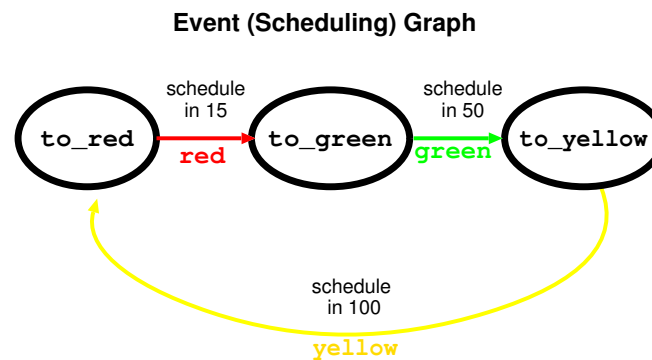
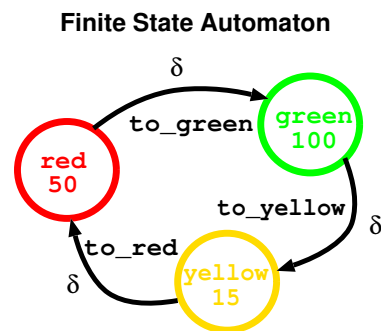
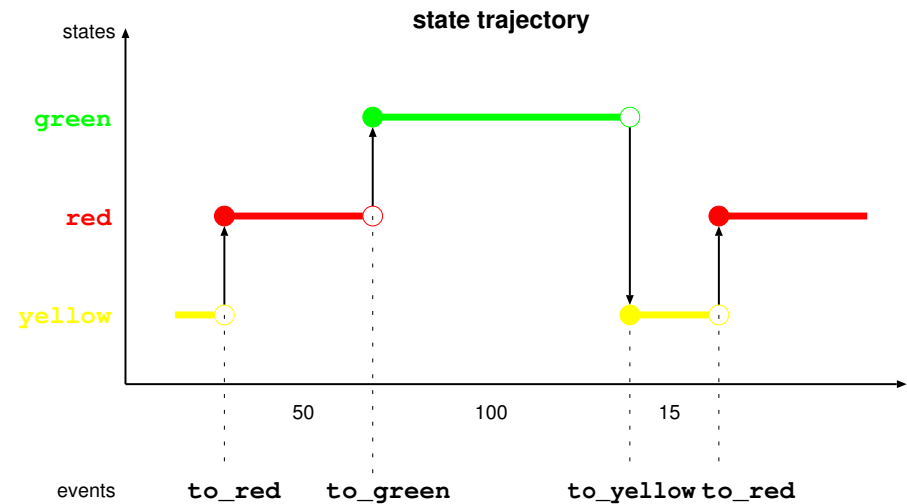


Timed Discrete Event Modelling and Simulation

- extend State Automata with “time in state”
- equivalent to Event Graphs “time to transition”

⇒ *schedule events*

(timed) Discrete Event Models



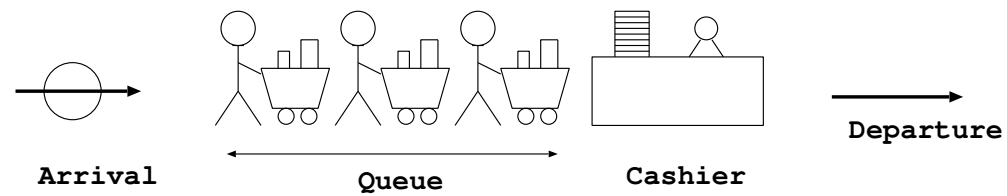
Discrete Event Modelling and Simulation

- Model : objects and relationships among objects
- Object : characterized by attributes to which values can be assigned
- Attributes:
 - indicative
 - relational
- Values: of a type

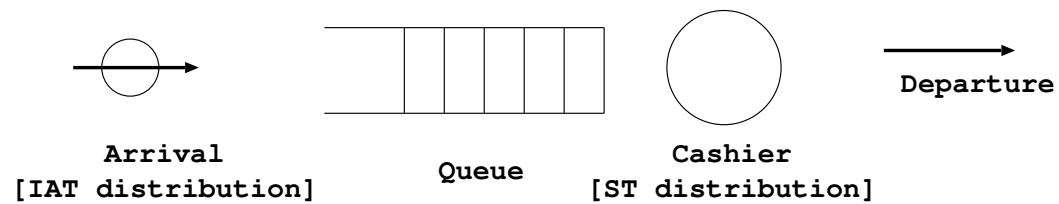
Time and State Relationships

- Indexing Attribute: enables state transitions
Time is most common.
- Instant: value of System Time at which the value of at least one attribute of an object can be assigned.
- Interval: duration between two successive instants.
- Span: contiguous succession of one or more intervals.
- State of an object: enumeration of all attribute values at a particular instant.
- State of the system: all object states at a particular instant.

