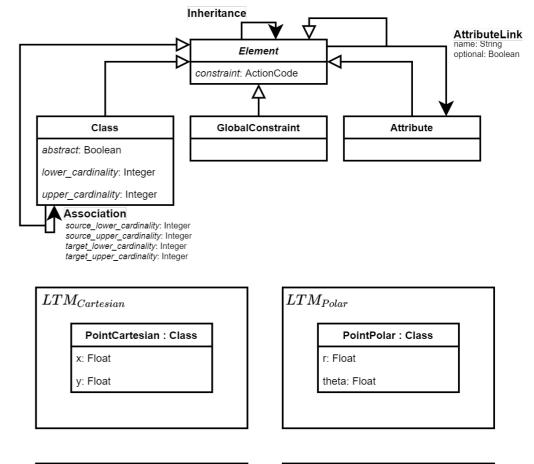
$M_{MyCartesian}$			$M_{MyPolar}$		
	my_cart : PointCartesian			my_p	
	x = 1.0			r = 1.0	
	y = 0.0			theta = 3	

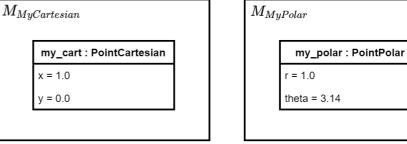




## Meta-Modelling (Language Engineering)

- Define linguistic type model (LTM)
  - Concepts
  - Concept structures
  - Interrelationships
- Described using a meta-language
  - Simplified form of UML class diagrams

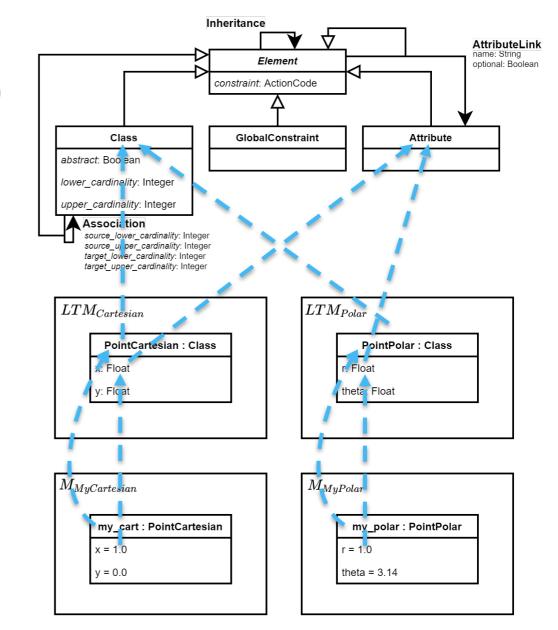






## Meta-Modelling (Language Engineering)

- Define linguistic type model (LTM)
  - Concepts
  - Concept structures
  - Interrelationships
- Described using a meta-language
  - Simplified form of UML class diagrams
- Type/instance relationship
  - By construction (instantiation)
  - A posteriori (conformance check)



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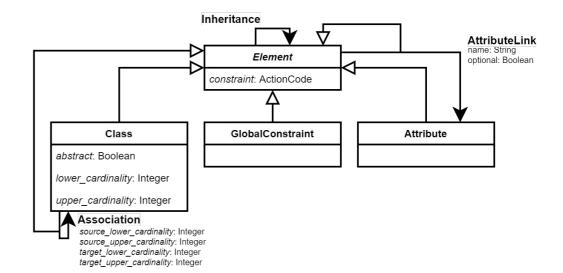
# **Modular Meta-Modelling**

