

Model Driven Engineering Map Generation

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Design Space Exploration

- ▶ Find good / best instance
- ▶ Steps:
 1. Generate a candidate
 2. Check the candidate for feasibility
 3. Evaluate the candidate
 4. Repeat
- ▶ Several algorithms ¹:
 - ▶ Exhaustive
 - ▶ Random
 - ▶ Hill Climbing

¹Denil, J., Han, G., Persson, M., Liu, X., Zeng, H., Vangheluwe, H., 2013. Model-driven engineering approaches to design space exploration. Tech. rep

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L-System: Introduction

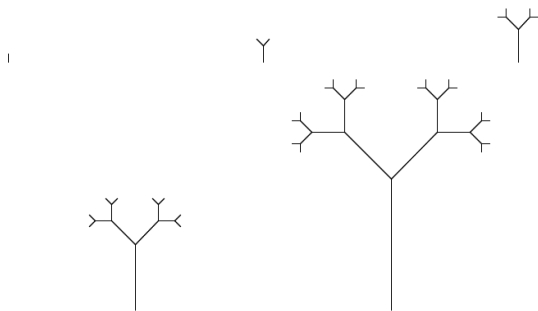
- ▶ Introduced to model plant growth
- ▶ $G = (V, \omega, P)$
 - ▶ An alphabet V
 - ▶ An initial string ω
 - ▶ A set of rules P
- ▶ Many extensions

L-System: Example

$V = 0, 1, [,], +, -$

$\omega = 0$

$P = \{(1 \rightarrow 11), (0 \rightarrow 1[-0]+0)\}$



L-System: Use

$$V = \left\{ \begin{array}{l} M : \text{map growth entity} \\ I : \text{intersection} \\ T : \text{two-way road} \\ O : \text{one-way road} \\ [: \text{store state} \\] : \text{restore state} \\ + : \text{angle} + 90^\circ \\ - : \text{angle} - 90^\circ \end{array} \right.$$

$$\omega = I [+M(n)] [-M(n)] [++M(n)] M(n)$$

$$P = \left\{ \begin{array}{l} P_1 : M(n) \rightarrow T(x) I [+M(\frac{n-x}{3})] [-M(\frac{n-x}{3})] M(\frac{n-x}{3}) \\ P_2 : M(0) \rightarrow \epsilon \\ P_3 : T(x) \rightarrow O(x) \end{array} \right.$$

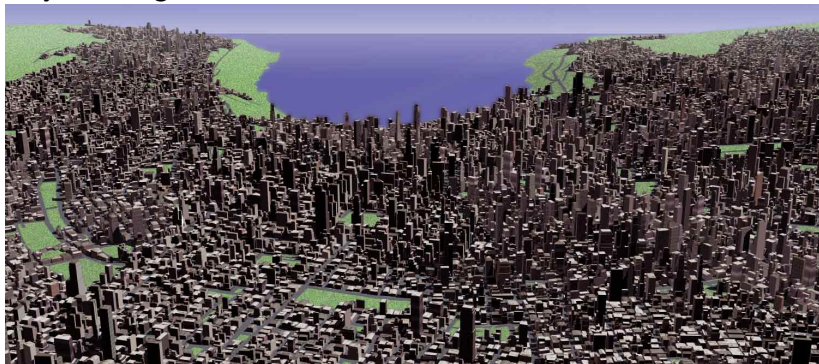
L-System: Use

Difficulties:

- ▶ Randomness \rightarrow Stochastic L-Systems
- ▶ Analysis \rightarrow Interpret string

L-System: Use

CityGen Engine ²:



²Parish, Y. I. H., Müller, P., 2001. Procedural modeling of cities

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L-System

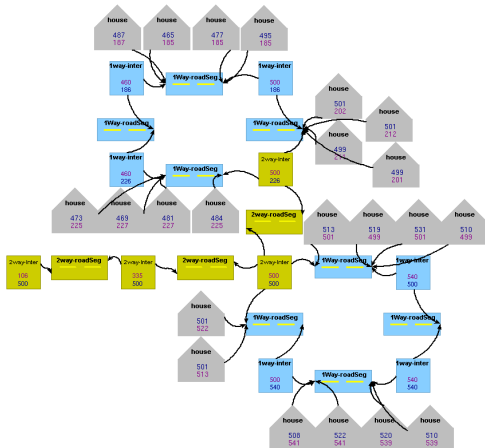
Graph Transformation

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Graph Transformation: Related Work