Single Server Queueing System

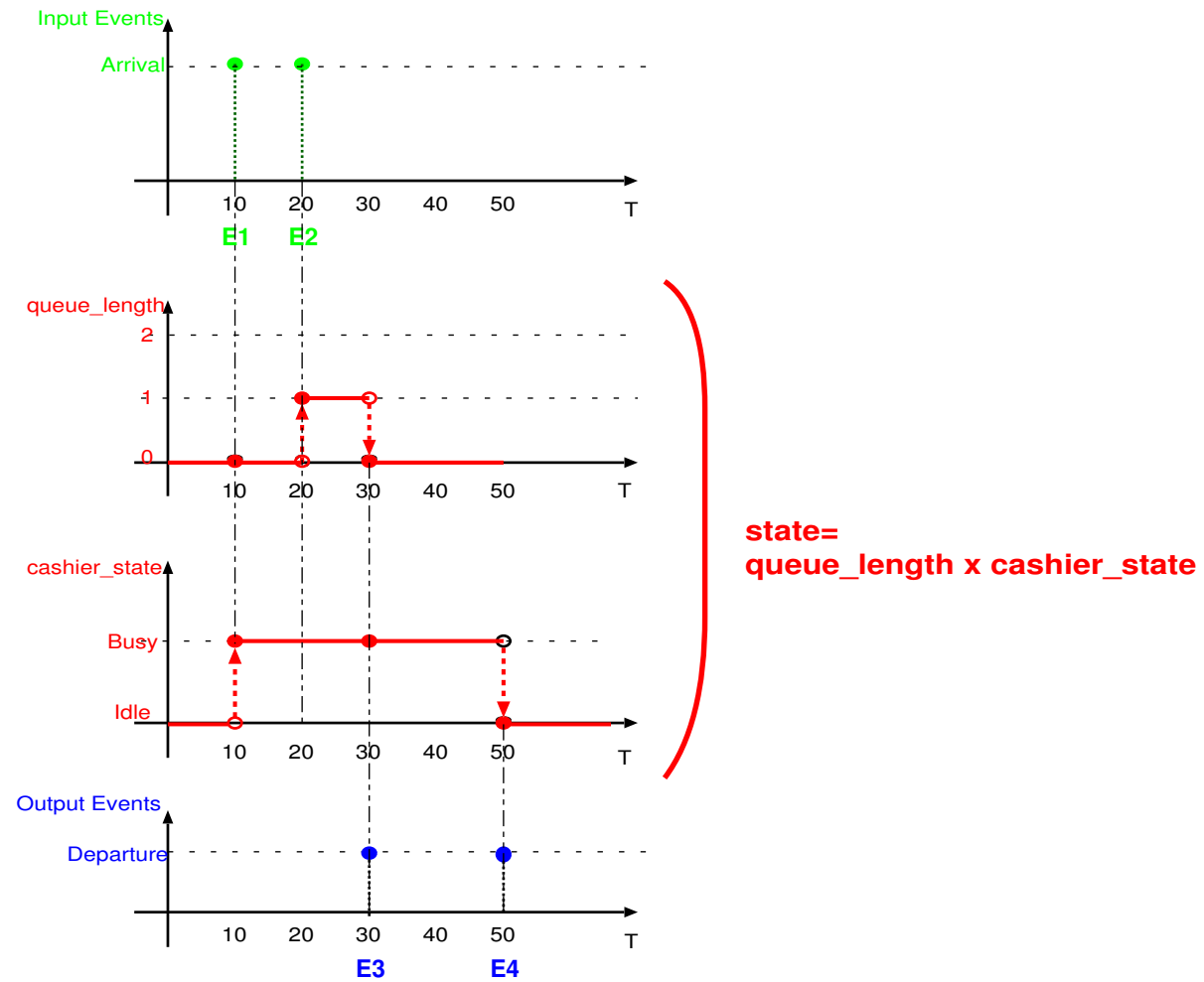


Physical View



Abstract View

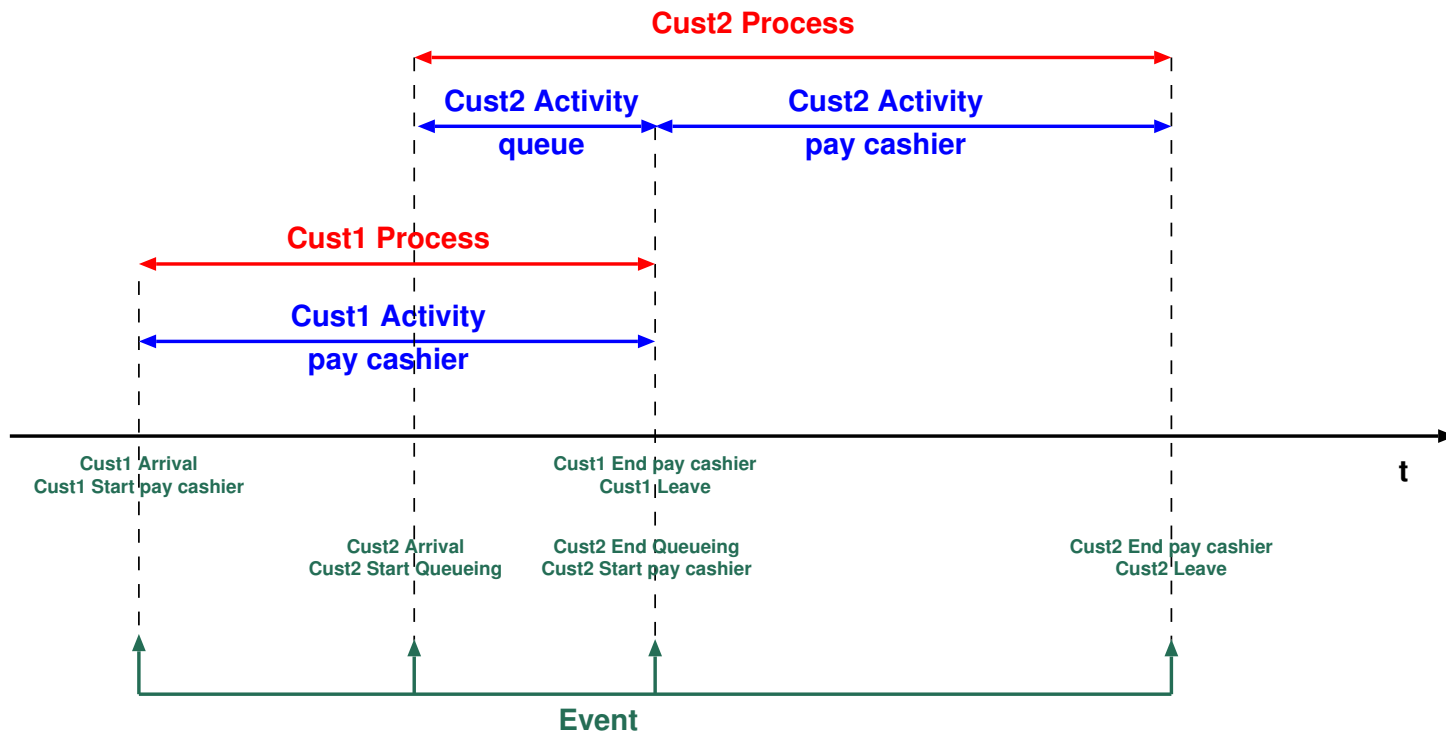
Queueing System State Trajectory



Time and State Relationships

- Activity: state of an object over an interval
- Event: change in object state, occurring at an instant.
Initiates an activity
 - Determined: occurrence based on time (“time event”)
 - Contingent: based on system conditions (“state event”)
- Object activity: state of object between two events for that object
- Process: succession of states of object over a span

Event/Object Activity/Process



Event Scheduling

- Identify *objects* and their *attributes*
- Identify *system attributes* (global)
- Define what causes *changes* in attribute value as *event*
- Write *event routine* for each event:
 - *modify state* (attributes)
 - *schedule event(s)* at $t + \Delta t, \Delta t \geq 0$
- Priorities for *tie-breaking*
- Event scheduling logic