**Contribution 1** 



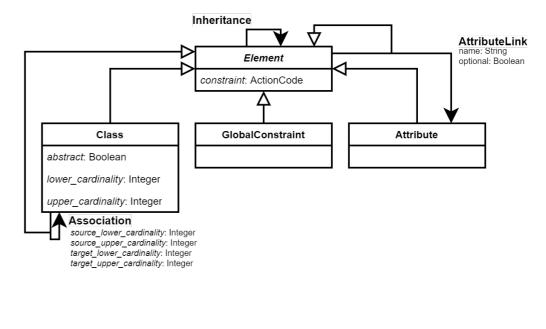
## **Modular Meta-Modelling**

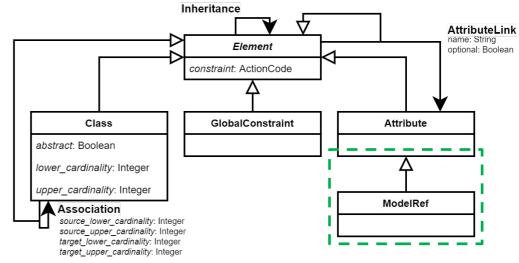
- Modelverse's meta-language ()
  - Redefinition of (primitive) types in each LTM



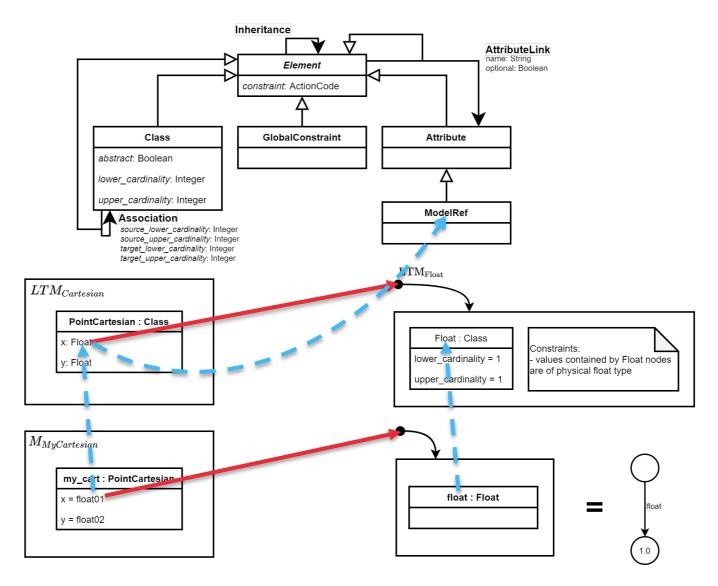
## **Modular Meta-Modelling**

- Modelverse's meta-language ()
  - Redefinition of (primitive) types in each LTM
- Proposed meta-language
  - Allow references to other models
  - Enables modular composition





