

# *Transforming Live Sequence Charts into Statecharts*

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# Overview

1. Recap of Play-In/Play-Out
2. Recap of LSCs (Live Sequence Charts)
3. LSC Specification in AToM3
4. LSC to Statechart Transformation
5. Transformed Microwave Functions
6. DChart Demo



## *Recap of Play-In/Play-Out*

The Play-In/Play-Out Approach is a way to easily generate and test LSCs (Live Sequence Charts). LSCs model all desired system reactions, providing a complete design for the system.

A full LSC specification of a system can be transformed into statecharts.



# *Recap of Play-In/Play-Out*

This presentation is based off “Synthesizing State-Based Object Systems from LSC Specifications” by David Harel and Hillel Kugler, with additional information from:

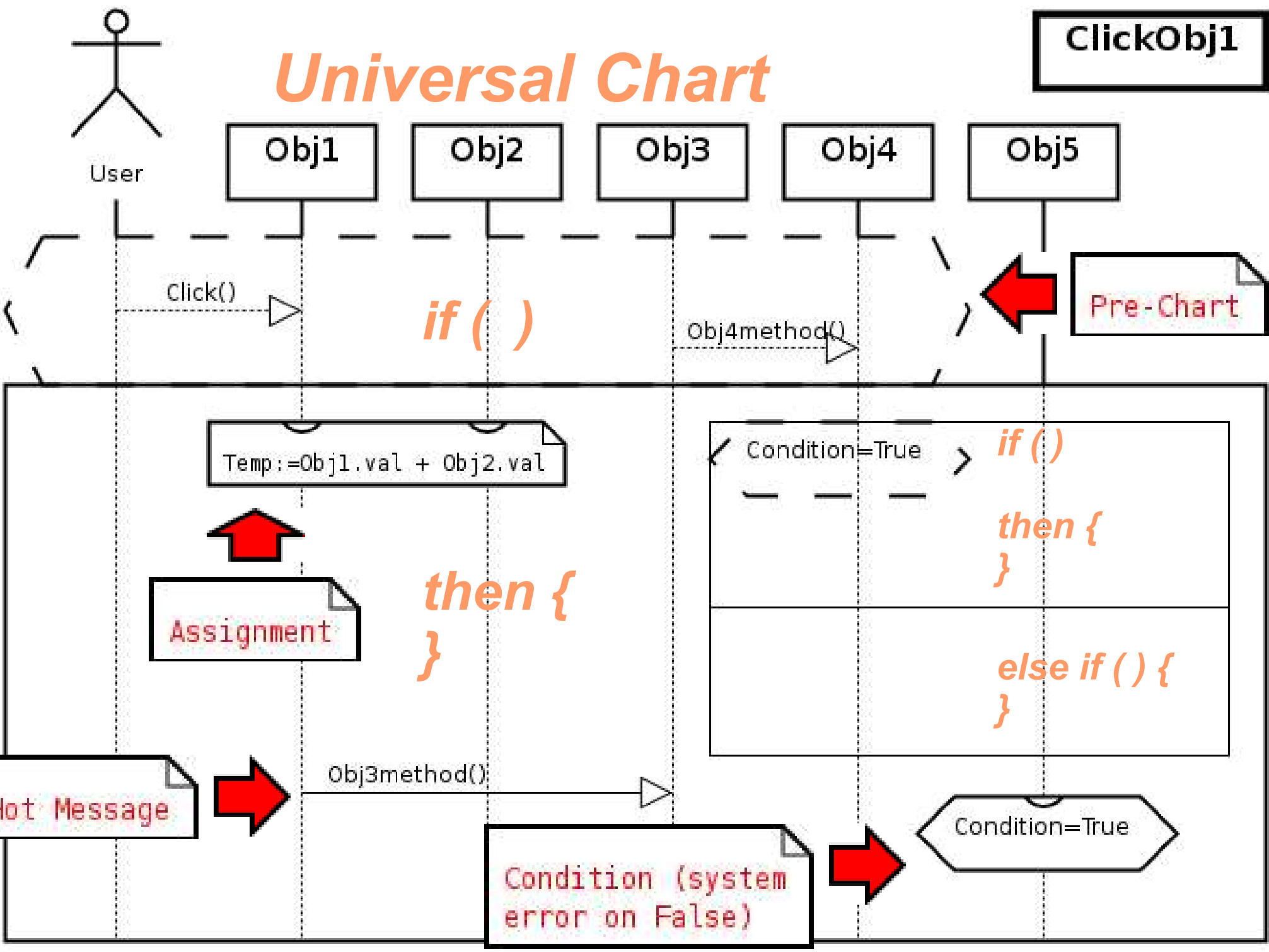
1. “DCharts, a Formalism for Modeling and Simulation Based Design for Reactive Software Systems” by Thomas Huning Feng
  2. “Can Behavioral Requirements be Executed? (And why would we want to do so?)” by David Harel
  3. “Specifying and Executing Behavioral Requirements: The Play-In/Play-Out Approach” by David Harel and Rami Marelly
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# Recap of LSCs

- Modified MSCs (Message Sequence Charts)
  - Two different kinds of LSCs:
    - Universal (Solid Border)
      - Model system reactions that *must* happen
      - Pre-Chart is condition for main chart actions
      - Exiting these prematurely causes a system error/crash
      - Drive system execution during Play-Out
    - Existential (Dashed Border)
      - Model system reactions that *may* happen
      - Must be able to run to completion in at least one scenario
      - Monitored during Play-Out
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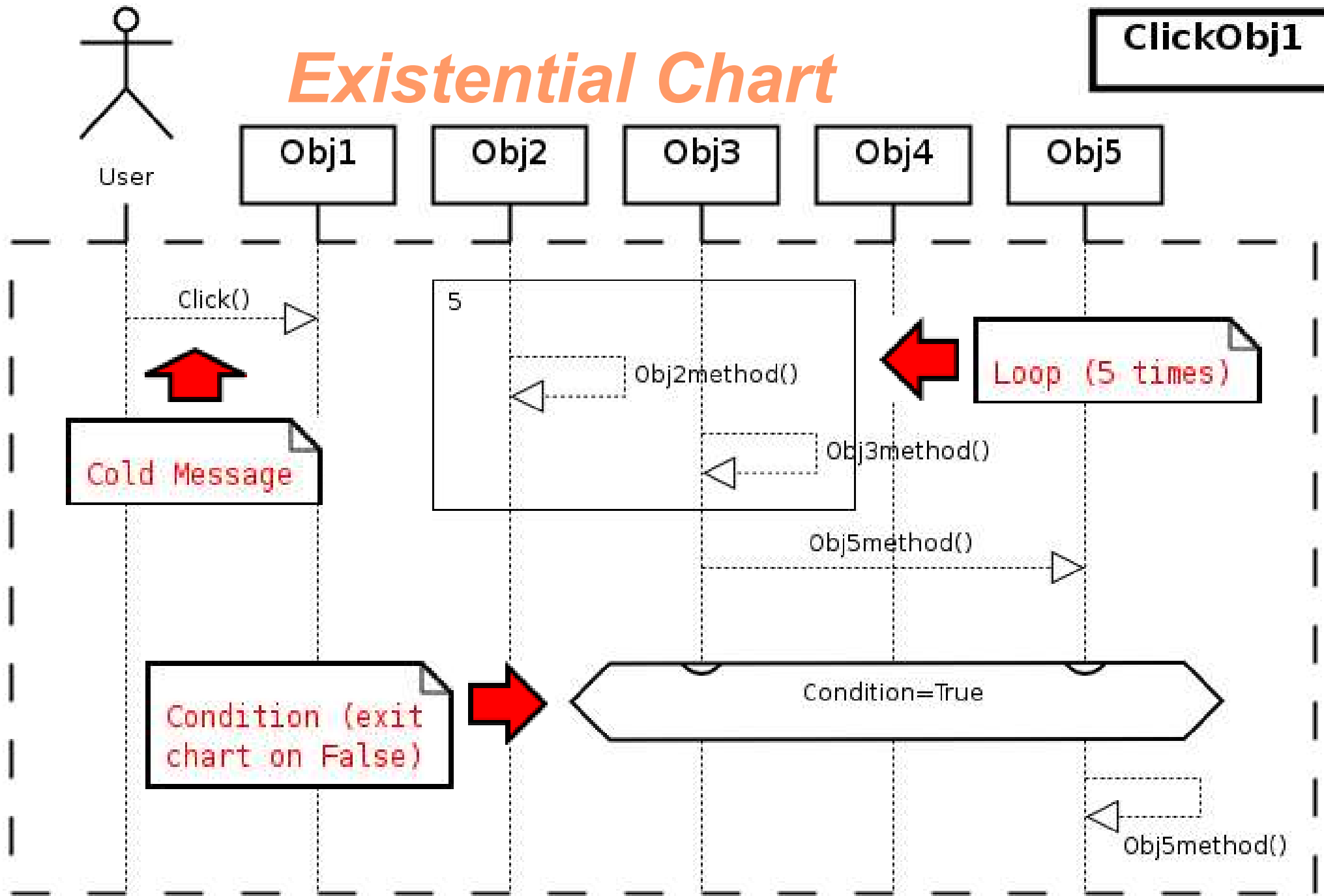
# Universal Chart