Cashier-queue Event Scheduling Model

```
declare variables:
  t          : Time
  queue_length : PosInt
  cashier_state : {Idle, Busy}

declare events:
  start, arrival, departure, end

define events:

  start event:
    /* scheduled first automatically by simulator */

    /* initializations */
    queue_length = 0
    cashier_state = Idle

    /* schedule end of simulation */
    schedule end absolute end_time
```

```

/* schedule first arrival */
schedule arrival relative 0

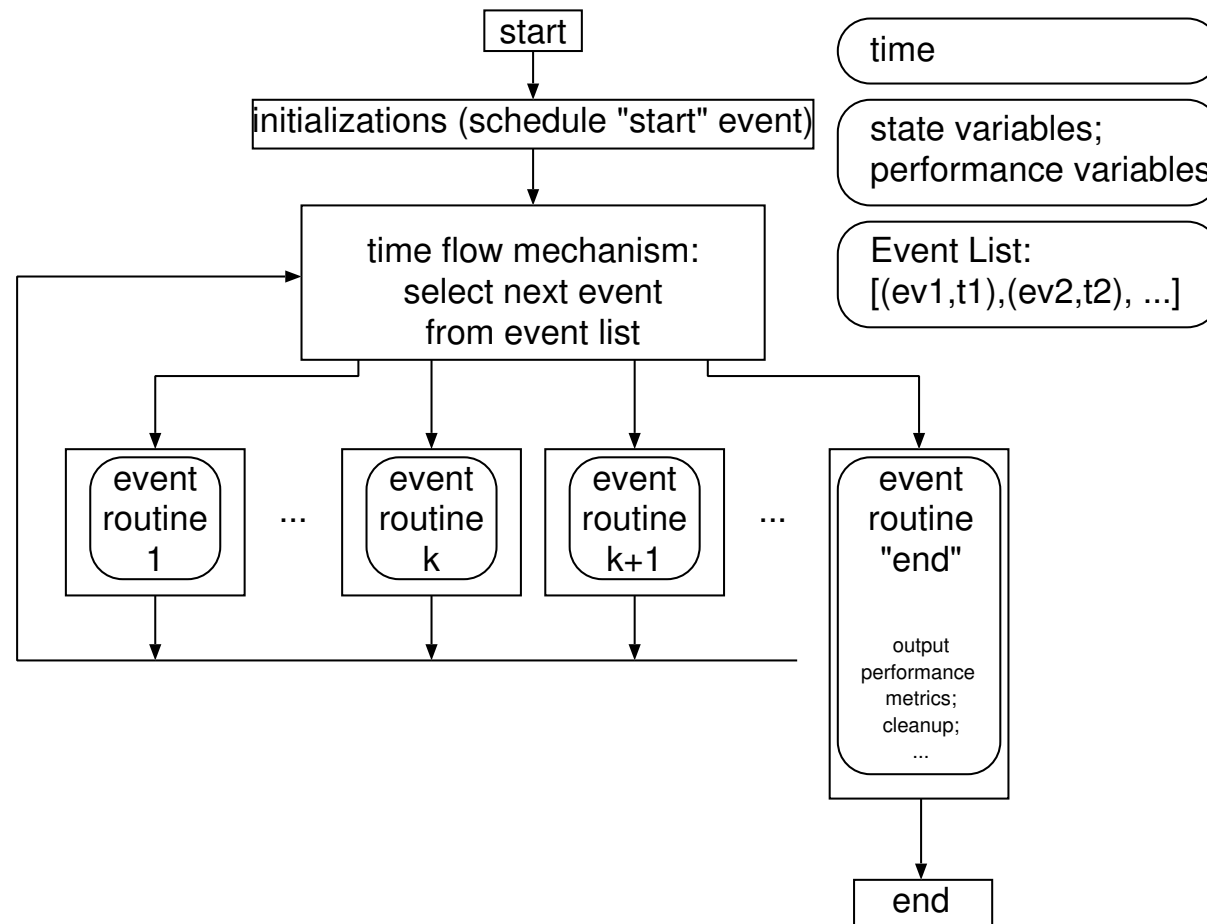
arrival event:
  schedule arrival relative Random(IATmean, IATspread)
  if (queue_length == 0)
    if (cashier_state == Idle)
      cashier_state = Busy
      schedule departure relative Random(SERVmean, SERVspread)
    else
      queue_length++
  else /* queue_length != 0 */
    queue_length++

departure event:
  if (queue_length == 0)
    cashier_state = Idle
  else /* queue_length != 0 */
    queue_length--
    schedule departure relative Random(SERVmean, SERVspread)

```

```
end event:  
  /* terminates simulation */  
  /* process/output performance metrics */  
  print time, queue_length /* current */  
  print average_queue_length
```

