ProMoBox: Domain-Specific Modelling Languages for Verification and Testing

Bart Meyers

Hans Vangheluwe

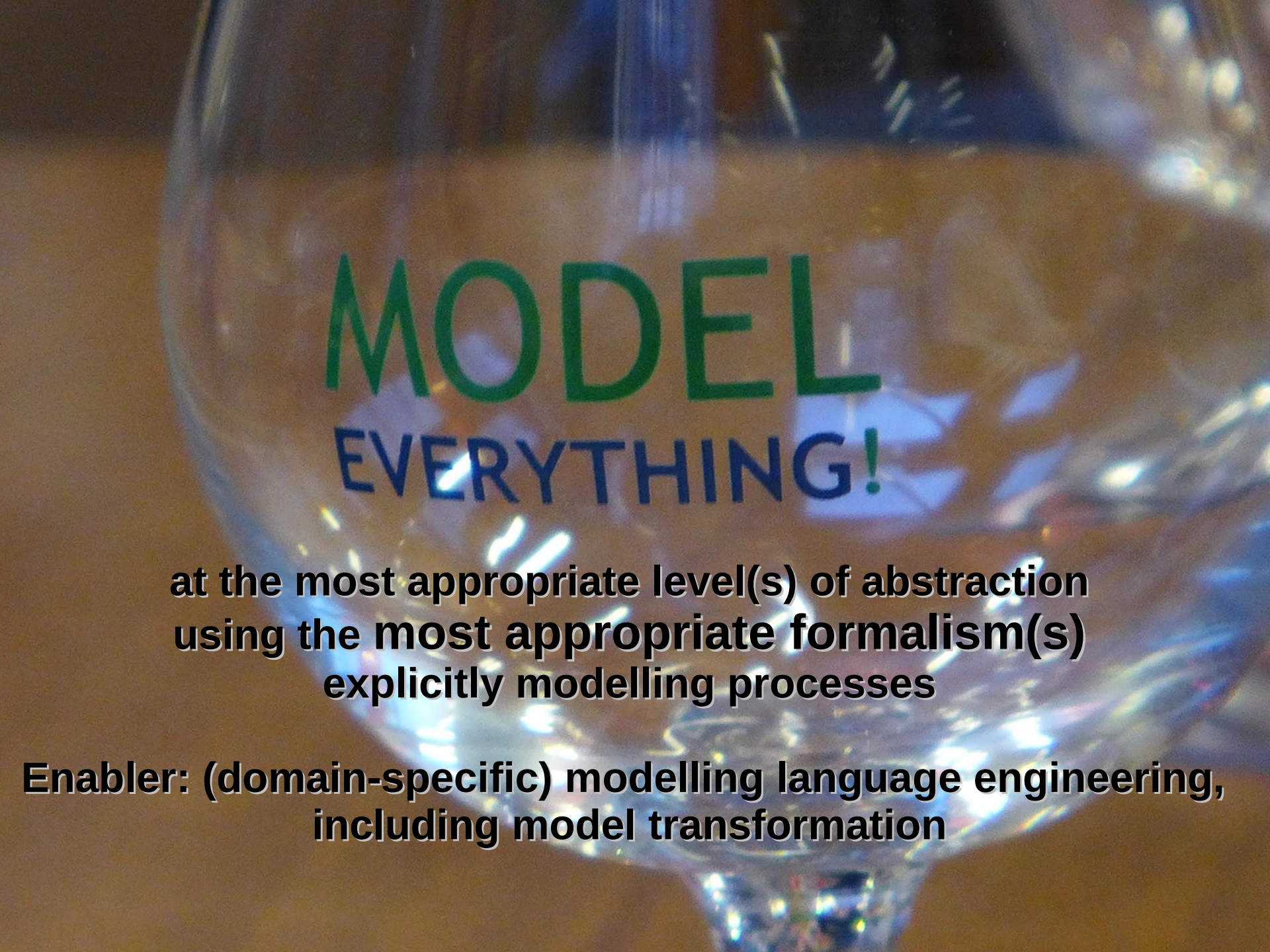
Universiteit Antwerpen

Ansymo
Antwerp Systems & Software Modelling
University of Antwerp

Nexor
Cyber-Physical Systems
University of Antwerp

FLANDERS MAKE
MANUFACTURING INNOVATION NETWORK

McGill



at the most appropriate level(s) of abstraction
using the most appropriate formalism(s)
explicitly modelling processes