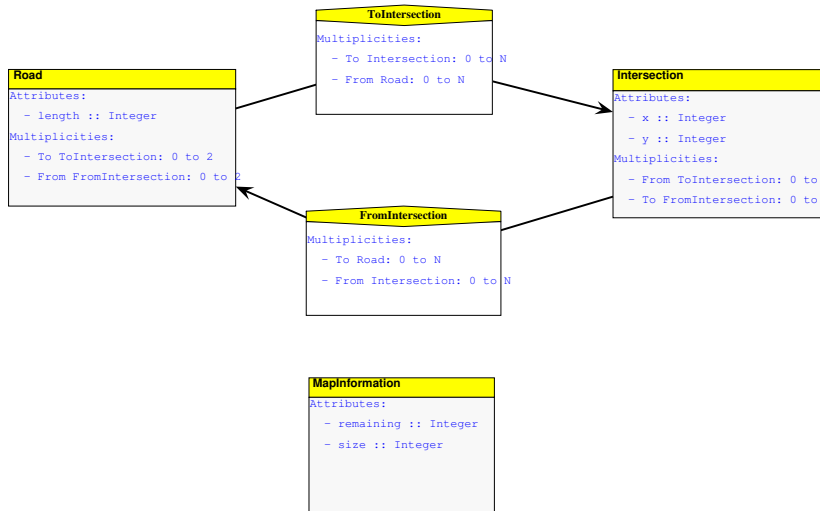
Riry Pheng³:



³Pheng, R., 2008. Procedural modeling for city map generation - final report

Graph Transformation: Project

Meta Model:



Graph Transformation: Project

Rules:

- ▶ Expand: North, East, South, West
- ▶ GrowRoad
- ▶ ConnectIntersections
- ▶ OneWay

Graph Transformation: Project

Feasibility:

- ▶ Strongly Connected Component

Desired Properties:

- ▶ Road distance close to Manhattan distance
- ▶ Minimize intersections on trajectory
- ▶ Cover as much as possible
- ▶ Roads are evenly distributed
- ▶ Multiple routes to an intersection

Metrics:

- ▶ Longest path
- ▶ Average minimal cut

Graph Transformation: Project

Space is huge \Rightarrow algorithm should produce results fast.

Algorithm:

1. Select the candidate with the highest score
2. Generate all children
3. Check and evaluate each child
 - ▶ Not feasible or lower score: reject
 - ▶ Higher score: add as candidate
4. Repeat

Graph Transformation: Project



Figure: The initial map

Graph Transformation: Project



Figure: Iteration 1

Graph Transformation: Project

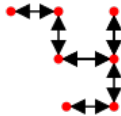


Figure: Iteration 10

Graph Transformation: Project

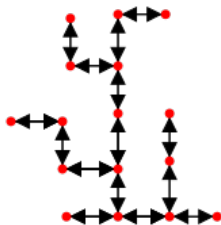


Figure: Iteration 50

Graph Transformation: Project

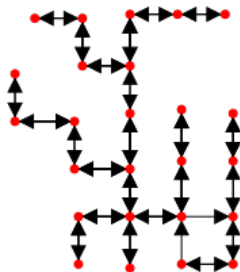


Figure: Iteration 100

Graph Transformation: Project

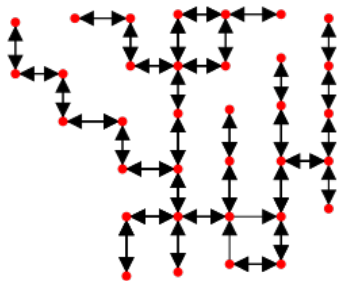


Figure: Iteration 150

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Simulation: PyDEVS⁴ Model

- ▶ Cars move from intersection to intersection (trajectory)
- ▶ Only 1 car at an intersection
- ▶ Car changes speed when:
 - ▶ Entering a new road
 - ▶ Car before him changes its speed
 - ▶ Reaching end of the road

⁴Bolduc, J.-S., Vangheluwe, H., Van Tendeloo, Y., 2000 - 2013.

URL <http://msdl.cs.mcgill.ca/projects/projects/DEVS/>

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Conclusion:

- ▶ Good metric is most important
- ▶ Time-expensive

Future Work:

- ▶ Houses, Stores, Offices, ... → Simulation
- ▶ Multiple lanes, traffic lights, maximum speed
- ▶ Initially start with Houses, etc and generate road network