Event Scheduling Kernel

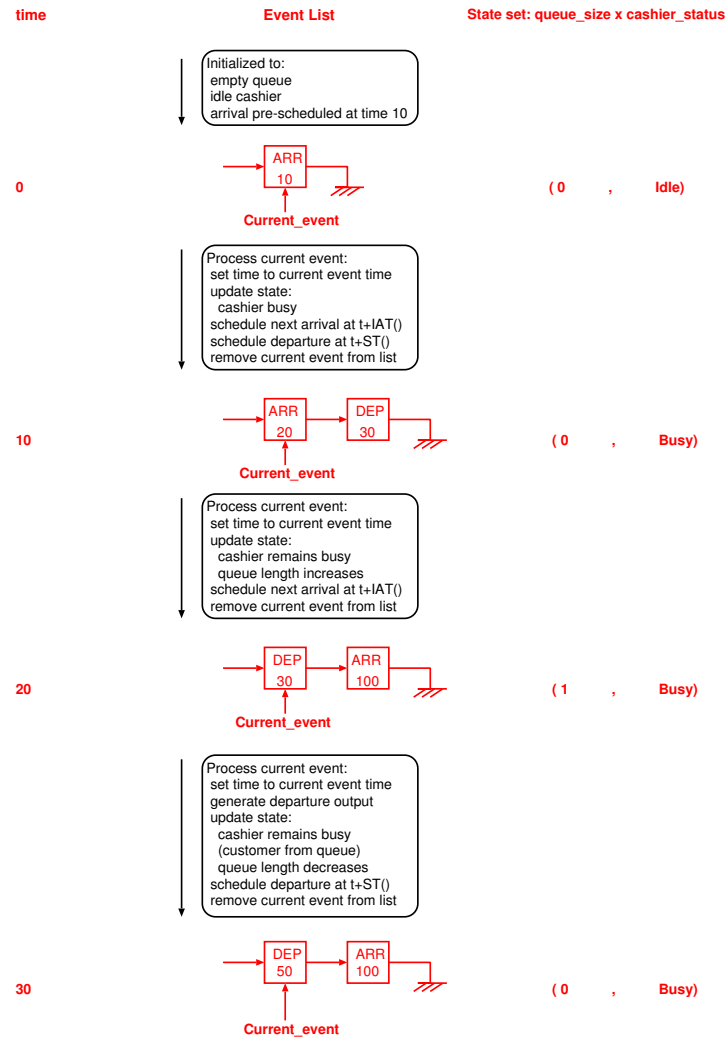


Input Generation

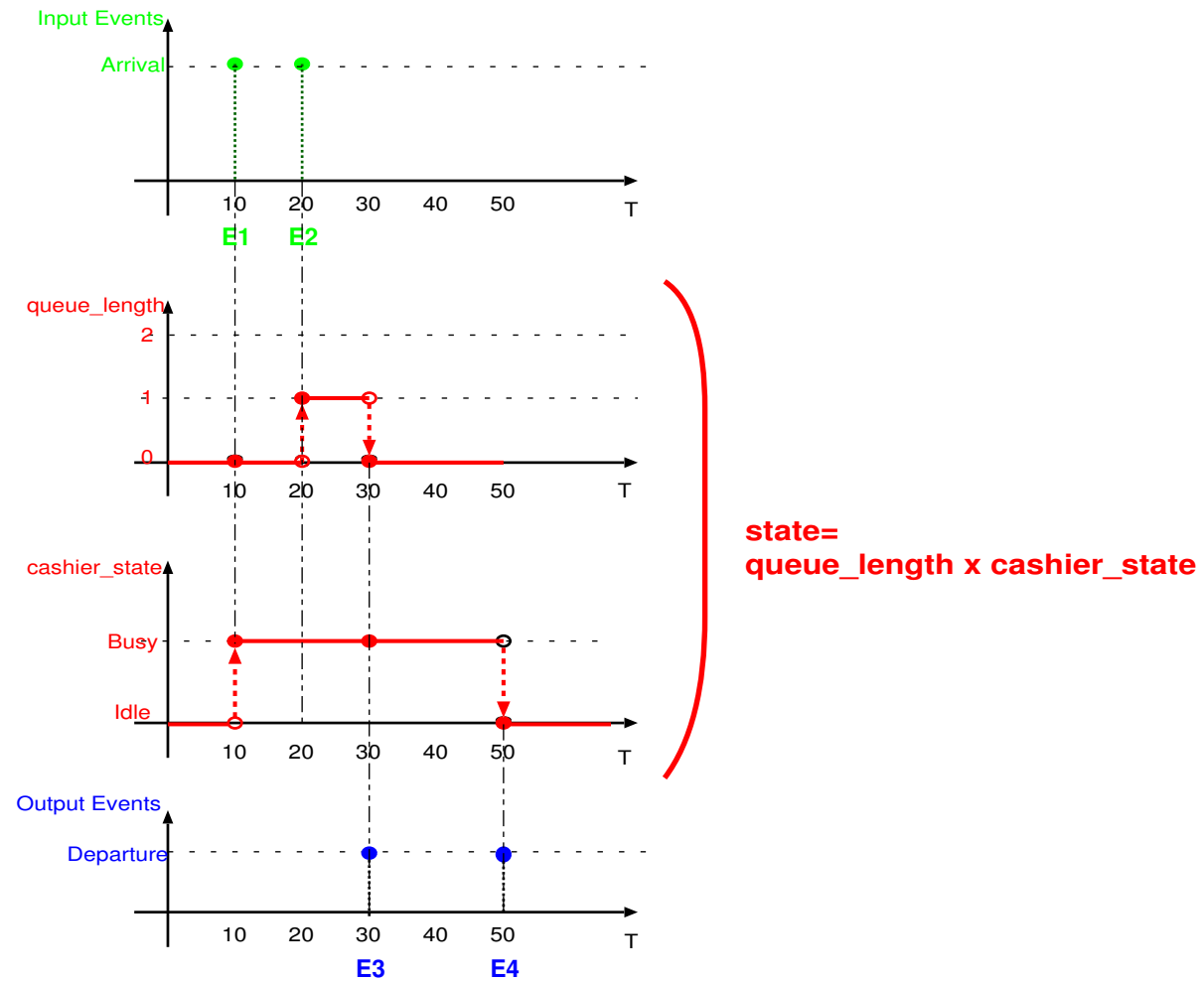
A “model” of input (sequence of Inter Arrival Times):

- Trace driven
- Auto generating (bootstrapping)

Cashier-queue Event List



Queueing System State Trajectory



Termination Conditions

- Empty Event List
 - Need to stop generating arrivals after t_{end} when auto-generating arrivals
- Schedule Termination Event
 - process statistics
 - cleanup
 - stop
 - *caveat*: process *all* final events !
 - * use reserved priority
 - * re-schedule
- Similarly: schedule initialization/setup

Event Scheduling (dis)advantages

- advantage: run-time efficient
- disadvantage: hard to understand model

Activity Scanning (rule-based)

Activity:

- condition: must be satisfied for activity to take place.
Becomes true *only* at event times.
- actions: operations performed when condition becomes true

Time-advance mechanism:

- fixed time-step

Also known as Two Phase Approach

Cashier-queue Activity Scanning Model

declare (and initialize) variables:

```
t           : Time
queue_length : PosInt = 0
cashier_state : {Idle, Busy} = Idle
t_arrival   : Time = 0
t_depart    : Time = plusInf
```