## **Modular Meta-Modelling: Example**



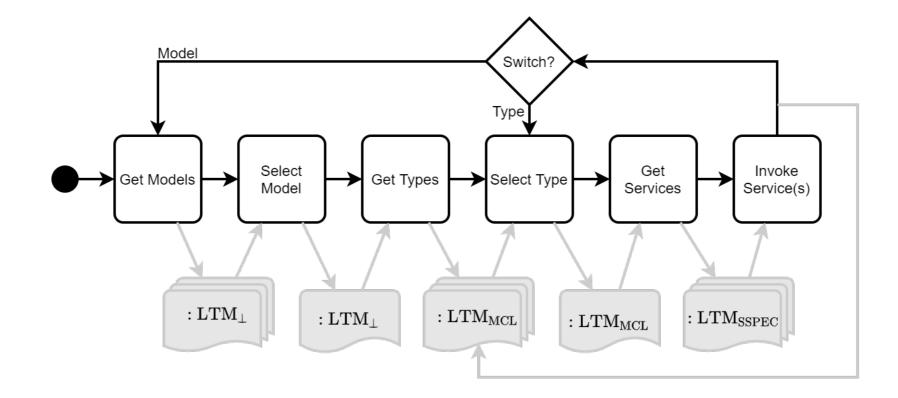


## Multi-Conformance Meta-Modelling Framework

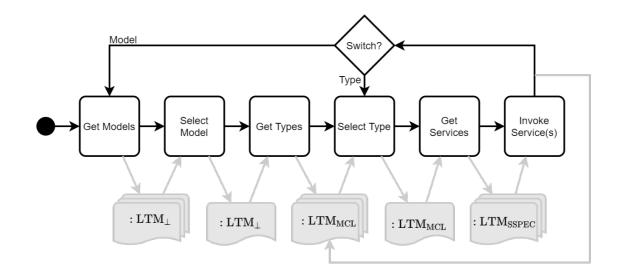
**Contribution 2** 



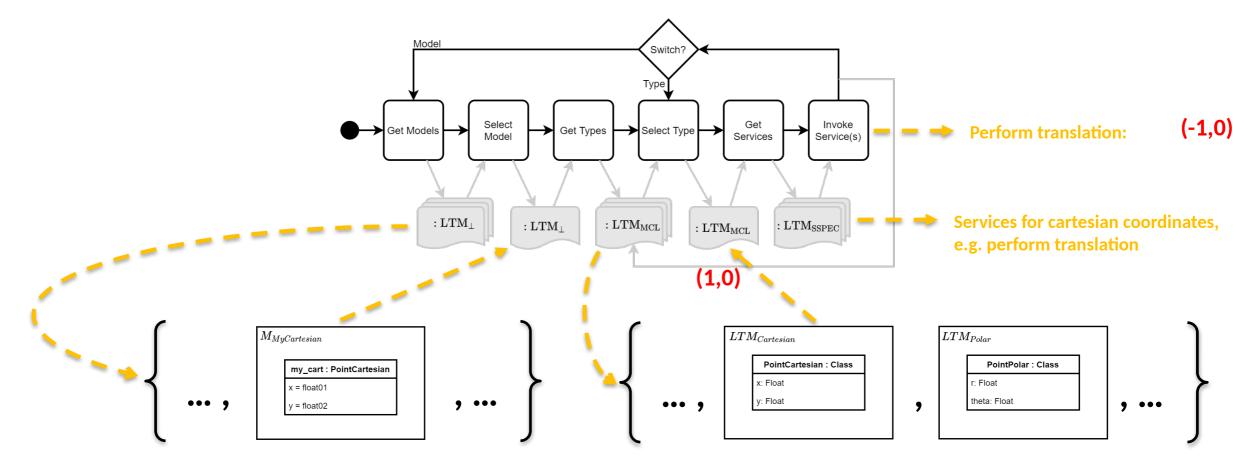
### **Framework: Workflow**



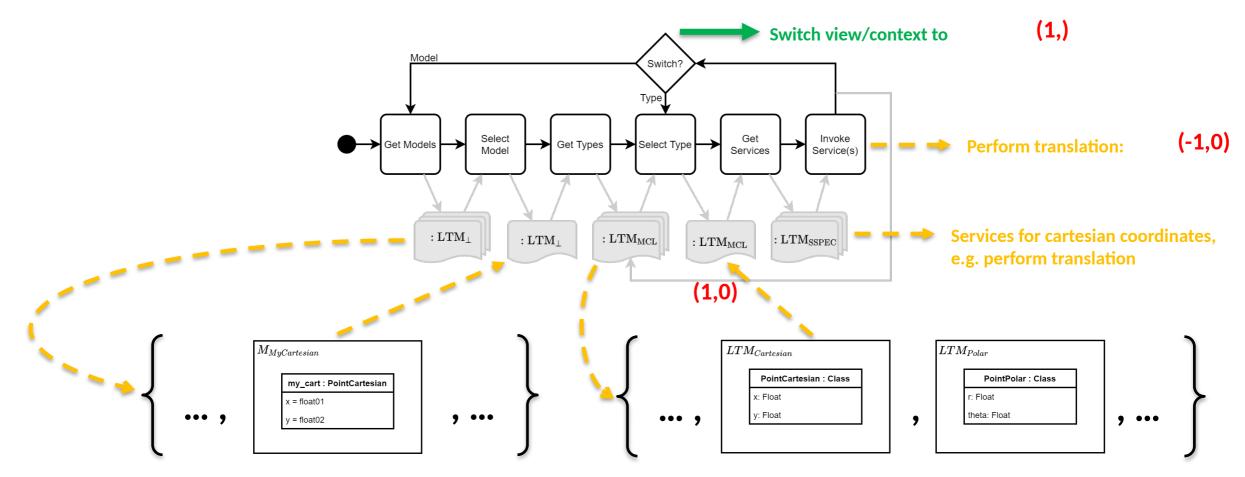


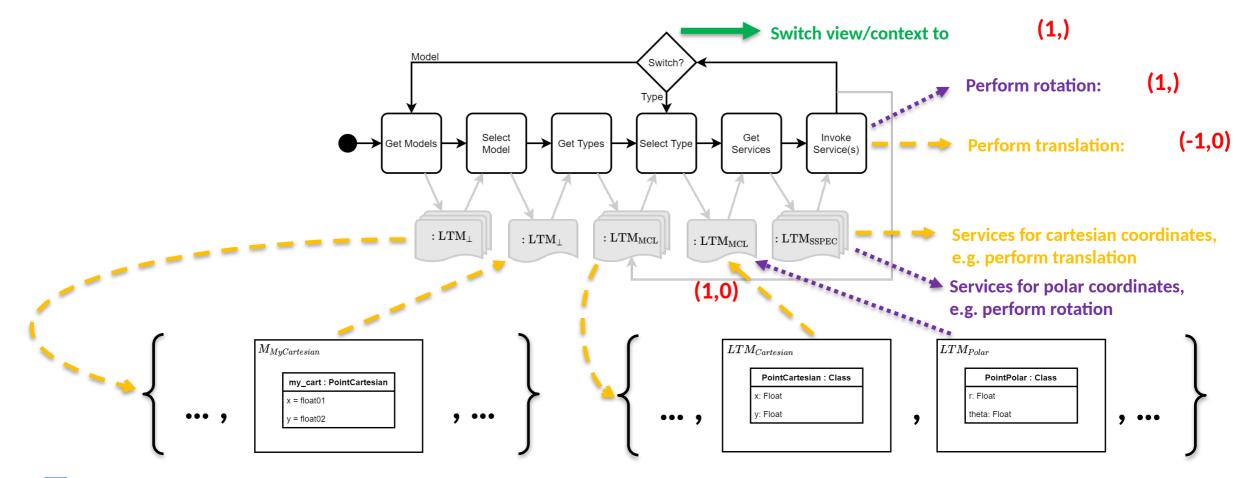




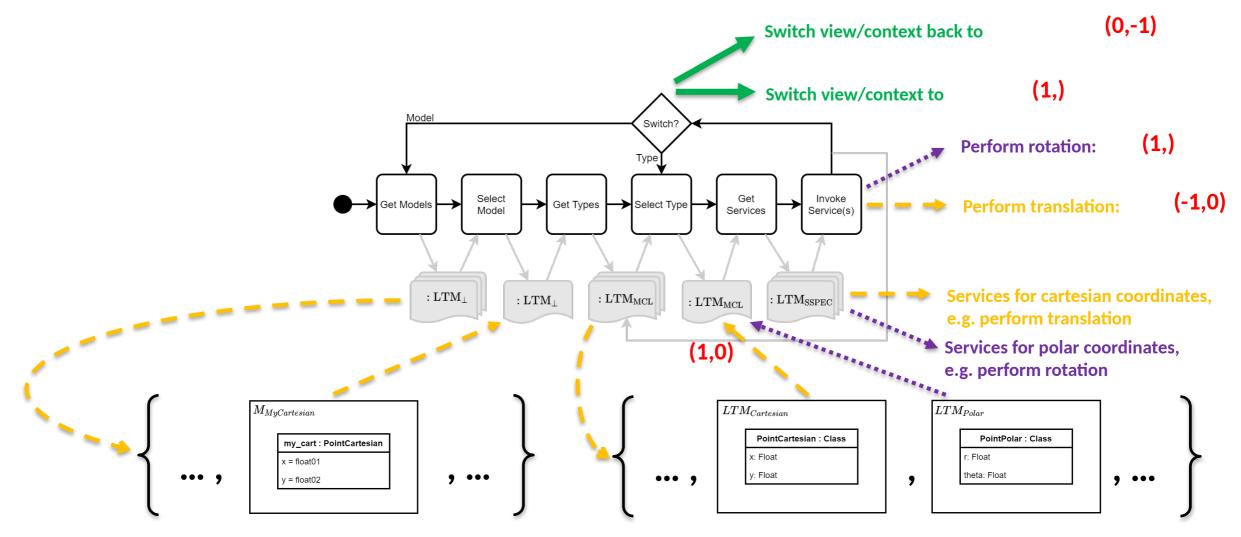