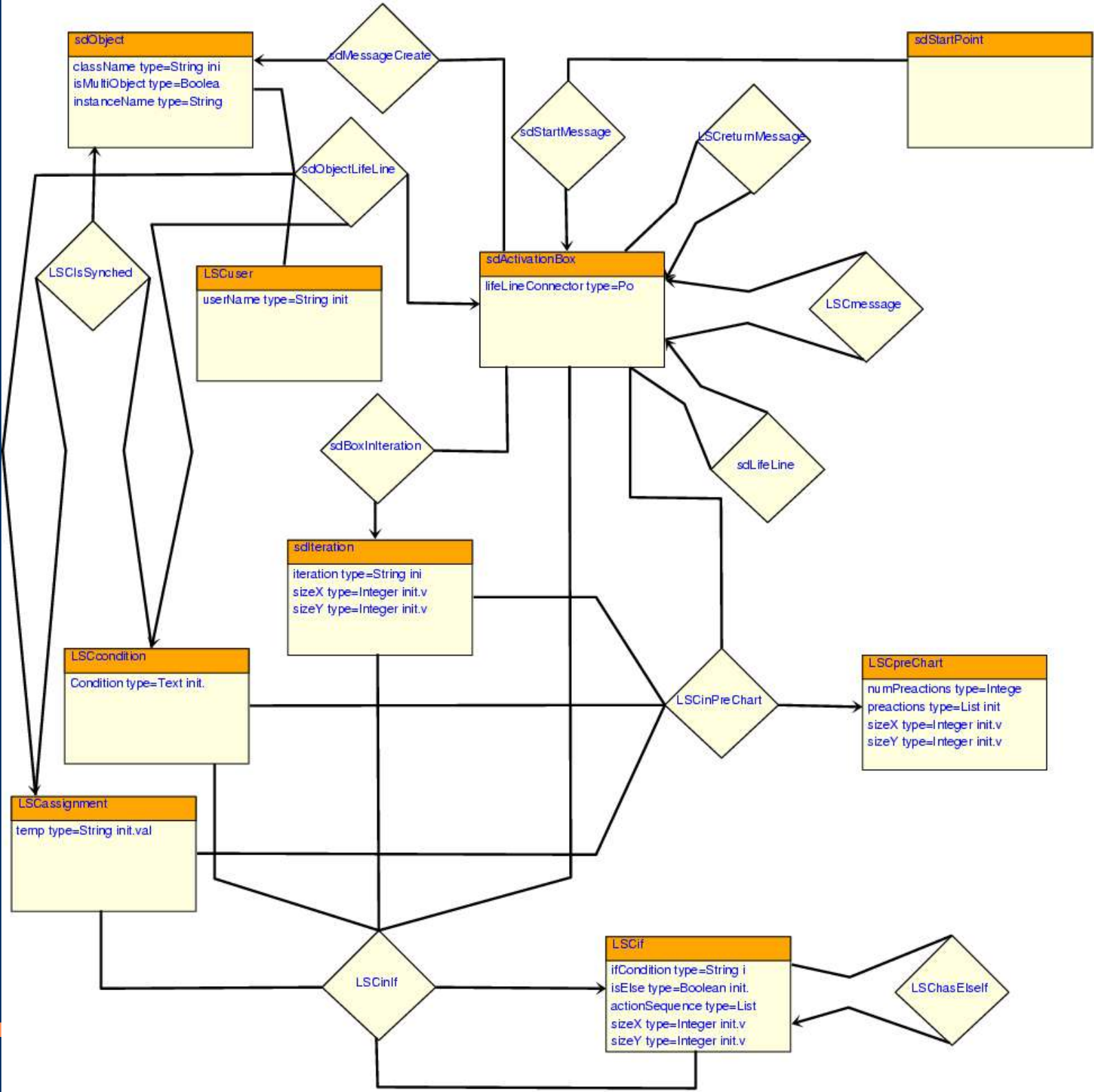
ClickObj1



ClickObj1

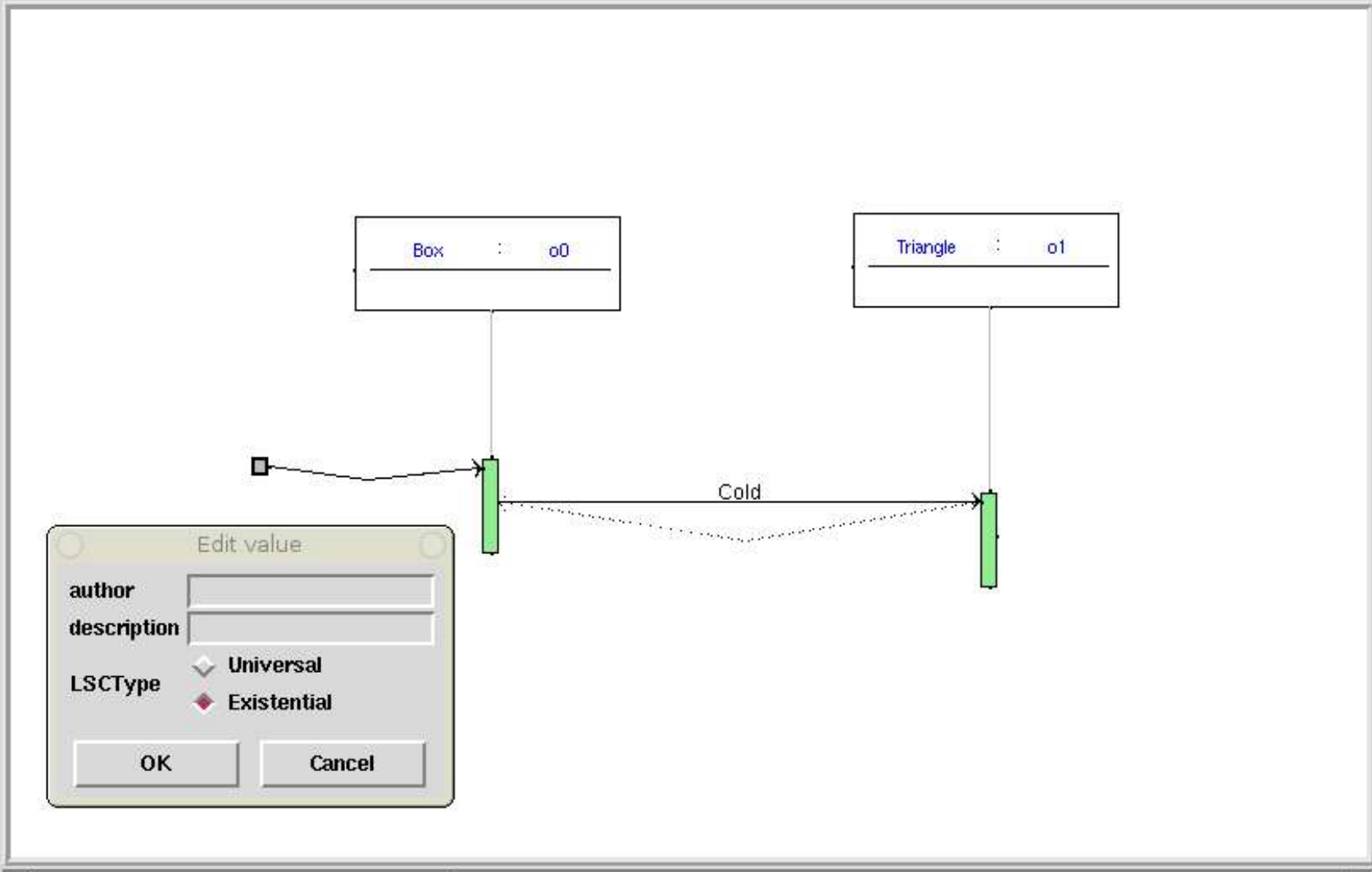
# Existential Chart







- Object
- Activation Box
- Iteration
- Start Point
- PRECHART
- CONDITION
- IF BLOCK
- ASSIGNMENT
- USER
- Message



Edit value

author

description

LSCType  Universal  Existential

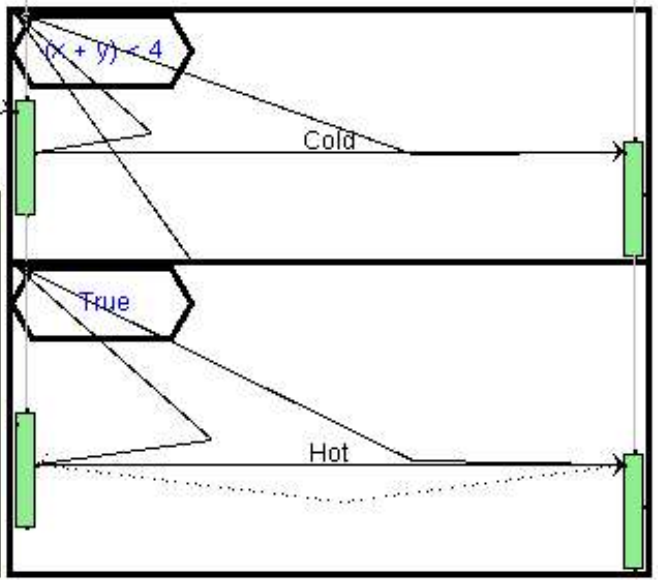
OK Cancel

LSC Model ops Edit entity Connect Delete Insert model Expand model

Exit

Visual ops Smooth Insert point Delete point Change connector

- Object
- Activation Box
- Iteration
- Start Point
- PRECHART
- CONDITION
- IF BLOCK
- ASSIGNMENT
- USER
- Message



**Edit value**

isElse

actionSequence

sizeX

sizeY

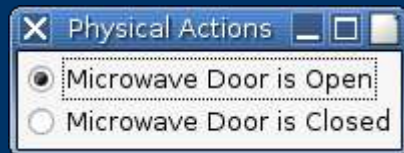
ifCondition

OK Cancel

Editing '...dl.py' (not modified)

Editing transf. 'Nonamed' (not modified) in file 'Nonamed'

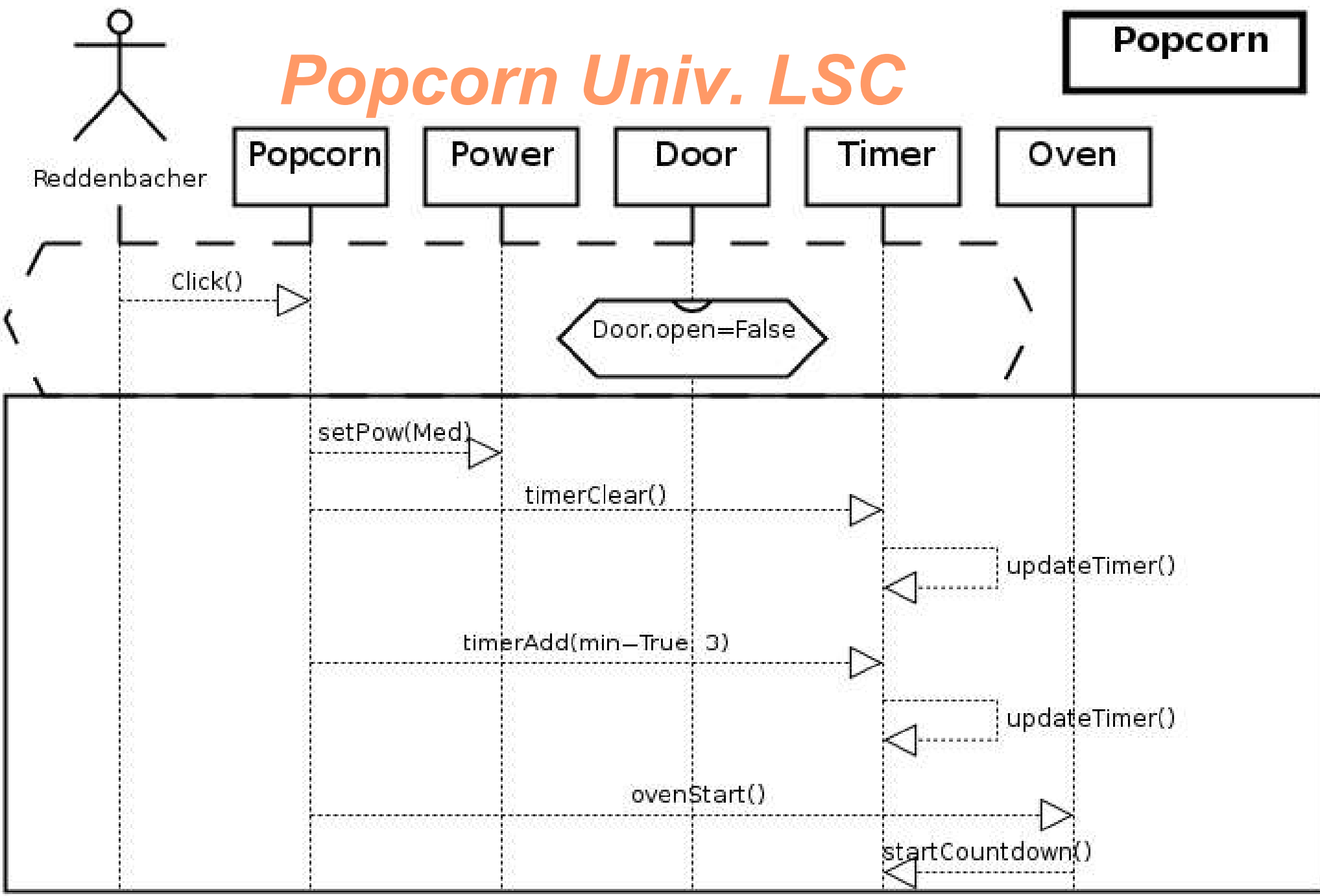
# LSC to Statechart Transformation

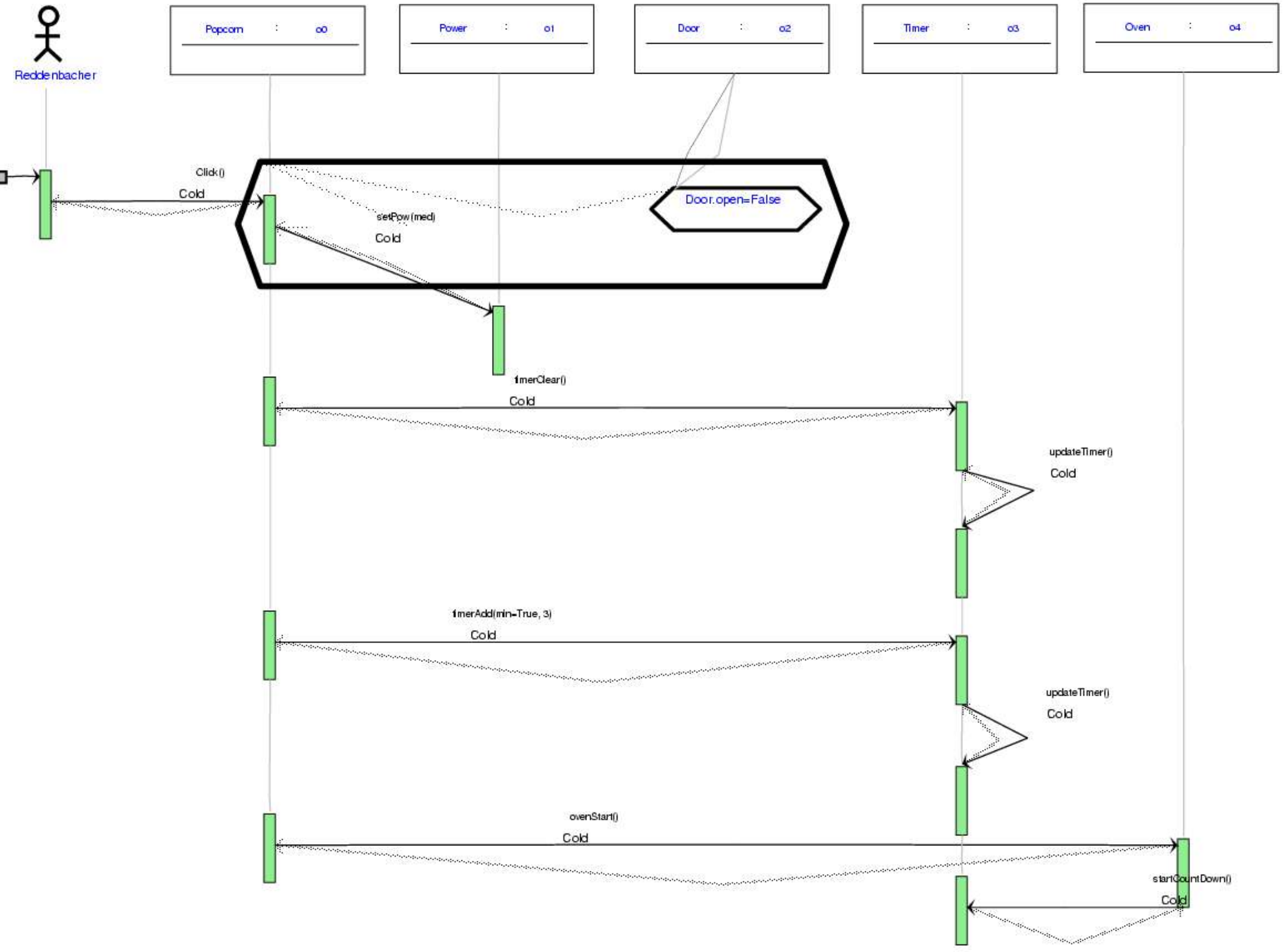


- Goal of this example: transform LSC for the 'Popcorn' button into language of Statecharts
- We'll use multiple Statecharts