declare activities:

```
queue_pay, depart, end
```

queue_pay activity

```
condition: t >= t_arrival
```

actions:

```
if (queue_length == 0)
  if (cashier_state == Idle)
    keep queue_length == 0
    cashier_state = Busy
    t_depart = t + Random(SERVmean, SERVspread) /* service time */
  else
    queue_length++
```

```

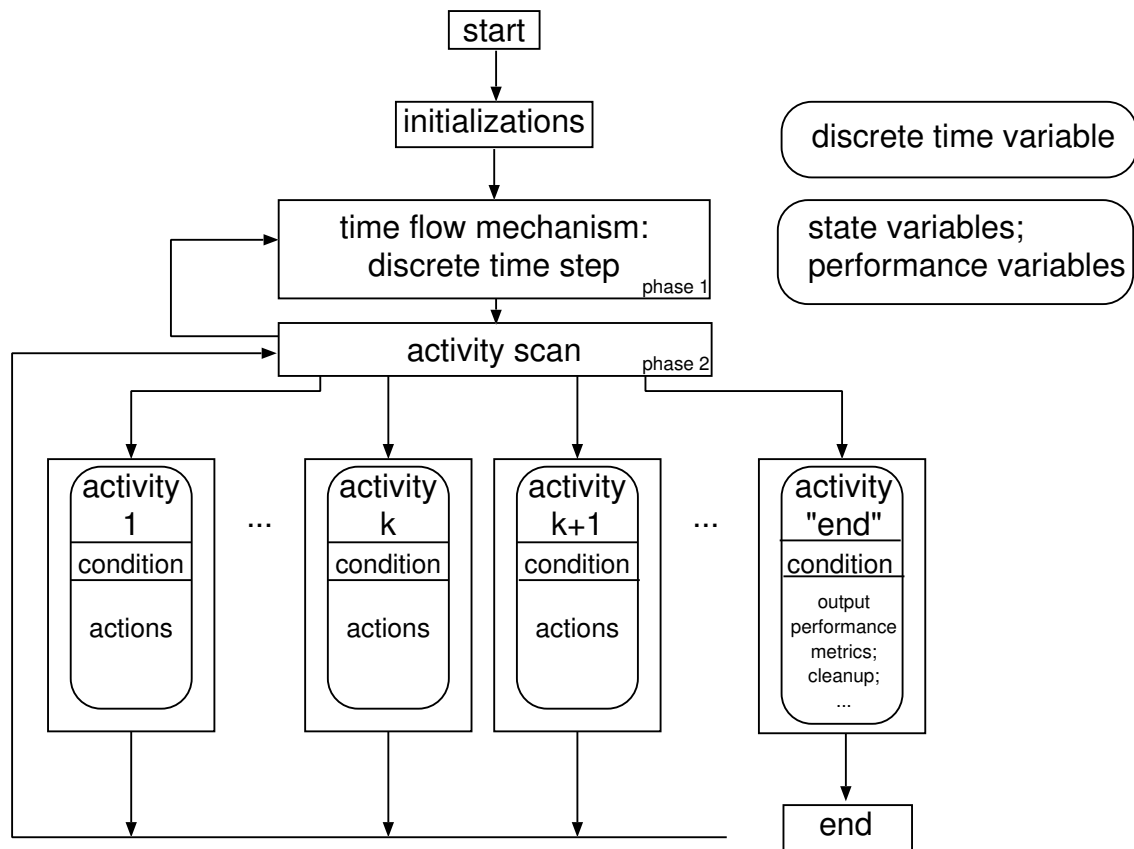
else /* queue_length != 0 */
    queue_length++, keep cashier_state == Busy
t_arrival = t + Random(IATmean, IATspread) /* inter arrival time */

depart activity
condition: t >= t_departure
actions:
    if (queue_length == 0)
        cashier_state = Idle
    else /* queue_length != 0 */
        queue_length--, keep cashier_state == Busy
        t_depart = t + Random(SERVmean, SERVspread) /* service time */

end activity
condition: t >= t_end
actions:
    print t, queue_length /* current */
    print avg_queue_length /* performance metric */

```

Activity Scanning



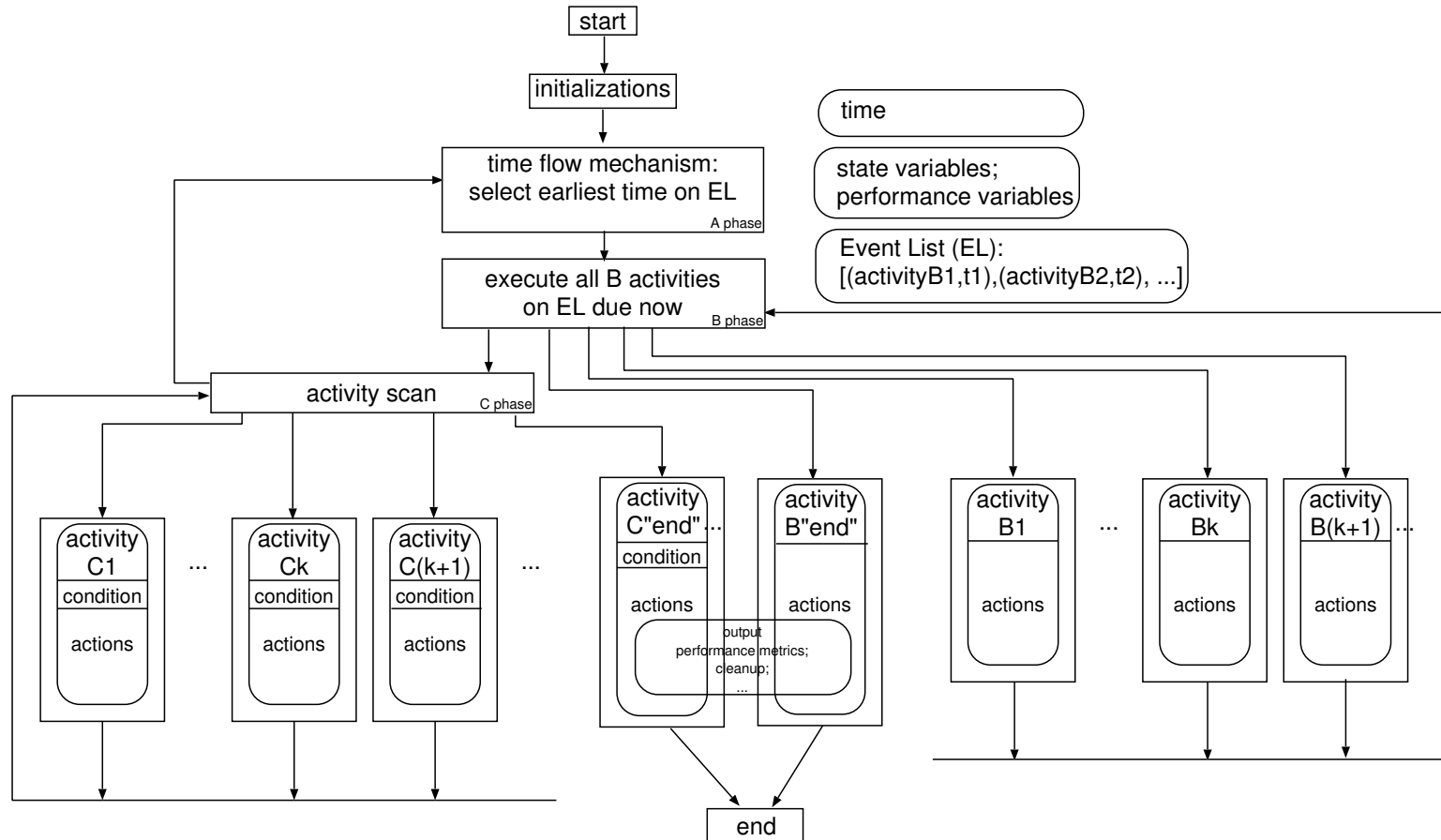
Activity Scanning (dis)advantages

- advantage: declarative model
- disadvantages:
 - inaccurate if changes occur in between time-steps
 - run-time inefficient (fixed time-step)