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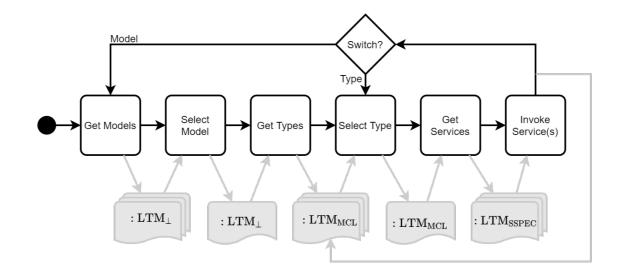






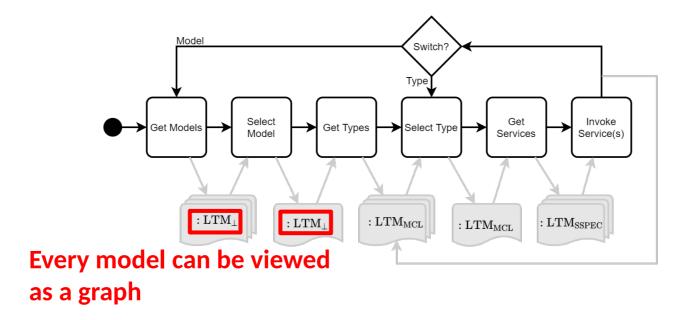


#### Framework: Multi-Conformance, Scalability and Reuse





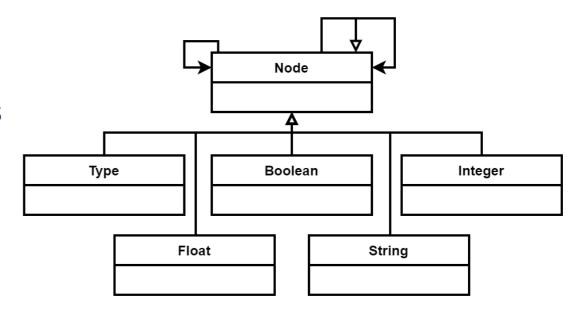
## Framework: Multi-Conformance, Scalability and Reuse





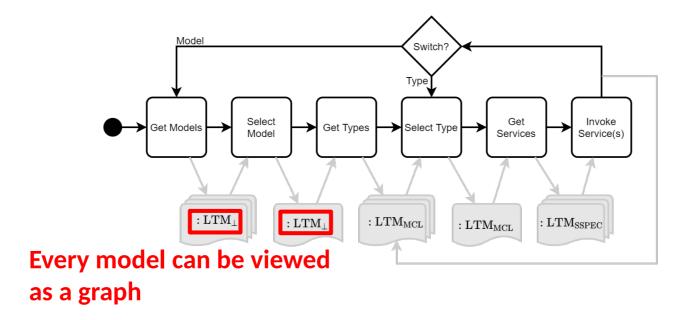
## **Linguistic Type Model** 0

- Explicit representation of the physical type model
  - Directed graph
  - Nodes and edges connected via edges
  - Nodes are empty or contain primitive values
- Axiom: every model conforms to
  - Canonical representation
  - Bootstrapping starting point
    - Decouple implementation/algorithms from internal data structure
  - Support for mega-modelling