# Popcorn Univ. LSC

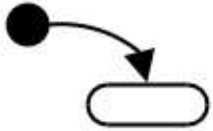
Popcorn





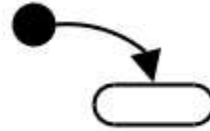
**Popcorn**

Popcorn



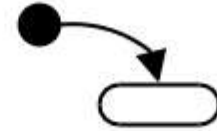
**Power**

Popcorn



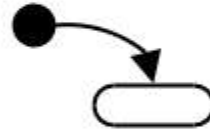
**Timer**

Popcorn



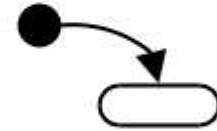
**Door**

Popcorn

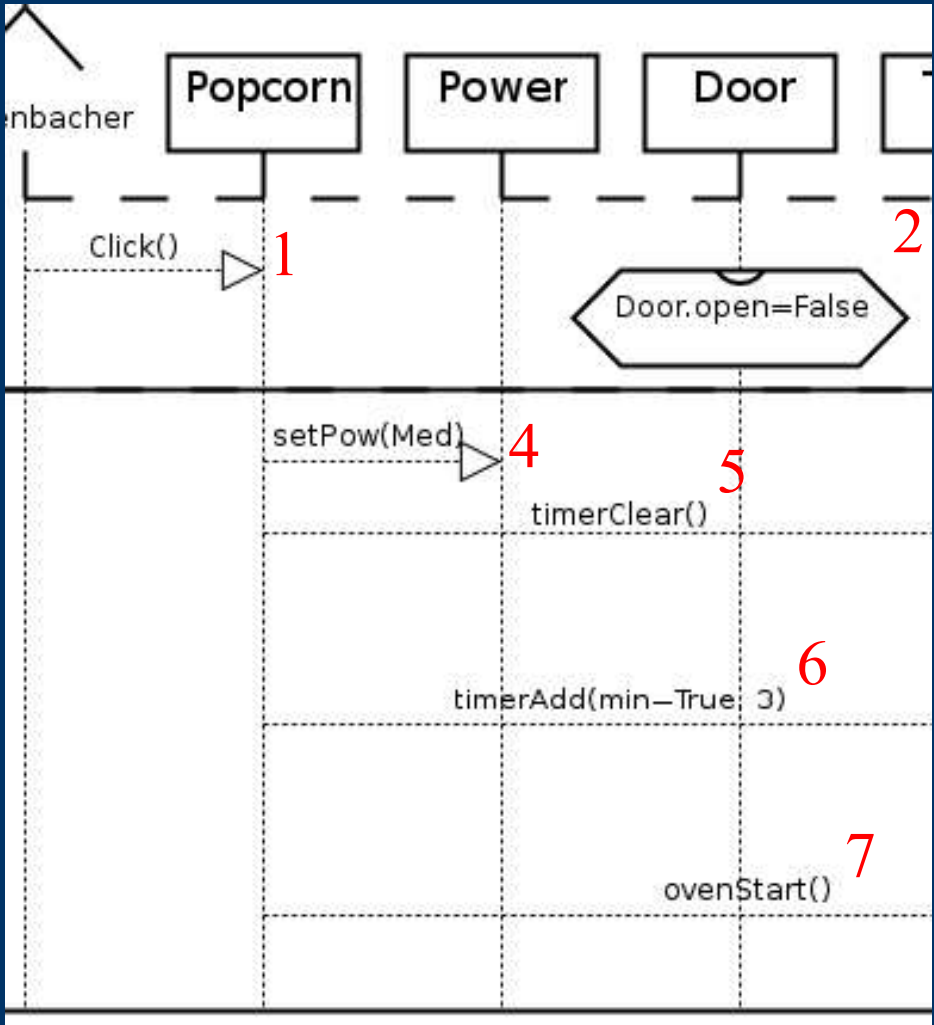
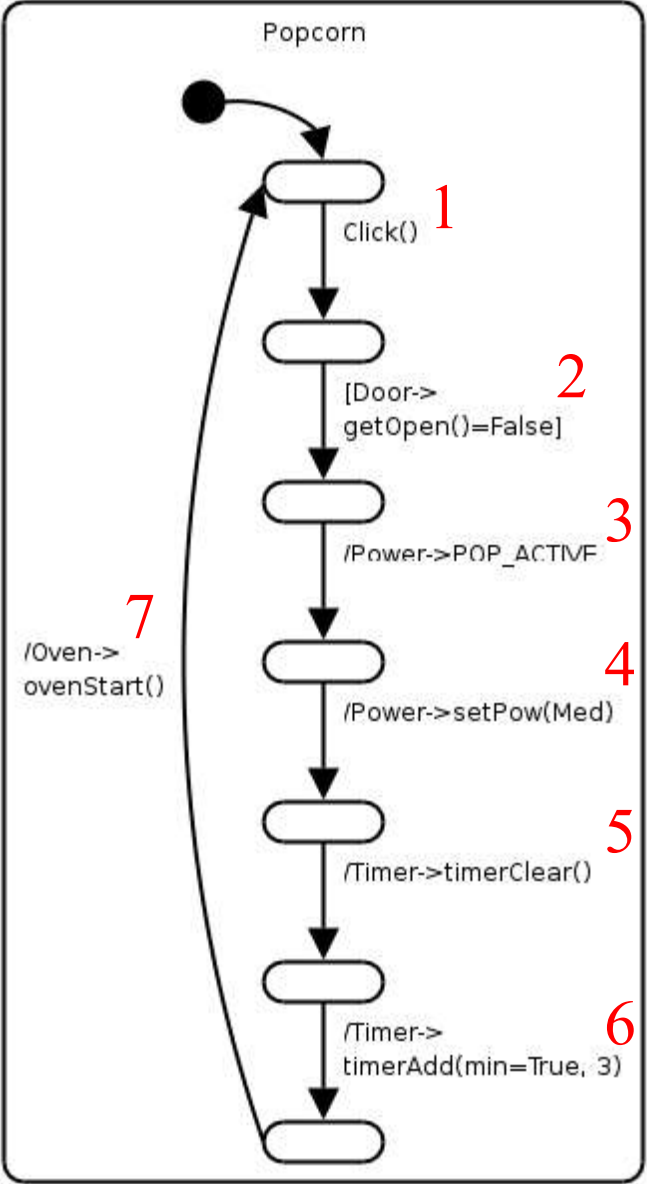


**Oven**

Popcorn

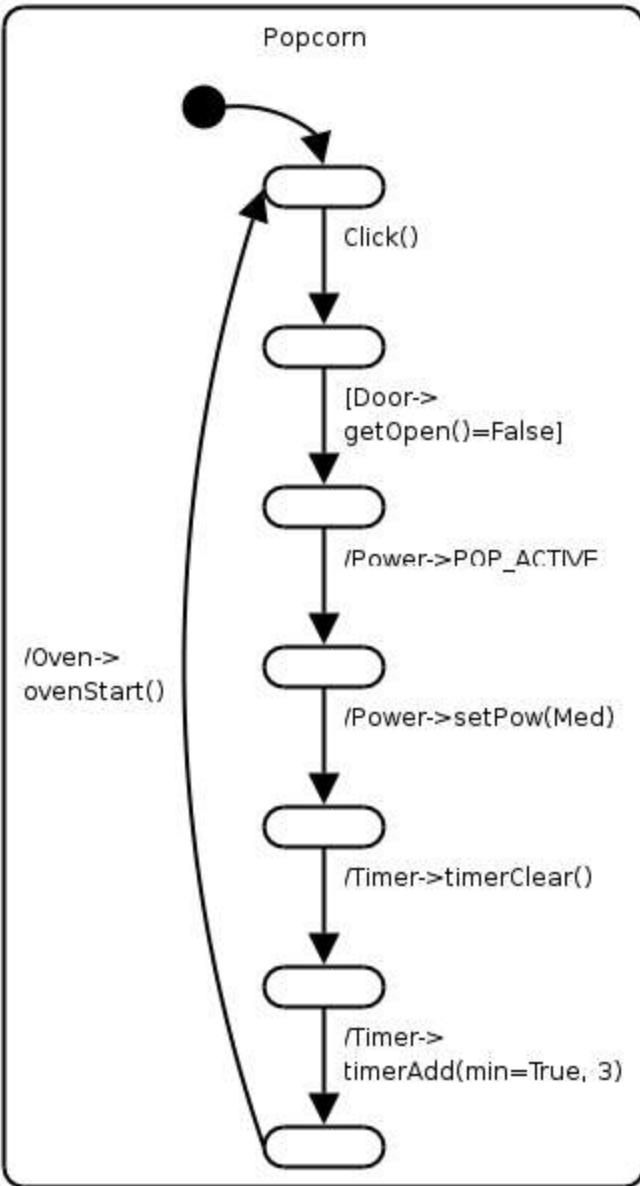


# Popcorn

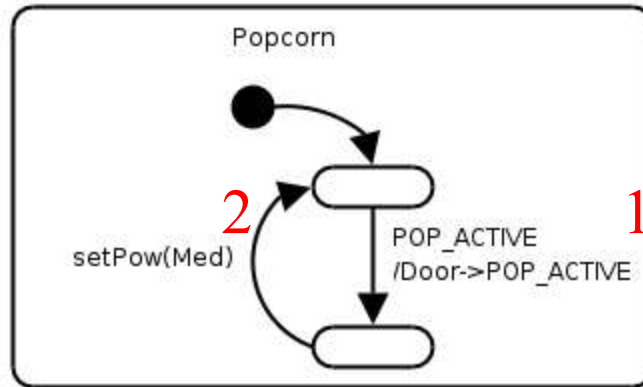


Note transition 3: “/Power->POP\_ACTIVE” starts chain of object notification

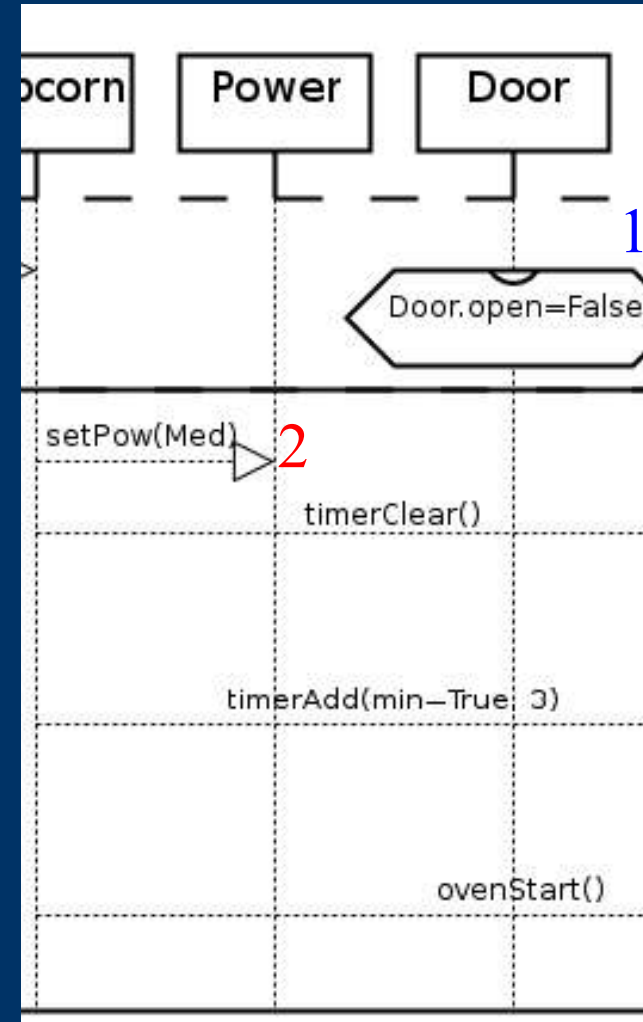
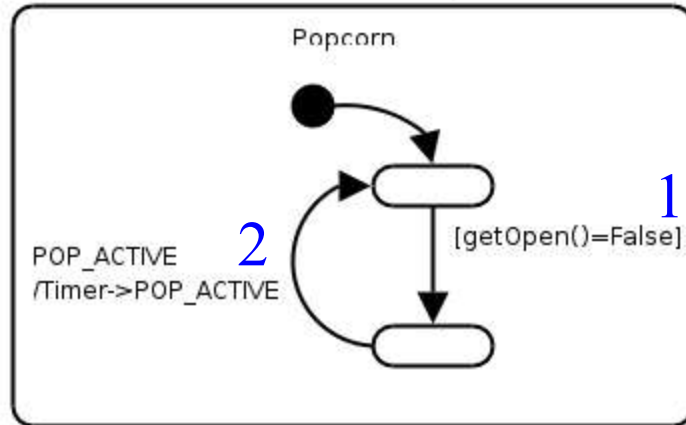
### Popcorn