Three Phase Approach

- Bound to occur activities: unconditional state changes. Pre-scheduled.
- Conditional activities

Three Phase Approach



Three Phase Approach (dis)advantages

- advantage: performance added to Activity Scanning
- disadvantage: mixing two views

Process Interaction Simulation Kernel

- Thomas J. Schriber. *Simulation Using GPSS* “The Red Book”. Wiley, 1974.
- Thomas J. Schriber. *Simulation Using GPSS/H*. Wiley, 1990.
- <http://isgwww.cs.uni-magdeburg.de/~pelo/s1e/sa5/sa52.shtml>
- **GPSS World** <http://www.minutemansoftware.com/>
- **AToM³ modelling GUI** <http://atom3.cs.mcgill.ca/>

GPSS Process Interaction Simulation Kernel

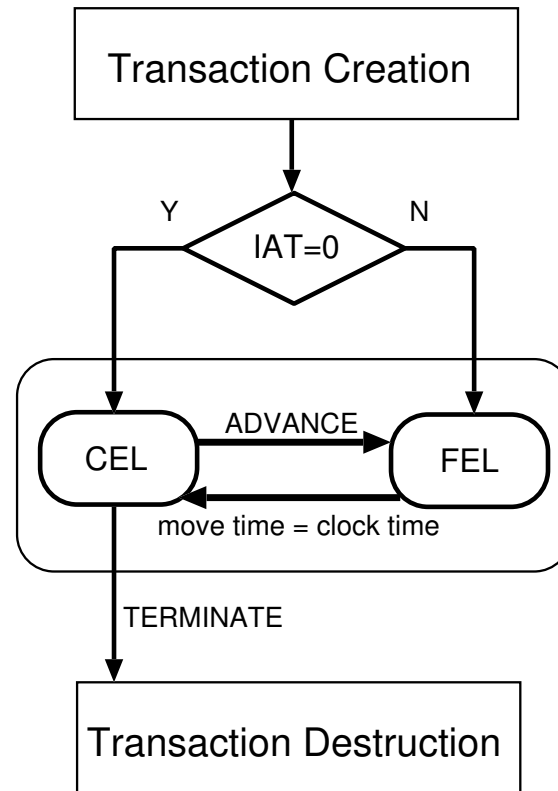
Data Structures: *chains*. A transactions is on *exactly one* chain at a time !

- (1) Current Events Chain (CEC):
Transactions, waiting for a condition, at current time.
- (1) Future Events Chain (FEC):
Transactions waiting for a known future time.
- (0 ... n) User Chain (UC):
Transactions waiting to be UNLINKed by a user transaction.
- (0 ... m) Interrupt Chain (IC):
Transactions waiting for the end of an interrupt.
- (0 ... p) Match Chain (MC):
Transactions waiting for a (Match, Assemble, Gather) rendezvous.

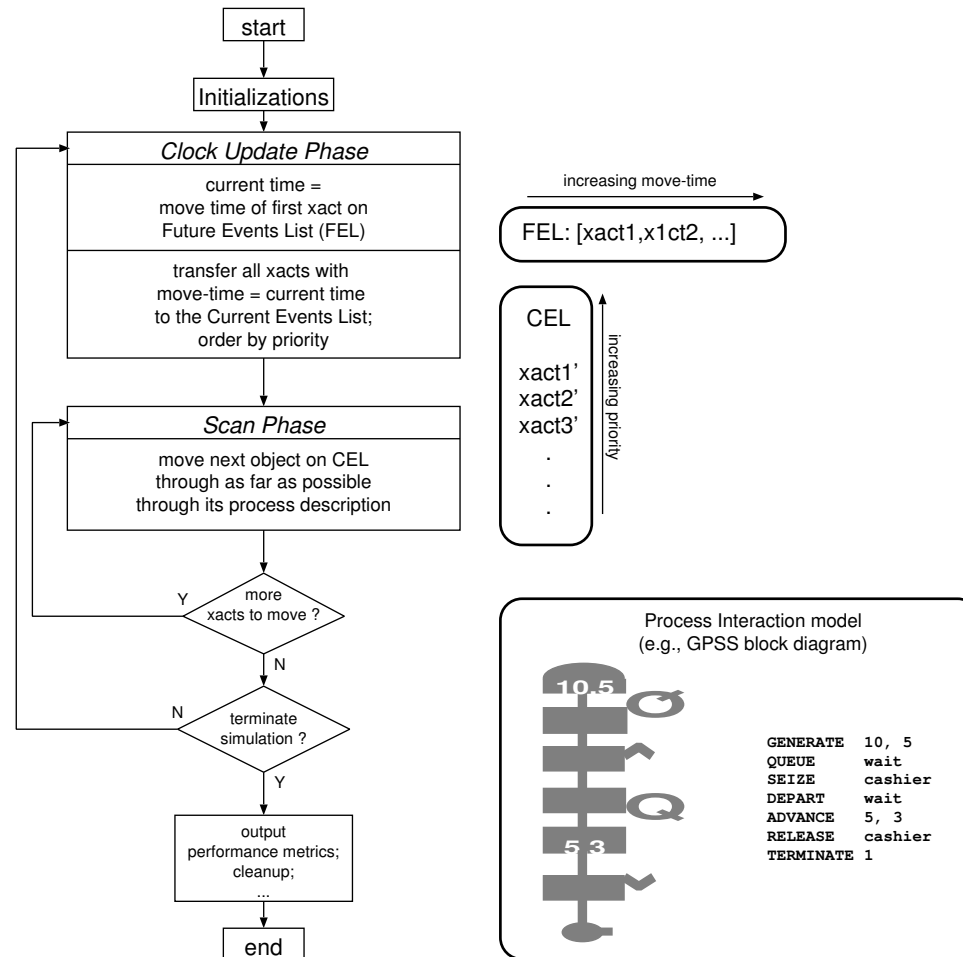
Transaction Life

- A transaction moves through GPSS blocks (as far as possible).
- Internally, its structure is on *exactly one* of the chains.
- Structure of a transaction:
unique Xact ID, current block, next block (attempt), move time, priority,
...
- Ordering:
 - On CEC: decreasing priority.
 - On FEC: increasing move time, FIFO(FCFS) irrespective of priority.