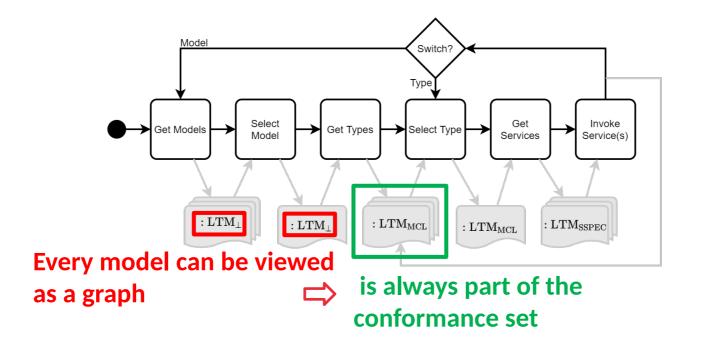




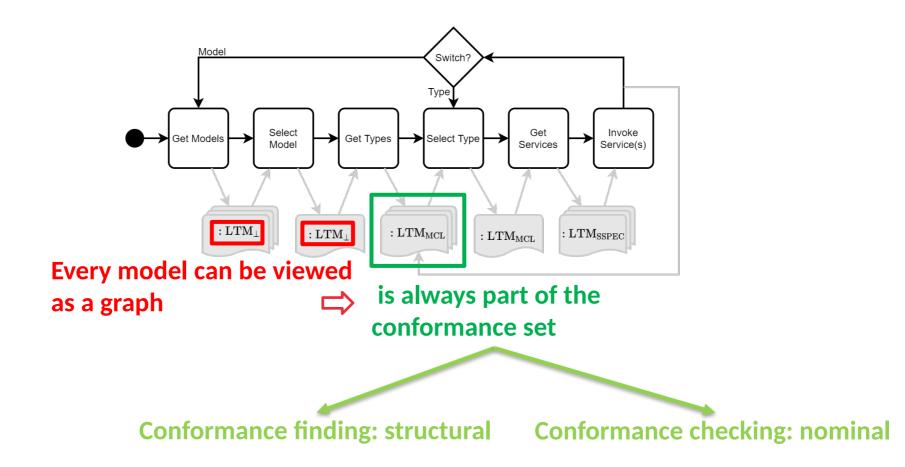
## Framework: Multi-Conformance, Scalability and Reuse