### Power

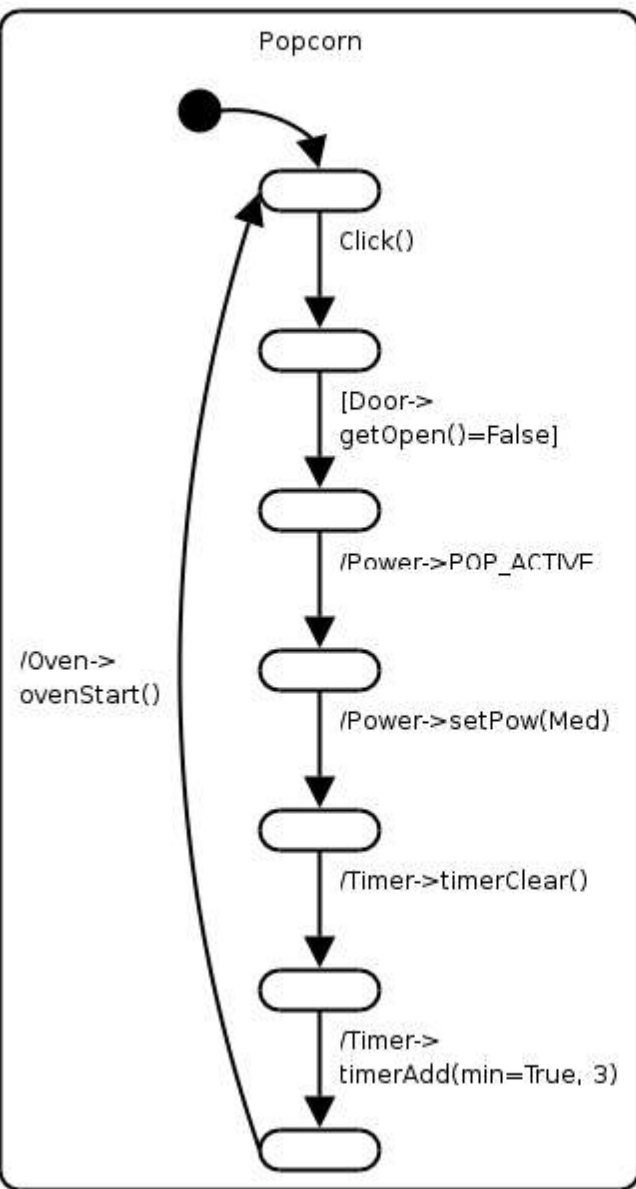


### Door

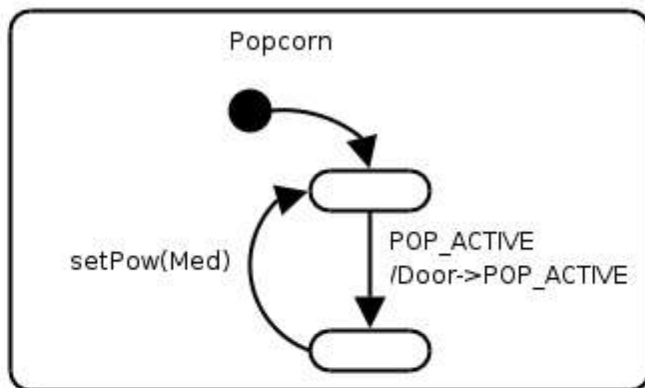




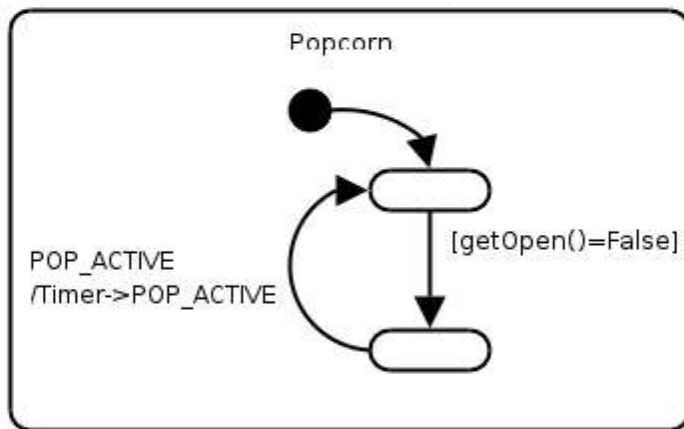
### Popcorn



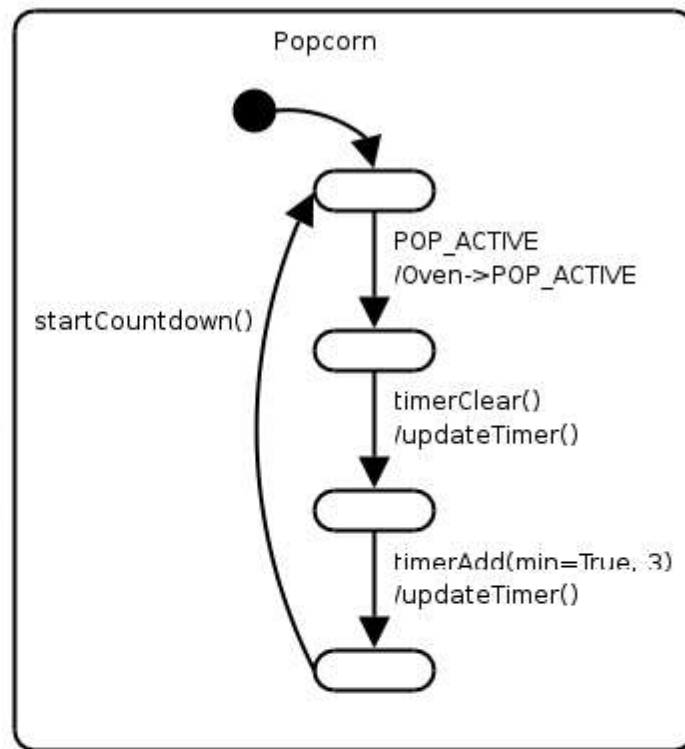
### Power



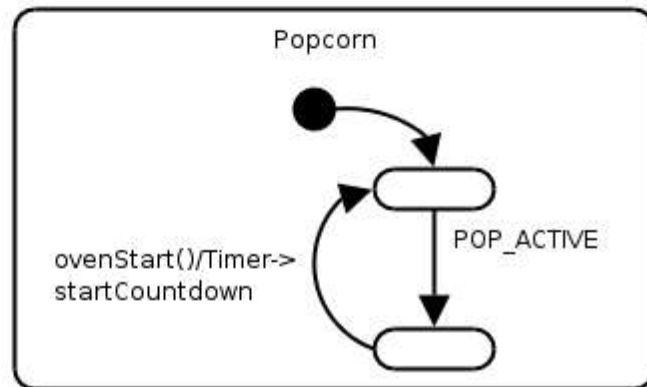
### Door



### Timer

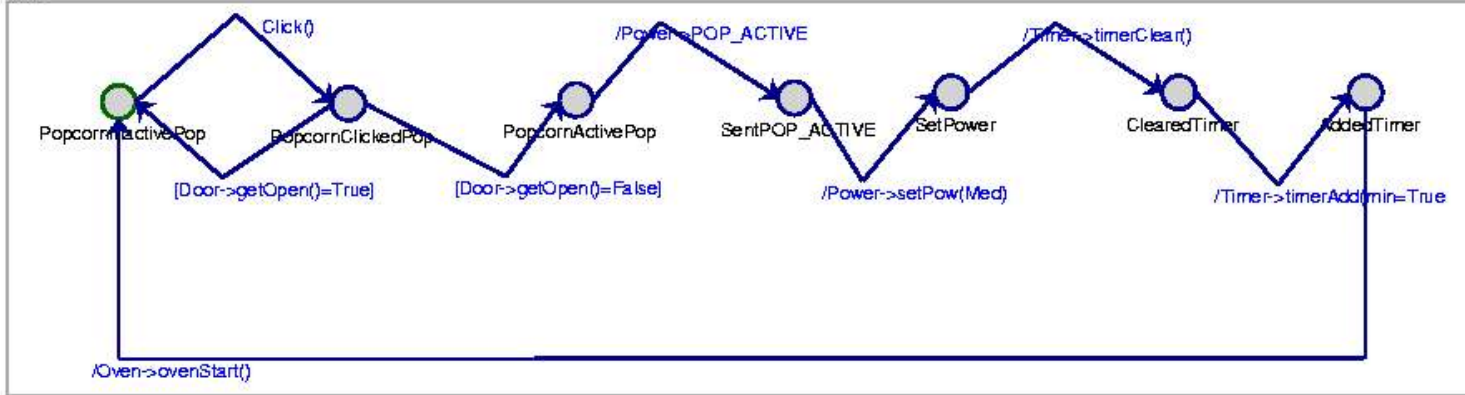


### Oven

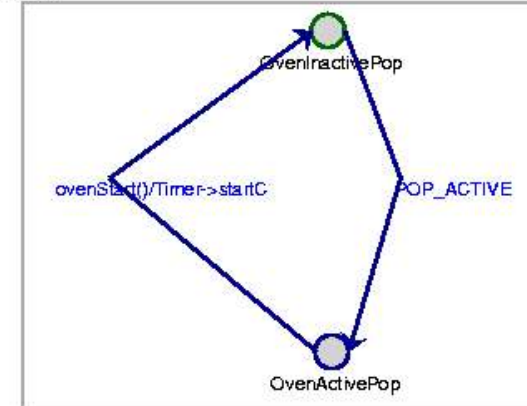


# Popcorn DChart

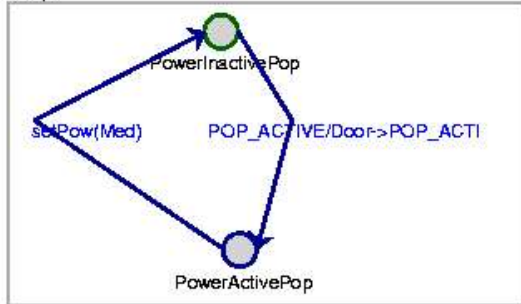
Popcorn



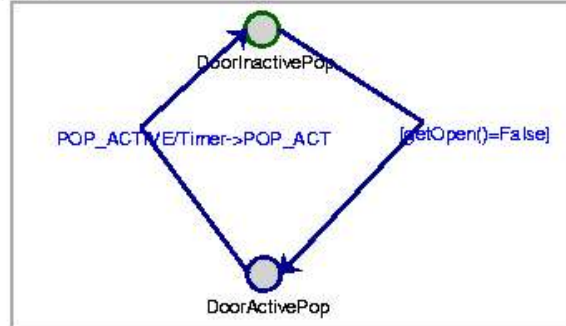
OvenPop



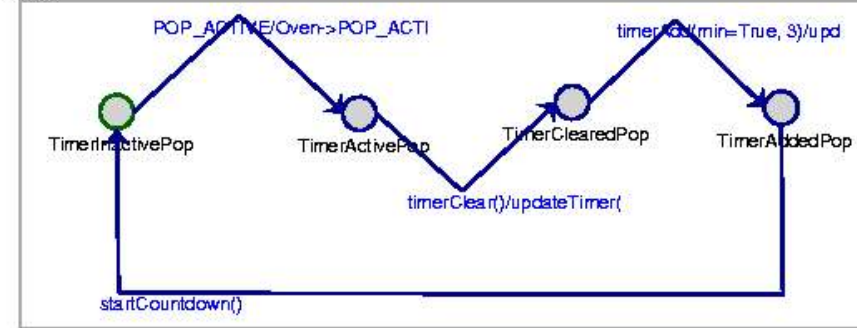
PowerPop



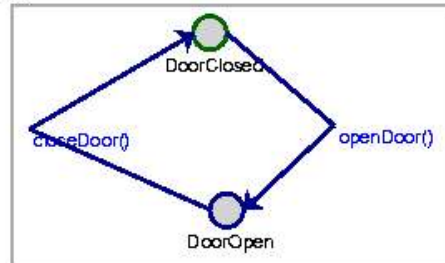
DoorPop



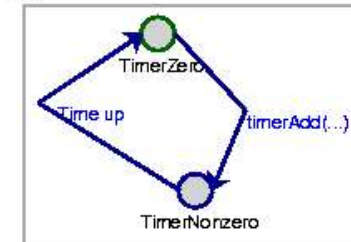
TimerPop



Door



Timer



# *LSC to Statechart Transformation*

1. Create one statechart for each unique object in Universal LSC
  2. For each statechart:
    1. Create default state
    2. Create one state for each action requiring the object
    3. Chain states together with transitions.
    4. Create one transition from state at end of chain to default state
    5. Label transitions with above actions and “ACTIVE” notification
- 
-

# *LSC to Statechart Transformation*

3. Use orthogonal components if object is in more than one Universal LSC\*
4. Check  $\text{Bad}_{\text{max}}$ , set of all supercuts without successors or that lead to those without successors\*

\*We didn't do these in the example

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# *Transformed Microwave Functions*

## LSCs:

1. Add1Min
2. Clear
3. Popcorn
4. Defrost
5. Start
6. Stop
7. OpenDoorWhileOven  
Active

## Statecharts:

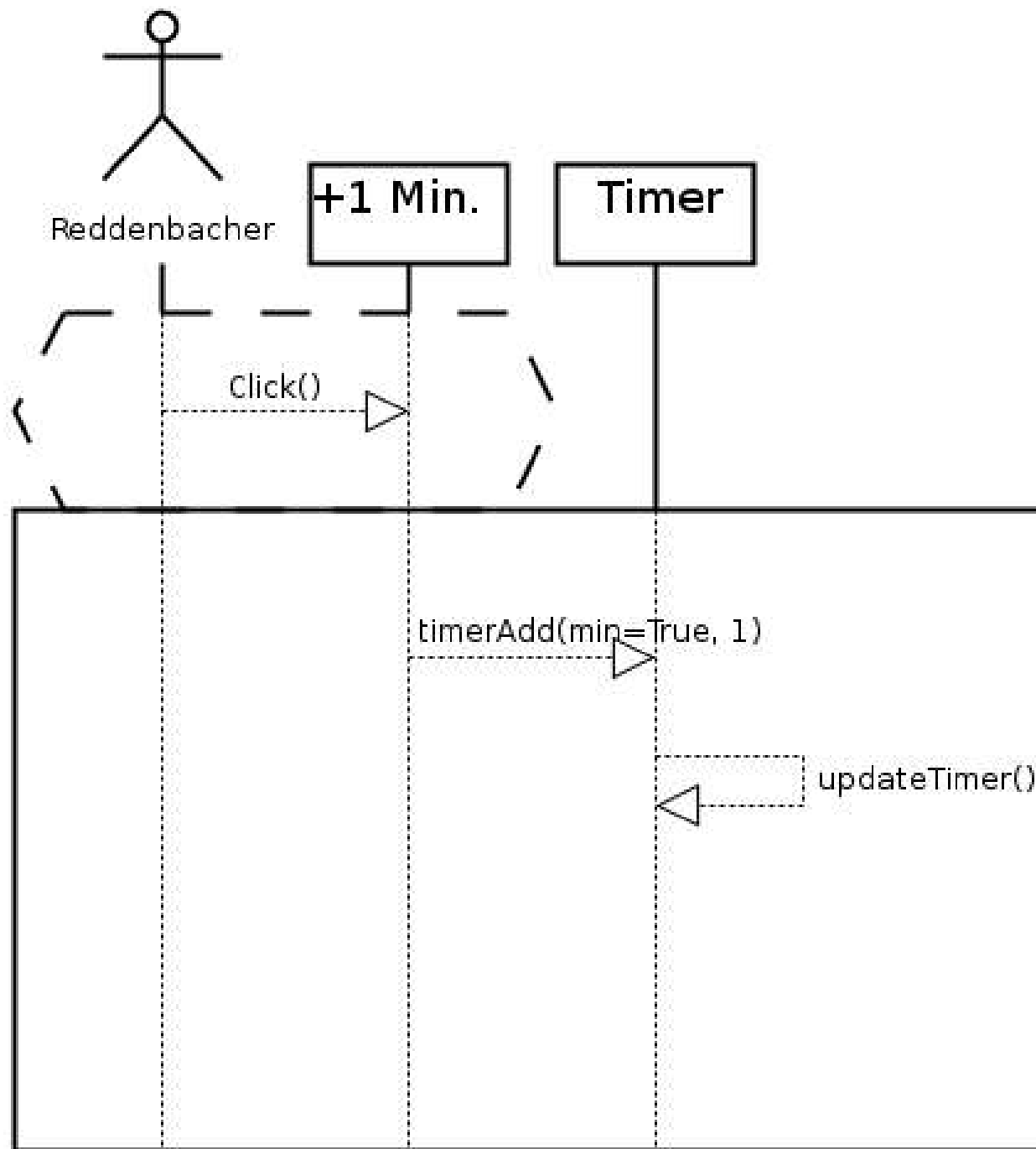
1. +1Min.
  2. Clear
  3. Popcorn
  4. Defrost
  5. Start
  6. Stop
  7. Power
  8. Door
  9. Timer
  10. Oven
- 
-