Enabler: (domain-specific) modelling language engineering, including model transformation

UNIVERSITÉ DE GENÈVE
Centre Universitaire d'Informatique

FACULTÉ DES SCIENCES
Professeur D. Buchs, directeur
Professeur G. Falquet, codirecteur

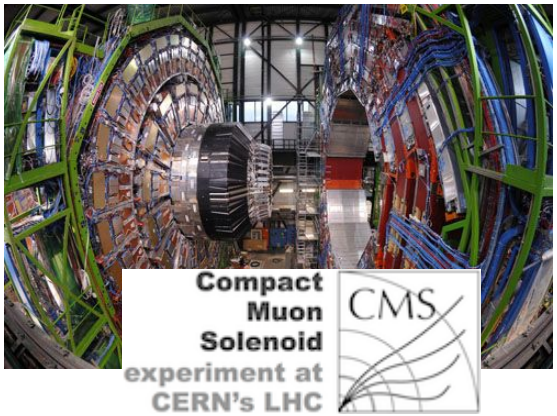
A Methodology For The Development Of Complex Domain Specific Languages

THÈSE

présentée à la Faculté des sciences de l'Université de Genève
pour obtenir le grade de Docteur ès sciences, mention informatique

2010

Matteo Risoldi



CMS Tracker Cosmic Rack

Design

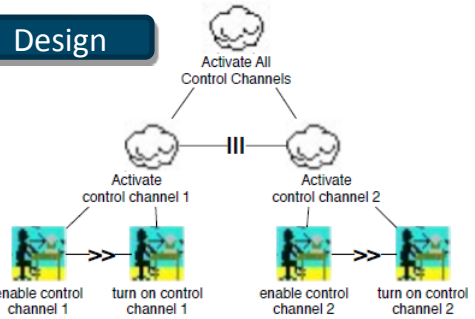
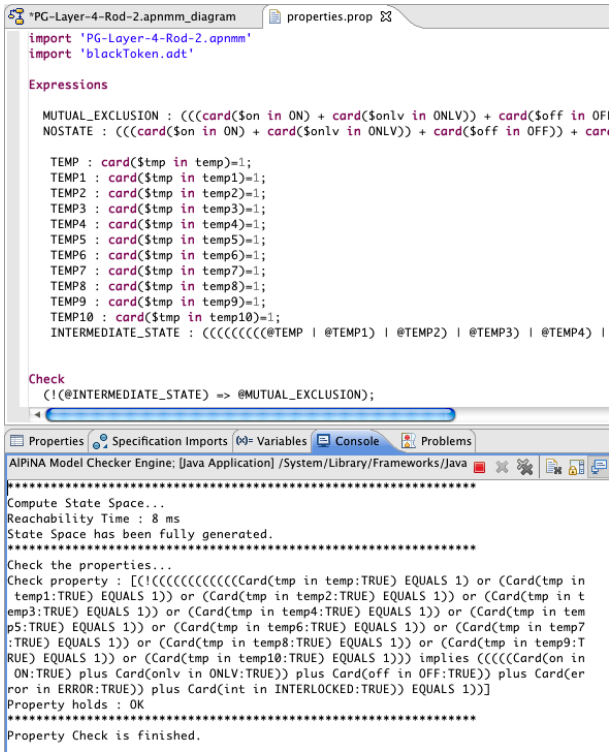