Process Interaction: Transaction Life



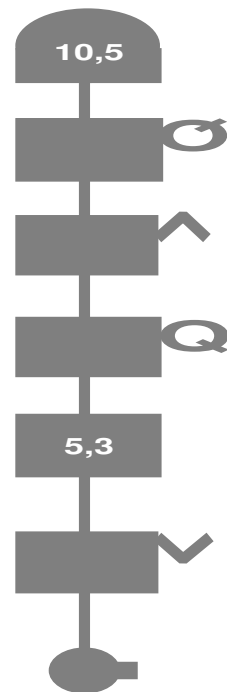
GPSS Process Interaction Simulation Procedure



Operational Semantics of Process-oriented Simulation Languages: π Demos

- Simula-style
- Operational semantics (Plotkin)
- Scheduling of Events, Synchronisation
- Birtwistle and Tofts (SCS Transactions, 10(4), 1994, 299-333)

Cashier-Queue: GPSS Process Interaction View



```
GENERATE 10, 5  
QUEUE   wait  
SEIZE   cashier  
DEPART  wait  
ADVANCE 5, 3  
RELEASE cashier  
TERMINATE 1
```

Process Interaction (dis)advantages

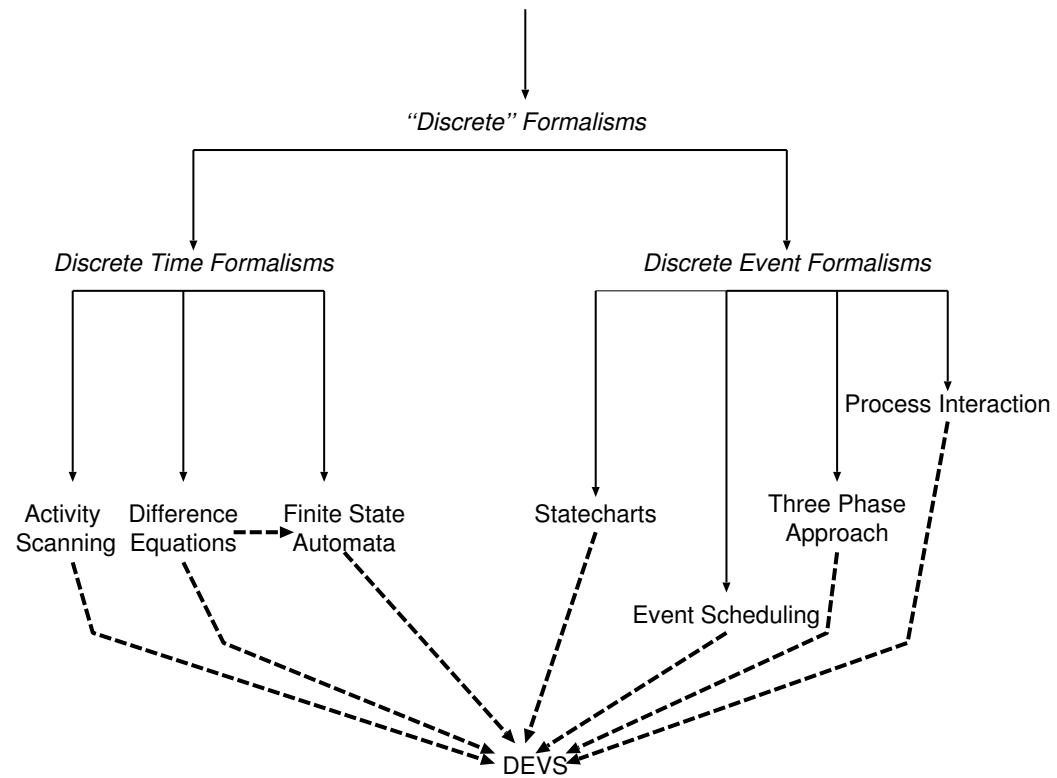
- advantage: declarative model, high-level “process view”
- disadvantage: rather inefficient

General disadvantages

- (here) not formally defined, is possible
- non-modular, is possible

⇒ DEVS formalism

World Views: Classification



(Pseudo-) Random-number Generators

- *SYS* model is deterministic + random constructs
- randomness \equiv not enough detail known or don't care
- randomness: characterized by distribution
- In *SYS*: *draw* from distribution and Monte-Carlo run multiple deterministic simulations.
- Alternatives:
 - Transform to deterministic.
 - Markov Chains (analytical).

Probability Distributions

- Continuous vs. discrete
- Probability Density Function ($f(x)$)
- Cumulative Probability Function ($F(X)$)
- see probability course: Poisson, Erlang, ...

Pseudo-random

- Sample from distribution ($U(0, 1)$)
- Reproducibility/comparison of experiments !
 - science needs reproducible results
 - makes debugging easier
 - *identical* random numbers to compare *different* systems
- Quality of generator:
 - appear uniformly distributed
 - non-correlated
 - fast and doesn't need much storage
 - long period, dense (full) coverage
 - provision for *streams* (subsegments)

Linear Congruential Generators

$$Z_i = (aZ_{i-1} + c) \bmod m$$

m is modulus

a is multiplier

c is increment

Z_0 is seed

$c = 0$ is called *multiplicative* LCG

Generators ctd.

- Composite Generators
- Tausworthe generators (operate on bits)
- L'Ecuyer, Devroye (non-uniform)
- Testing RNG: empirical vs. theoretical
- References: Knuth, Law & Kelton

Marse and Roberts' portable RNG

$$Z[i] = (630360016 * Z[i - 1]) \bmod (2^{31} - 1)$$

- Prime modulus multiplicative linear congruential generator.
- Based on Fortran UNIRAN code.
- Multiple (100) streams are supported with seeds spaced 100,000 apart.
- Include file: rand.h
- C file: rand.c
- Example use: randtest.c

Non-uniform continuously distributed RNG

Inverse Transformation Method

Gathering Statistics (report generation)

1. *counters*
2. *summary measures*
3. *utilization*
4. *occupancy*
5. *distributions and transit times*

Counters

In all previous examples: keep/update counters (as state vars) !

- numbers of entities of different types in the system
- number of times a particular event occurred
- basis for statistics (performance metrics)

Summary Measures

- minima and maxima:
compare new values to current *min* and *max*, update when necessary
- mean of a set of N observations $x_i, i = 1, 2, \dots, N$

$$m = \frac{1}{N} \sum_{i=1}^N x_i$$

Summary Measures (ctd.)