# *Results of Transformation*

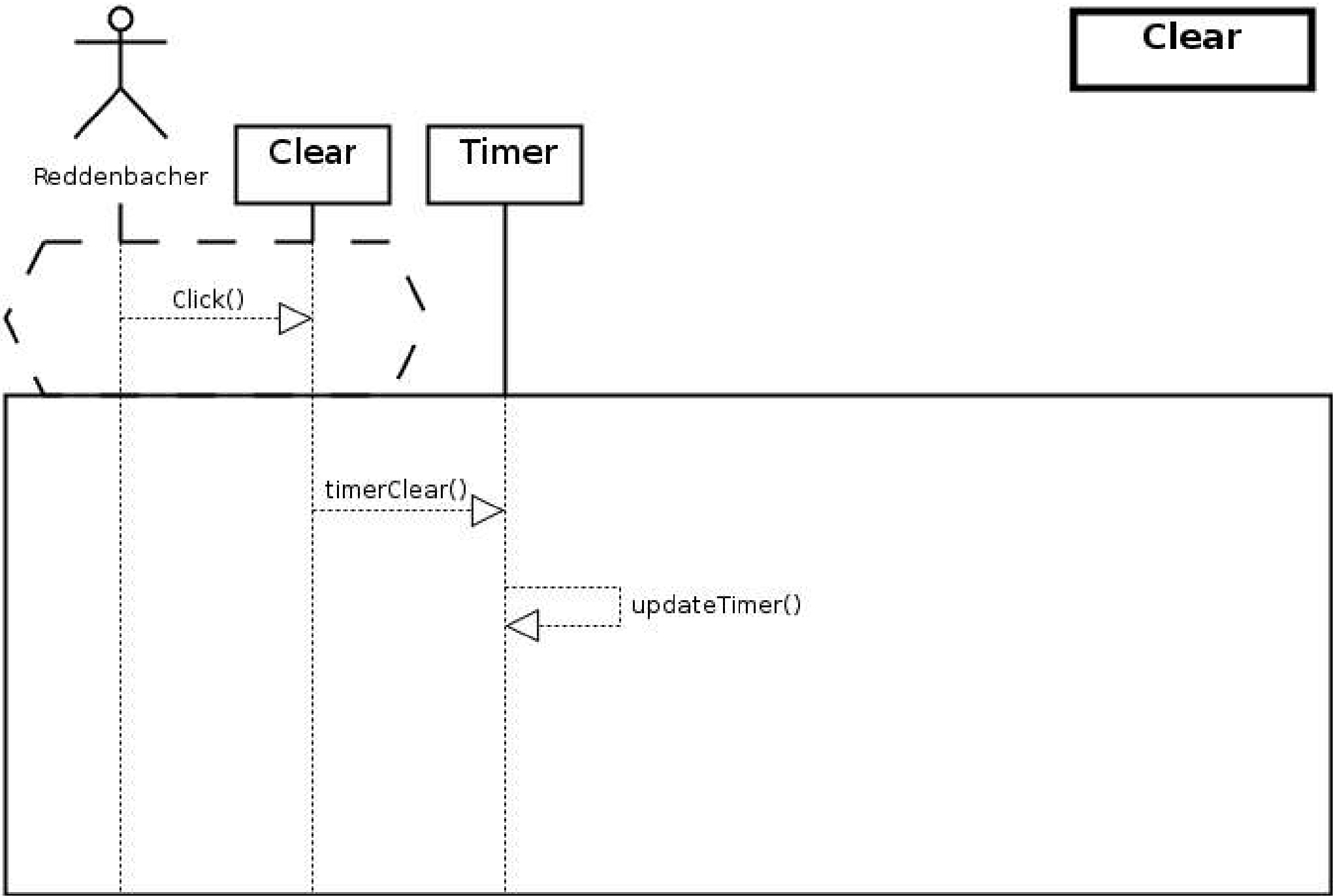
In the following statecharts, please assume all states before “ACTIVE” notices have transitions to the default states.



# Add1Min



# Clear

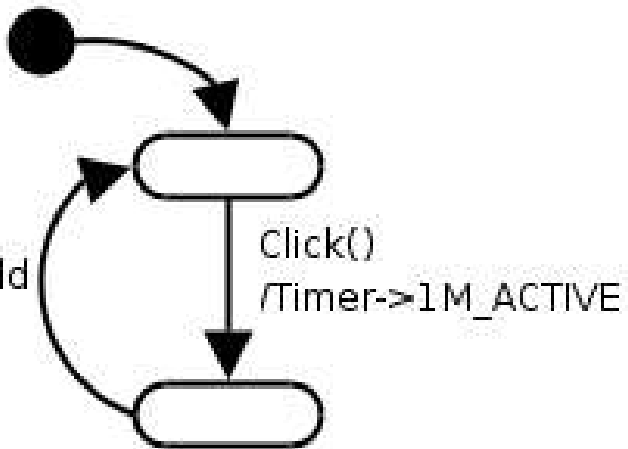




**+1Min.**

Add1Min

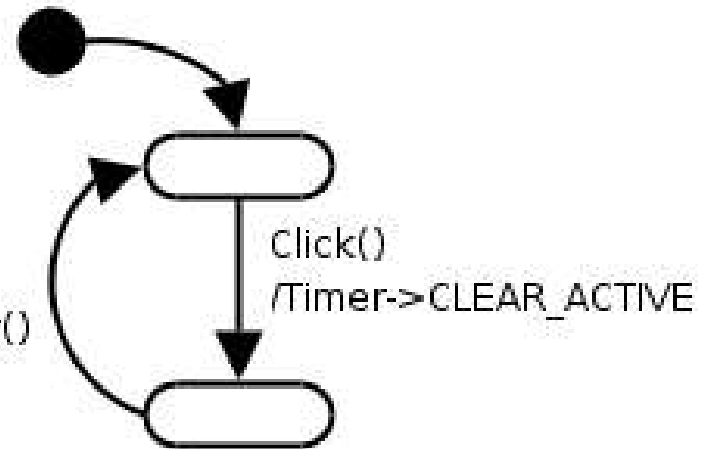
/Timer->timerAdd  
(min=True, 1)

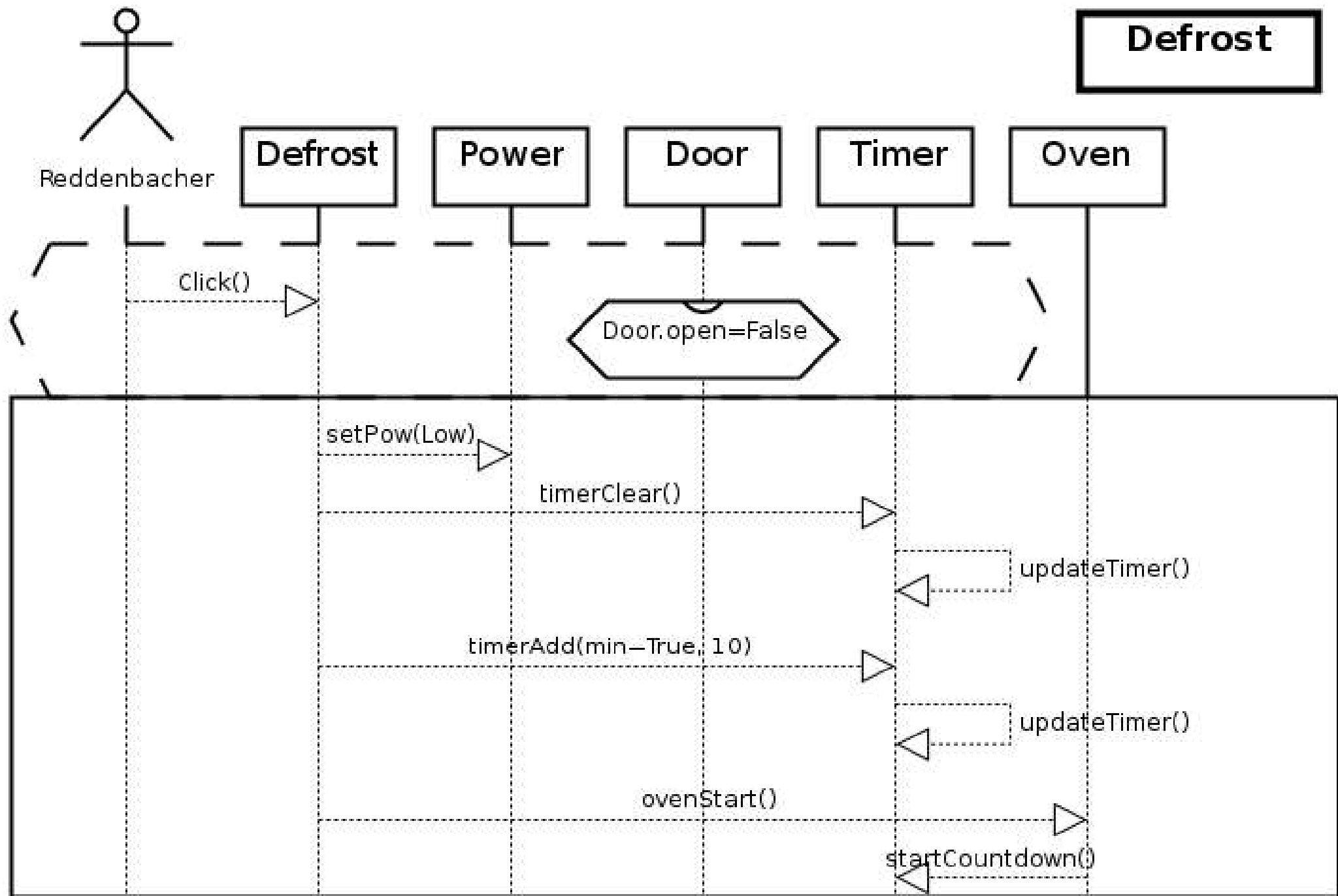


**Clear**

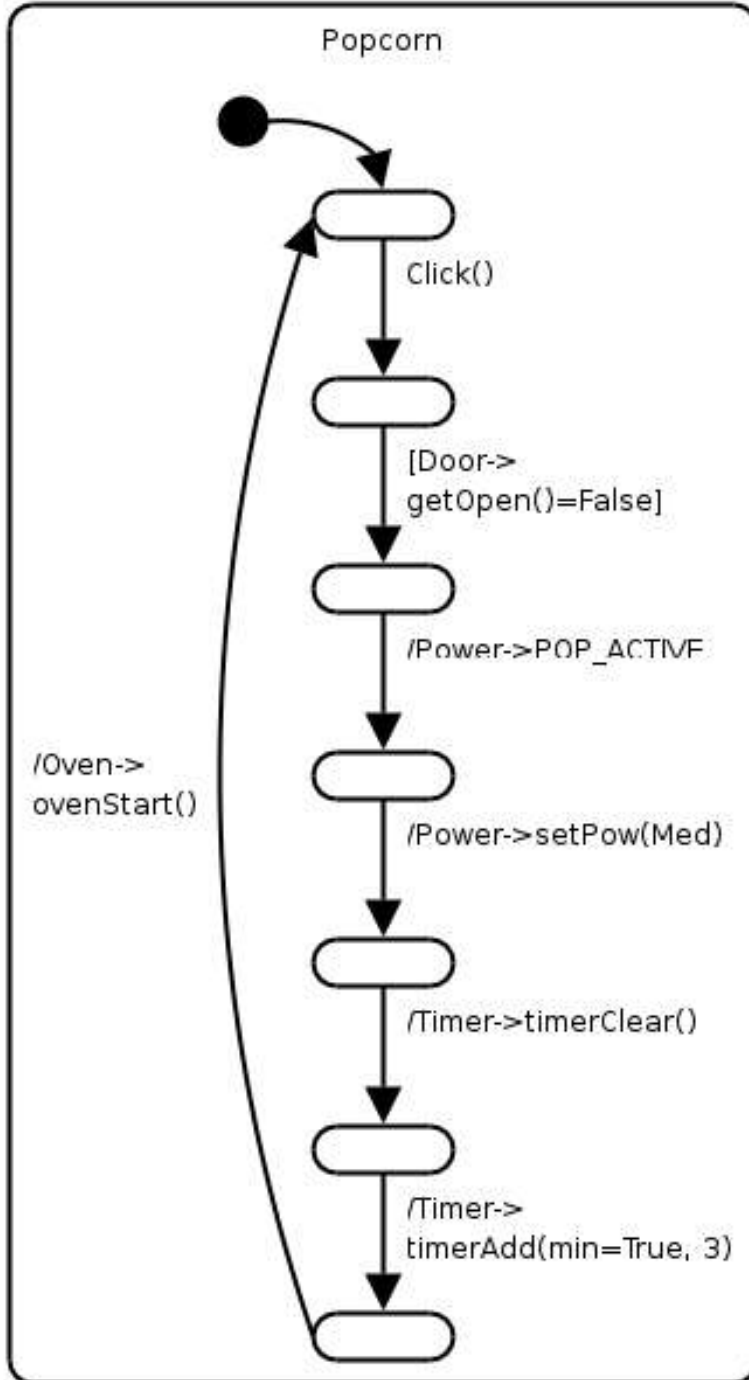
Clear

/Timer->  
timerClear()