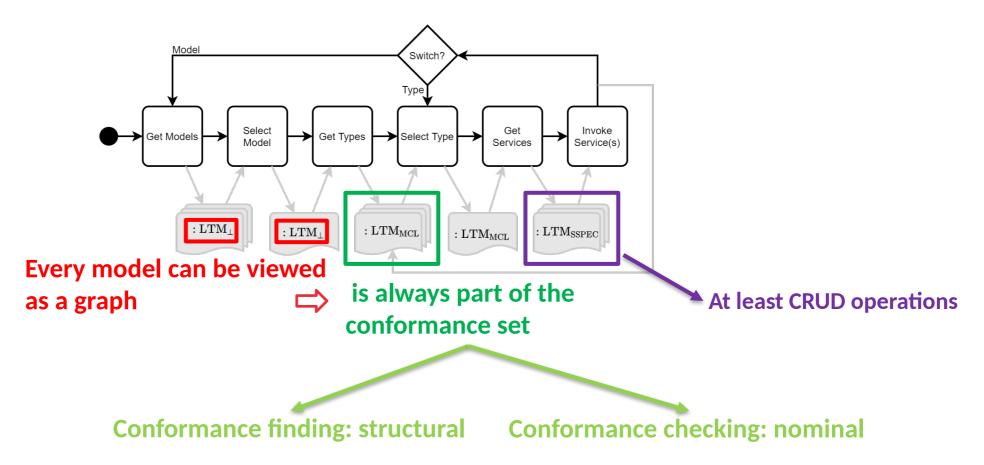




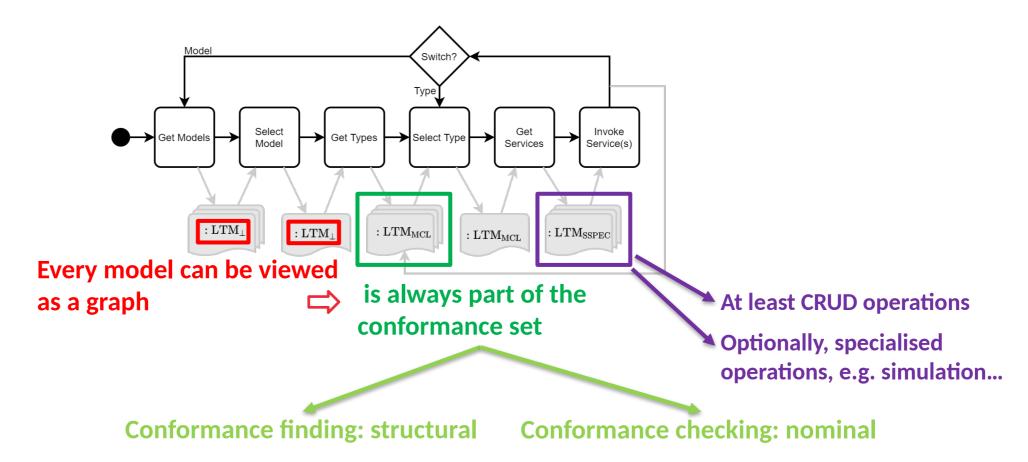




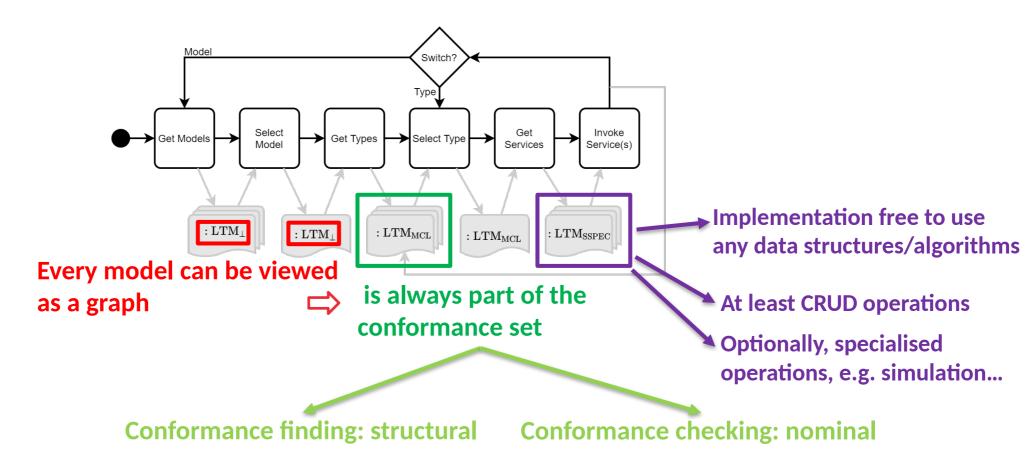




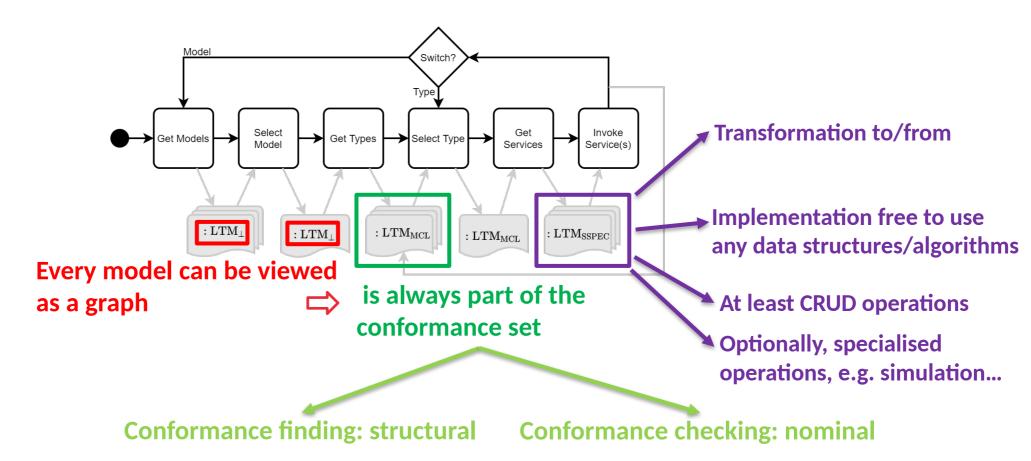




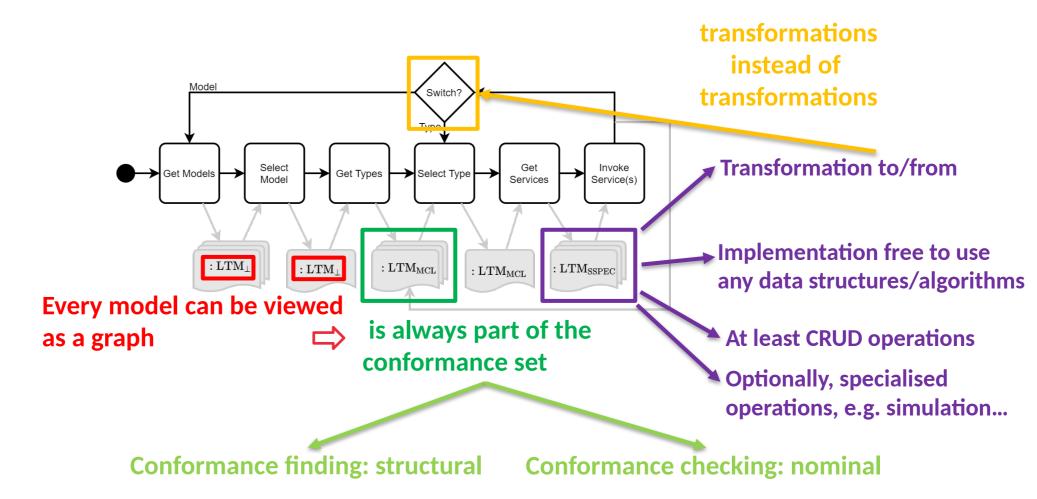












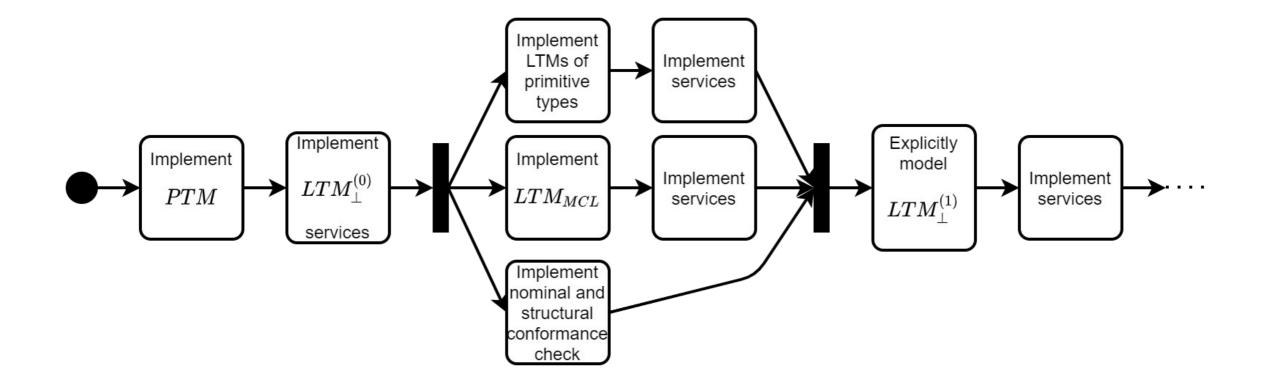


# **Explicit Development Process**

**Contribution 3** 



### Implementation/Bootstrapping Workflow





### **Summary of Contributions**

- Meta-language / with support for modular composition
- Meta-modelling framework
  - Heterogeneous model storage and service implementation
  - Canonical graph representation
    - Multi-conformance
    - Context switching

#### Explicitly described implementation workflow



### **Future Work**

- Addition of model transformations (reimplementation of RP2)
  - Allows definition of translational and operational semantics
  - Full fledged language engineering environment
- Continue the implementation/bootstrapping cycle
  - Start bootstrapping the framework within itself
- Efficient computation of conformance set
  - For each model
  - Incrementally





# Thank you for you attention

**Questions?**