- standard deviation (from mean)

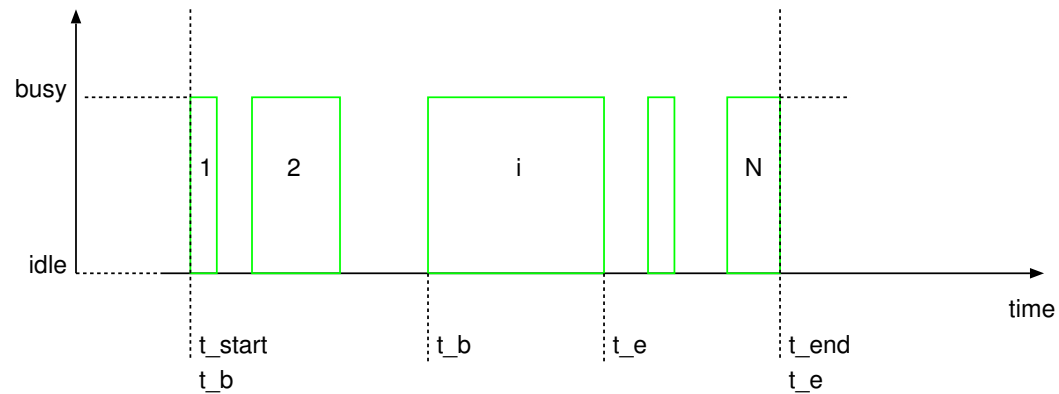
$$s = \sqrt{\frac{1}{N-1} \sum_{i=1}^N (m - x_i)^2}$$

- need to calculate m first \rightarrow need to keep all observations
- sum of squares may grow *very* large (accuracy \downarrow)

$$\sum_{i=1}^N (m - x_i)^2 = \sum_{i=1}^N x_i^2 - Nm^2$$

Utilization

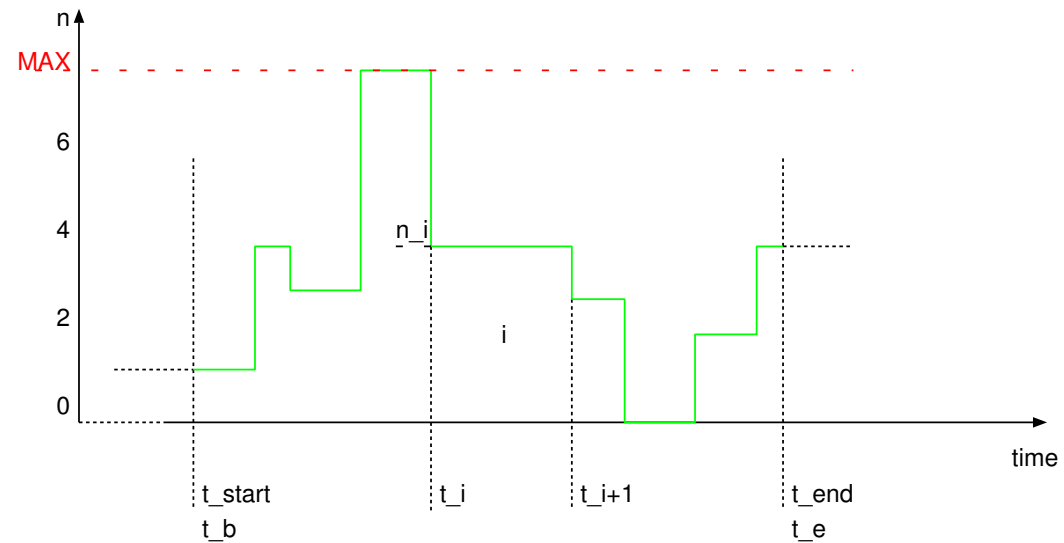
The fraction (or %) of time each *individual* entity is engaged



$$U = \frac{1}{t_{end} - t_{start}} \sum_{i=1}^N (t_e - t_b)_i$$

Average Use and Occupancy

for *groups* and *classes* of entities



Average Use and Occupancy (ctd.)

- Average use over time (t_i are times of change)

$$A = \frac{1}{t_{end} - t_{start}} \sum_{i=1}^N n_i (t_{i+1} - t_i)$$

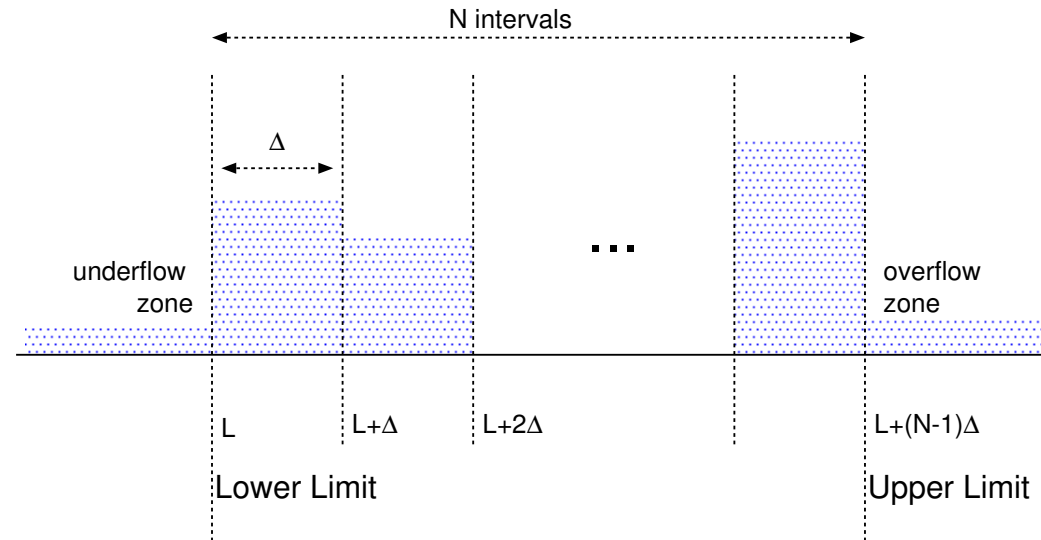
Example use: average queue length.

- Occupancy: average number in use with respect to MAX

$$O = \frac{A}{MAX}$$

No bookkeeping of individual entity information required, only *total* use (n_i) and *when* change occurs. This, as opposed to for example average transit time computation where individual times must be kept.

Distributions and Transit Times



Number of intervals N , Uniform interval size Δ , Lower tabulation limit L .

Implementation: table of interval *counters*.

Global accumulation: number of entries, sum of entries, sum of squares.

Distributions and Transit Times (ctd.)

- Transit times: use clock as *time stamp*, enter in table at end of transit.
- Distribution of number of entities: measure at uniform intervals of time.