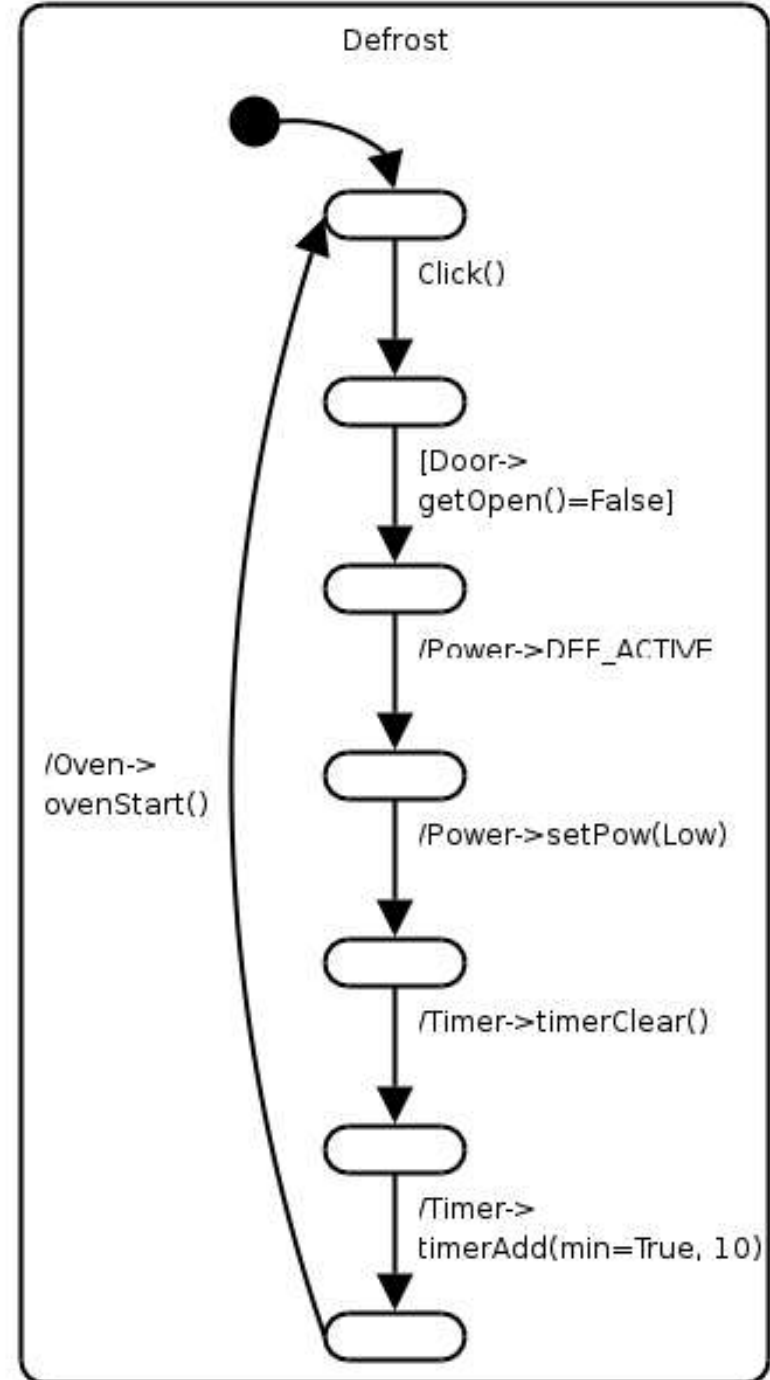




## Popcorn

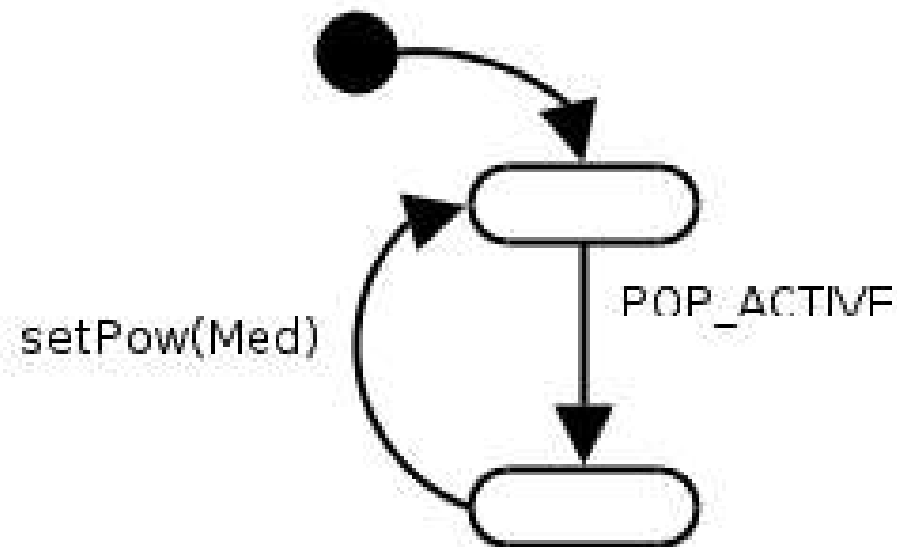


## Defrost

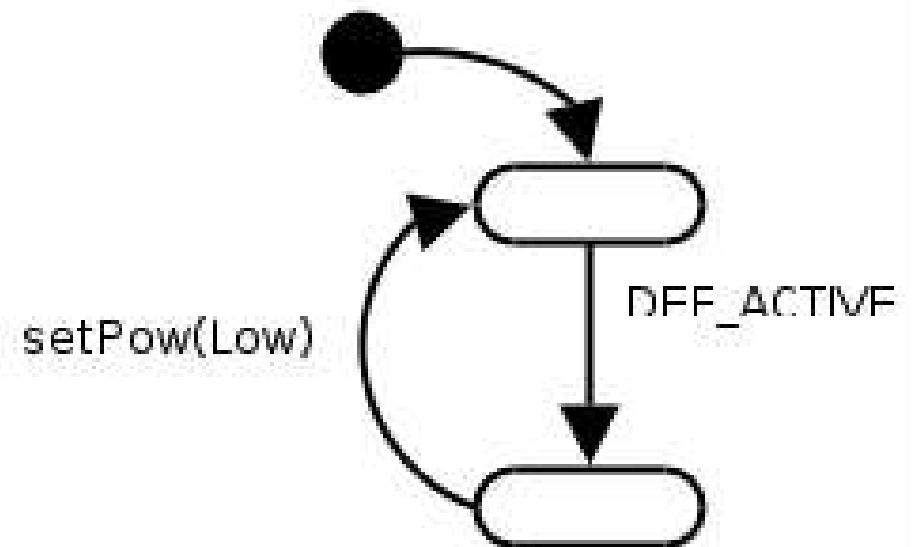


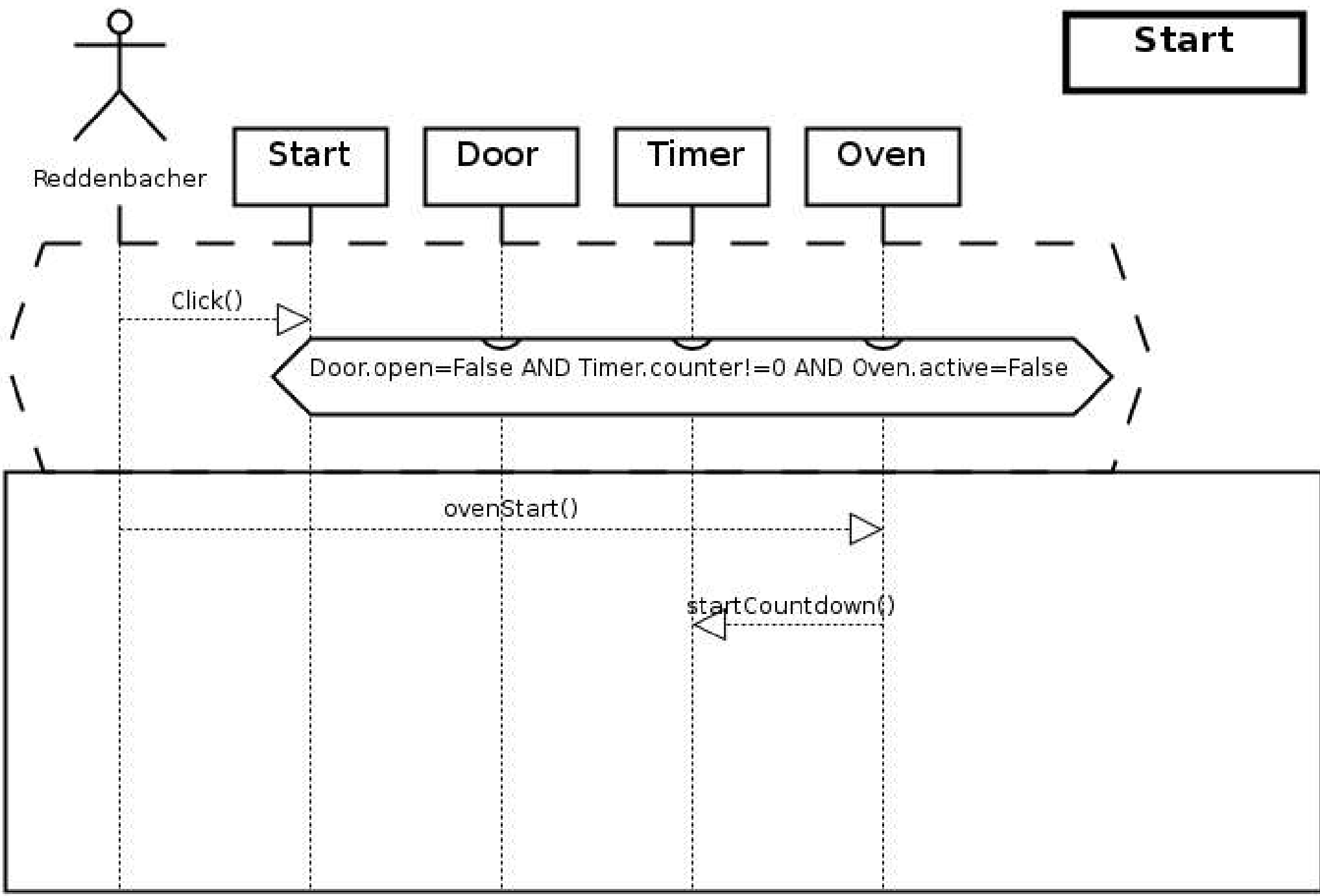
# Power

Popcorn



Defrost





Start

Start

Door

Timer

Oven

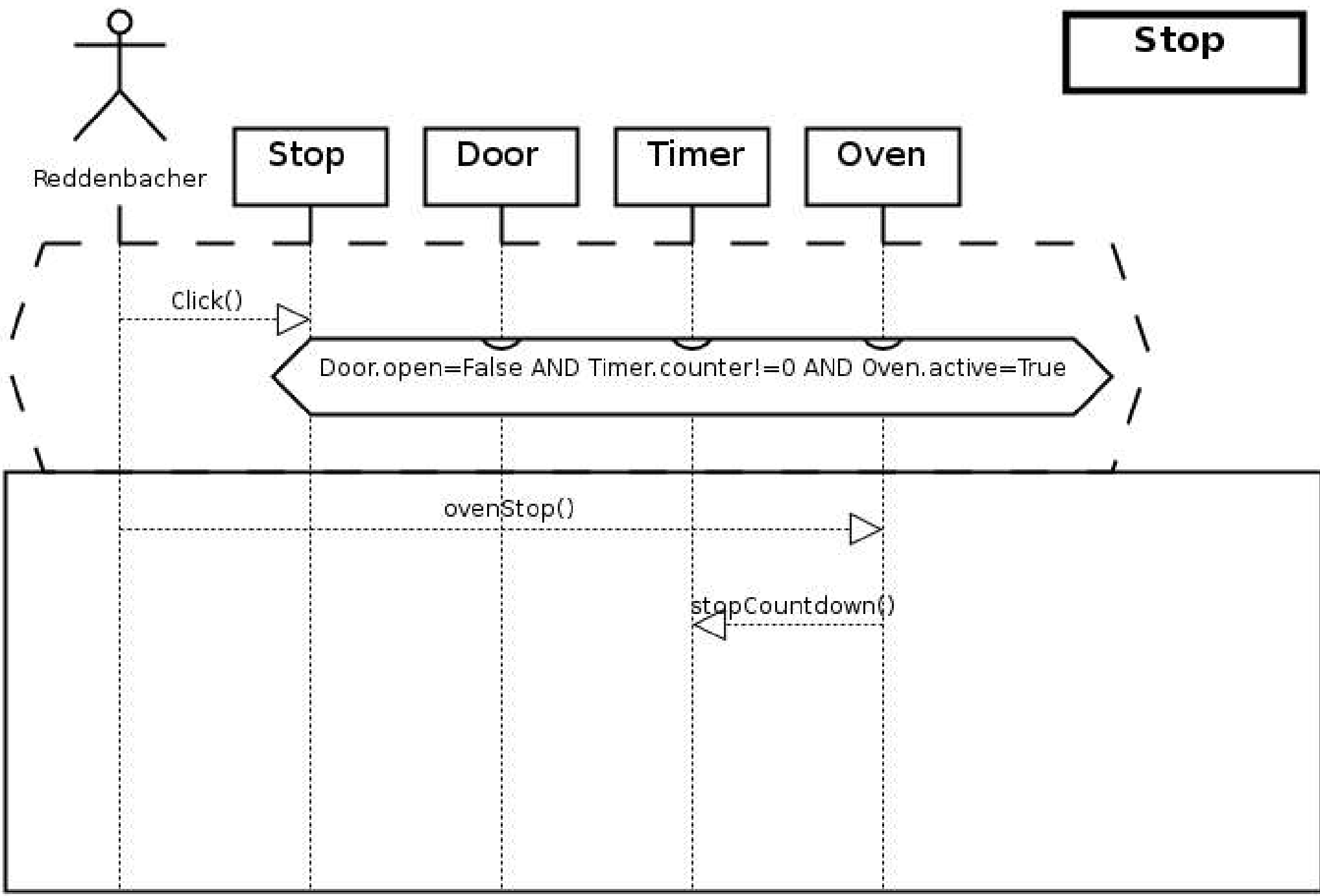
Reddenbacher

Click()

Door.open=False AND Timer.counter!=0 AND Oven.active=False

ovenStart()

startCountdown()



Stop

Stop

Door

Timer

Oven

Reddenbacher

Click()

Door.open=False AND Timer.counter!=0 AND Oven.active=True

ovenStop()

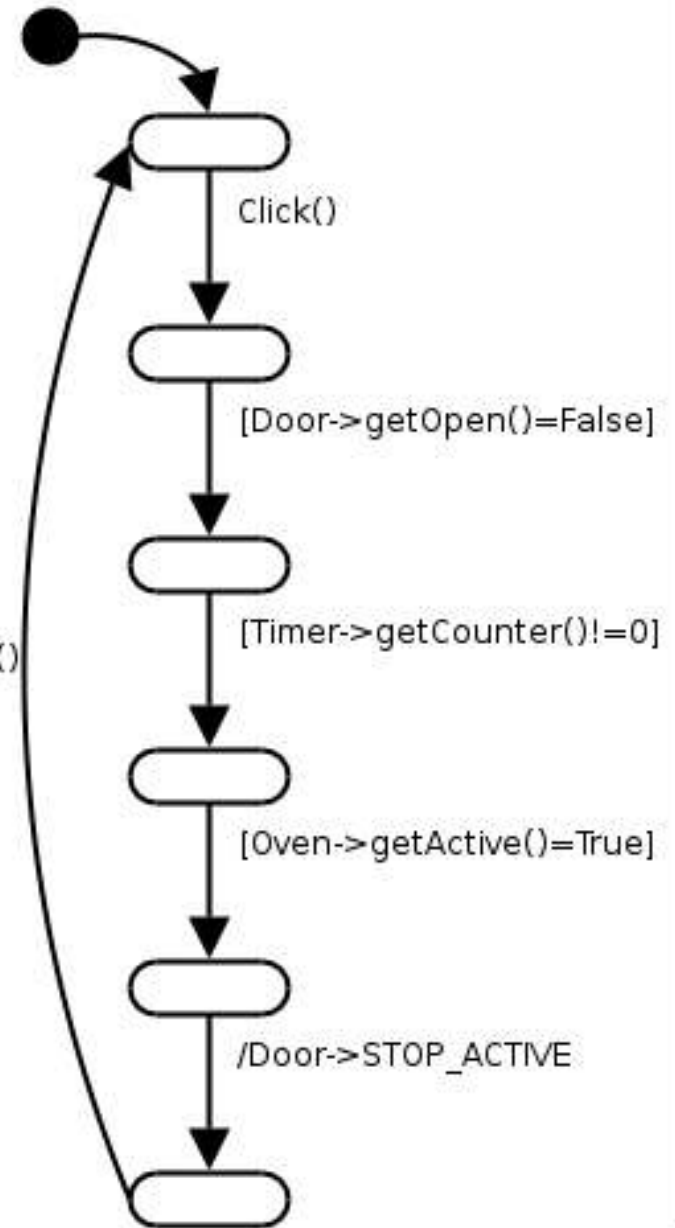
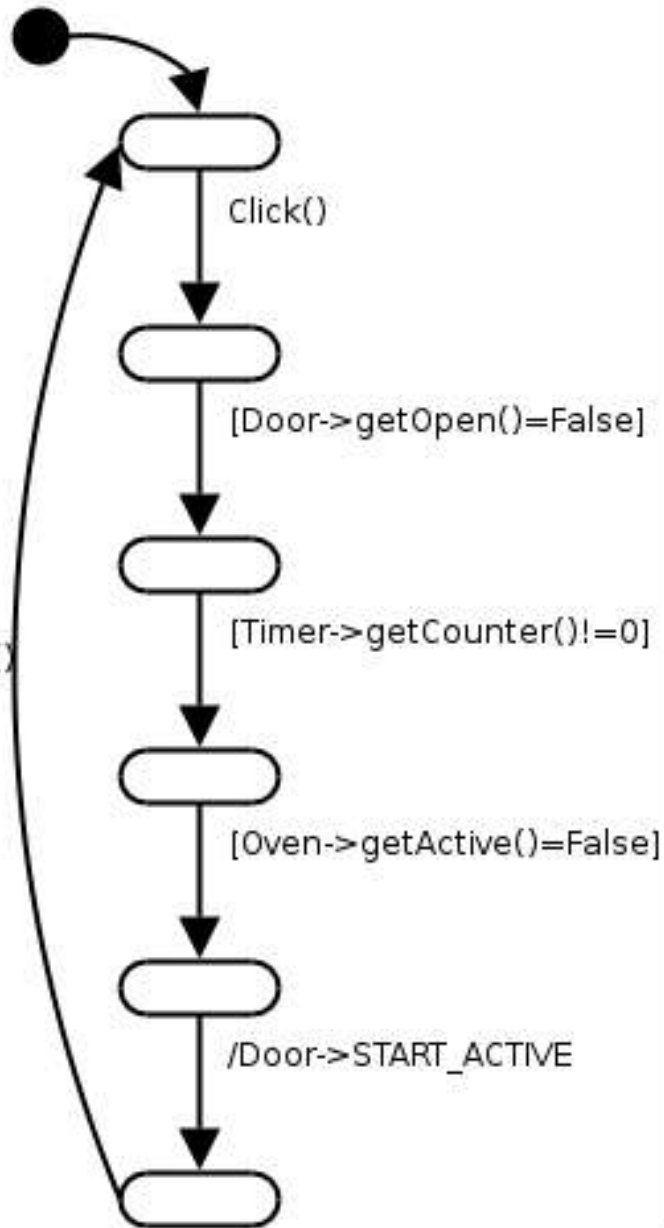
stopCountdown()

# Start

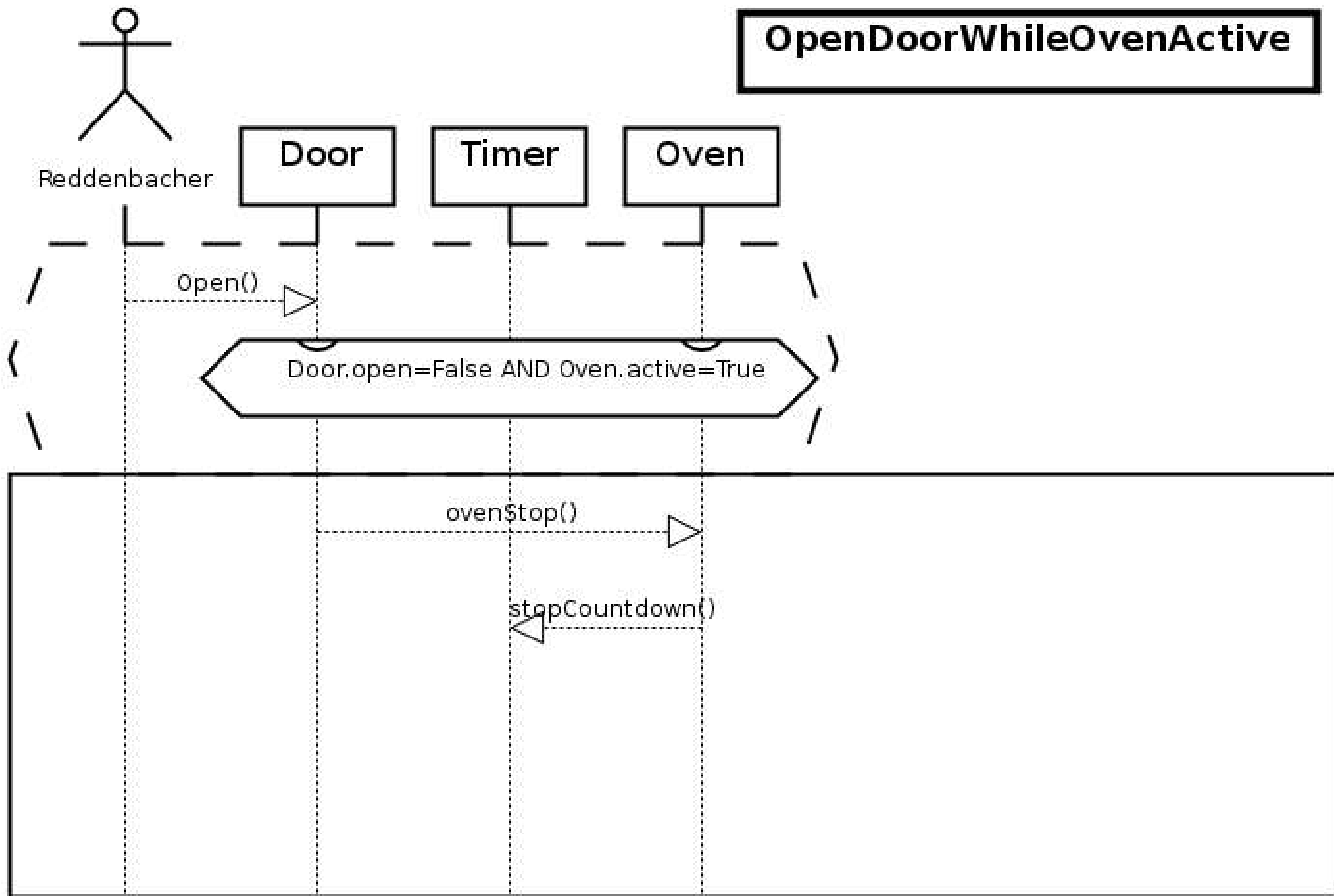
# Stop

Start

Stop

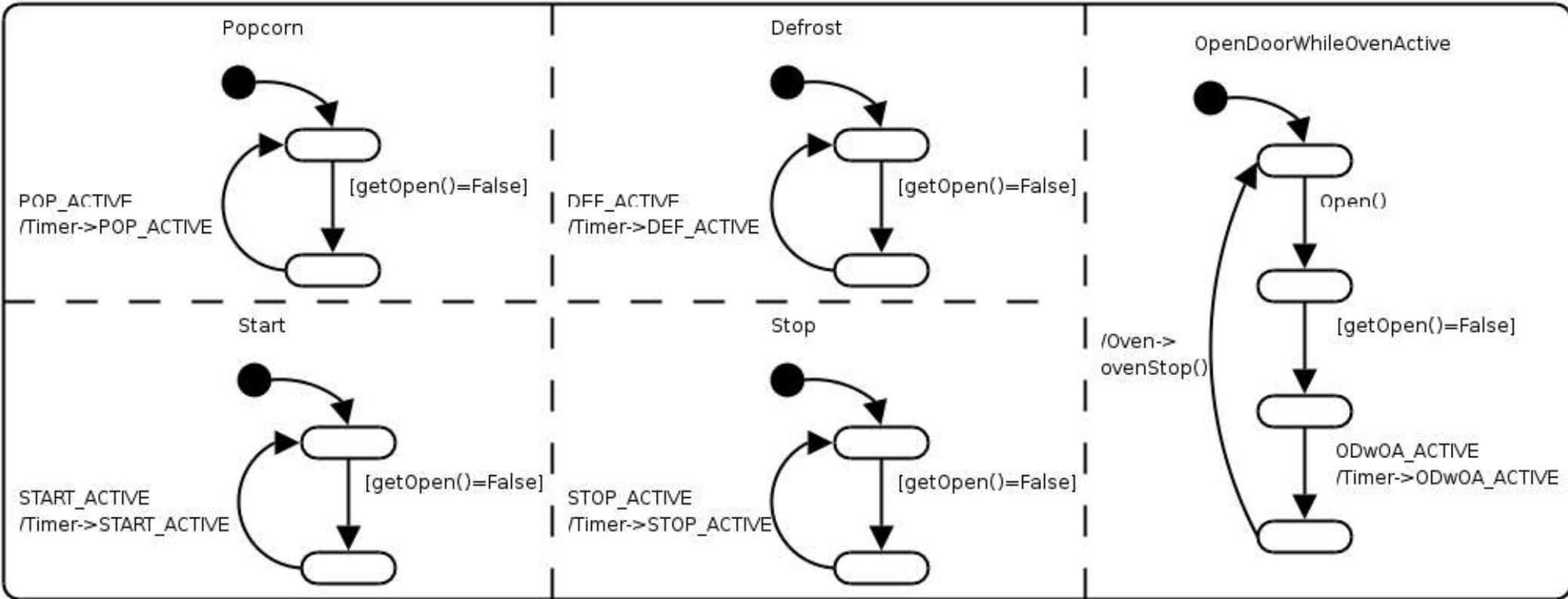


# OpenDoorWhileOvenActive

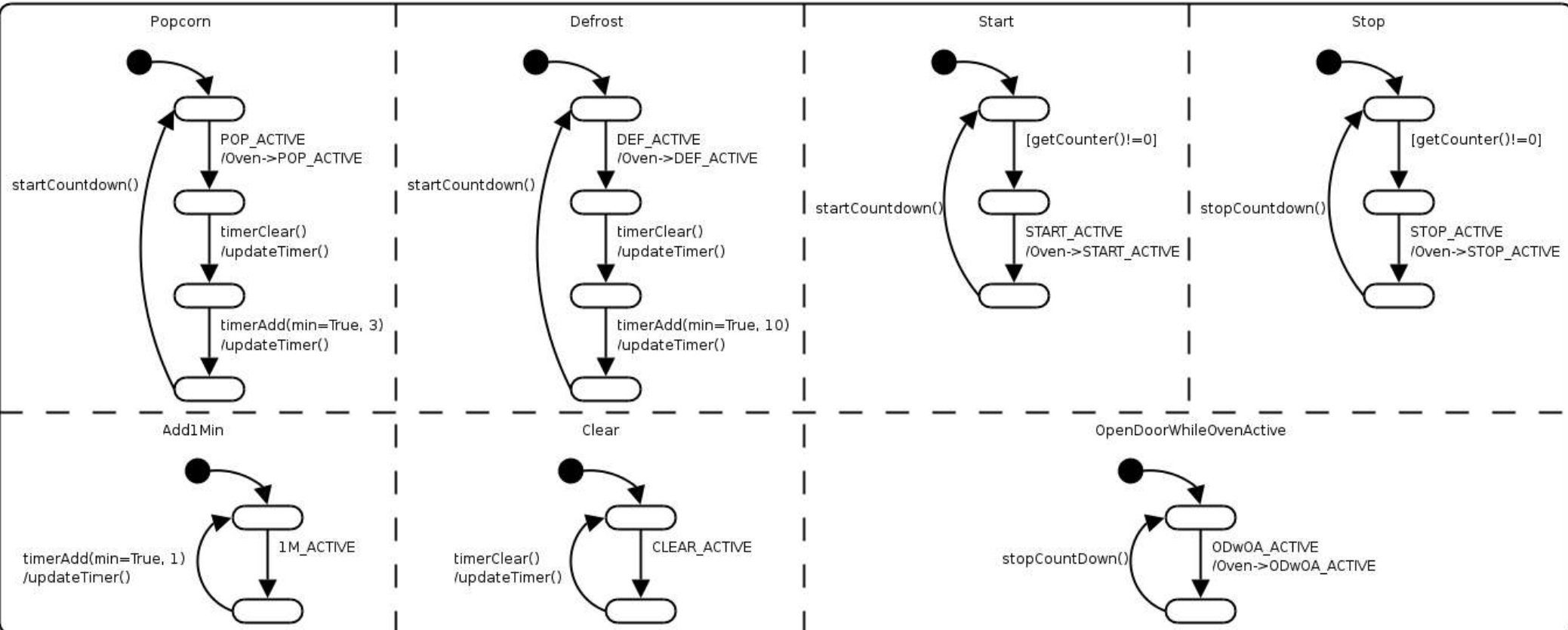




**Door**

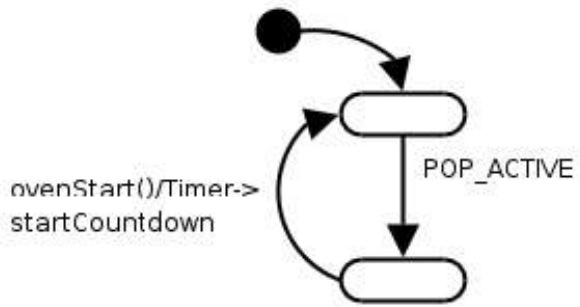


# Timer

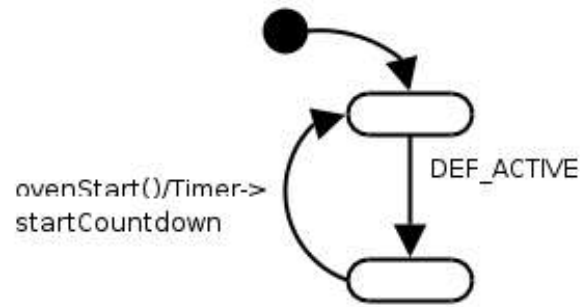


# Oven

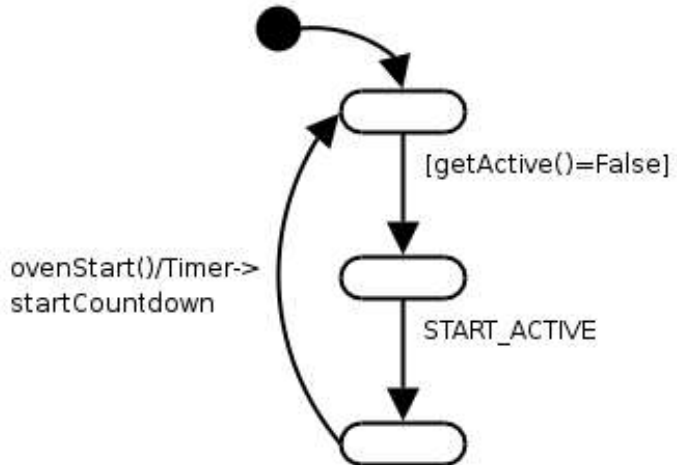
Popcorn



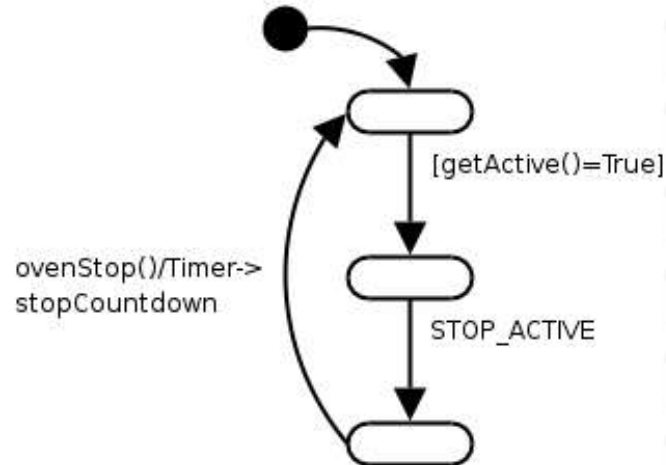
Defrost



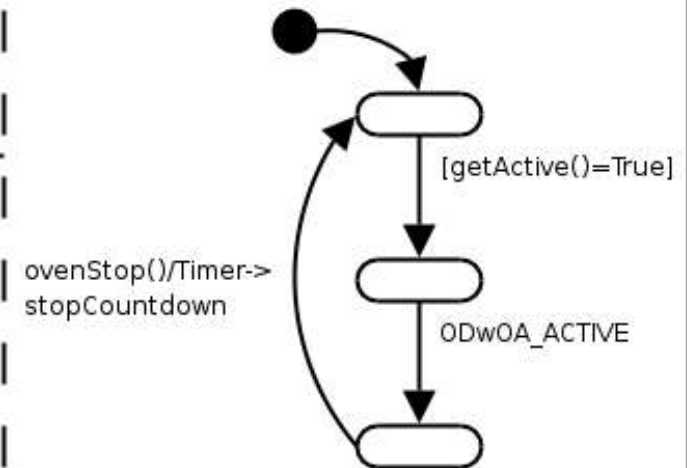
Start

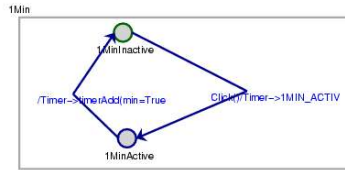
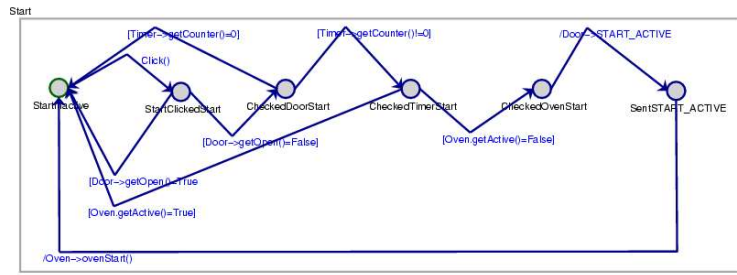
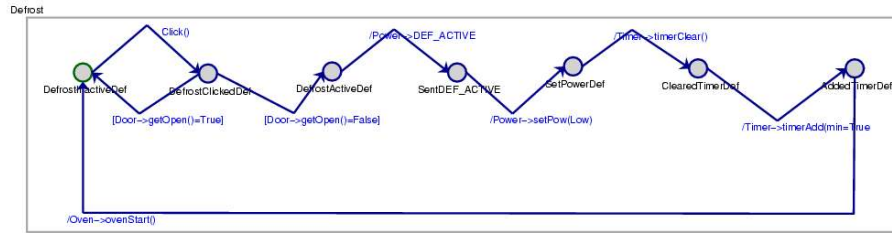
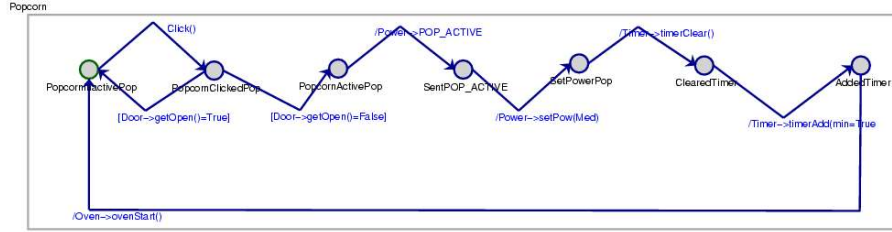


Stop



OpenDoorWhileOvenActive

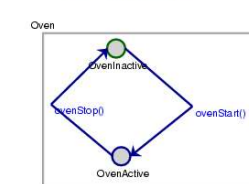
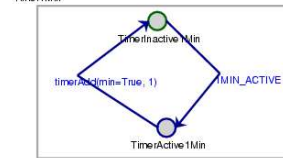
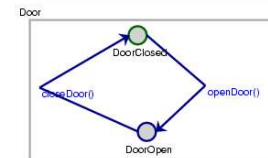
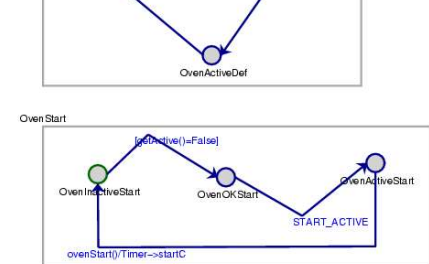
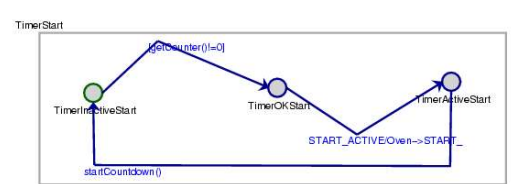
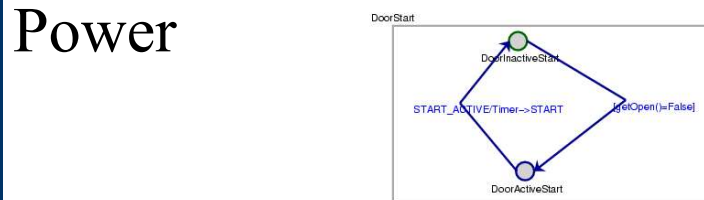
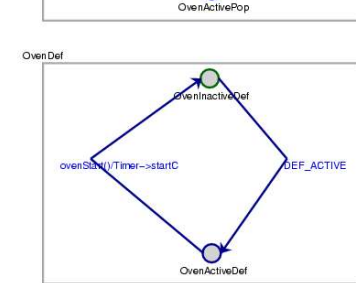
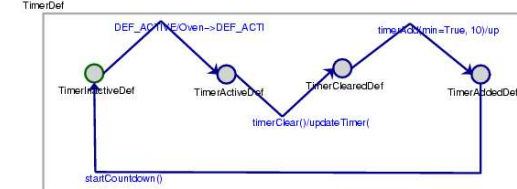
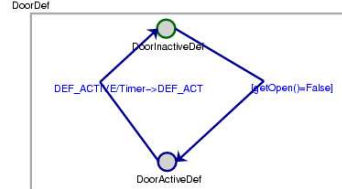
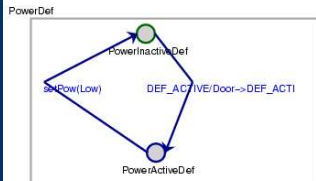
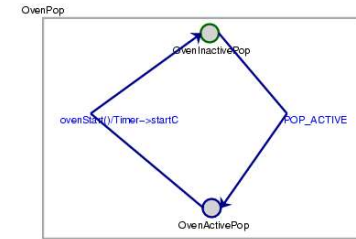
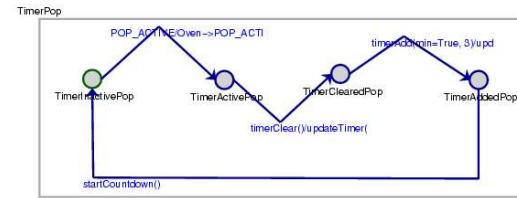
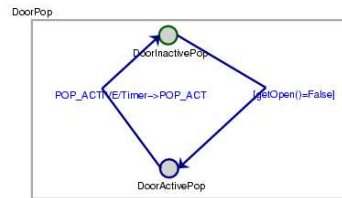
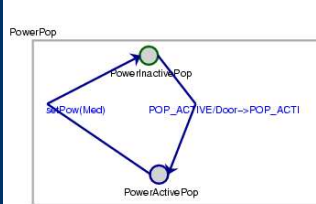




Start

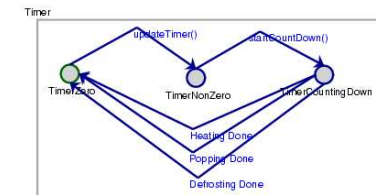
+1Min.

# Popcorn, Defrost



Oven

Door



Timer

# *Demonstration & Questions*

Final Questions?



# References

1. Feng, Thomas Huining. “Charts, a Formalism for Modeling and Simulation Based Design of Reactive Software Systems”.  
<http://mones.cs.mcgill.ca/people/TFENG/thesis/thesis.html>. Feb. 2004.
  2. Harel, David. “Can Behavioral Requirements be Executed? (And why would we want to do so?)”
  3. Harel, David and Hillel Kugler. “Synthesizing State-Based Object Systems from LSC Specifications”.
  4. Harel, David and Rami Marelly. “Specifying and Executing Behavioral Requirements: The Play-In/Play-Out Approach”.  
September 10, 2002.
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