Figure 4.8. CTT for the turn on control channels *task*

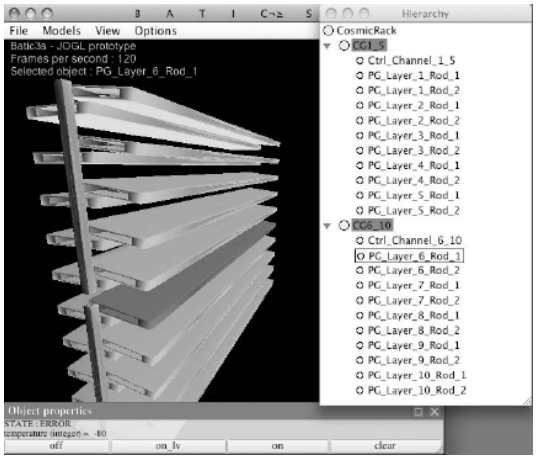
Property

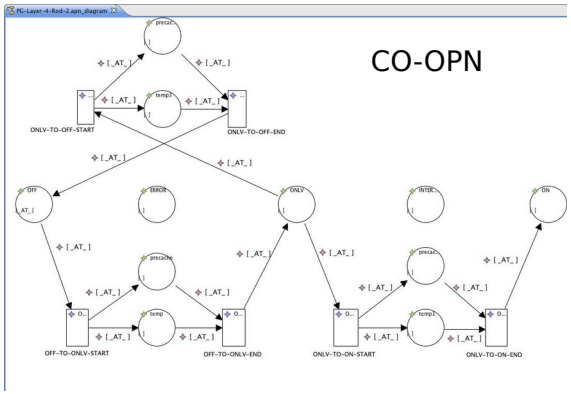


Alpina

Application

UI prototype





CO-OPN

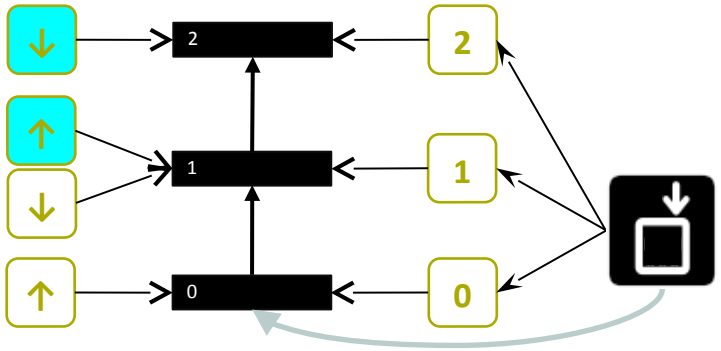
Domain-Specific Modelling

Modelling of complex systems for **domain users**

- Familiar domain **concepts** (reduces cognitive gap)
- Incorporate domain **constraints** (maximally constrain)

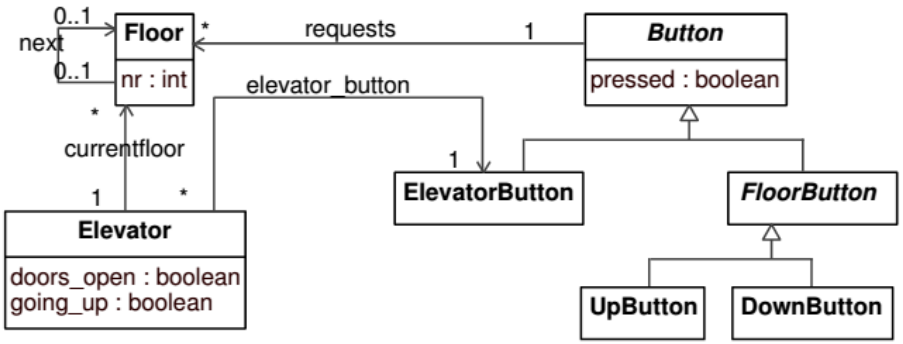
Precisely defined (semantics) models

Example: elevator system model in an Elevator DSL

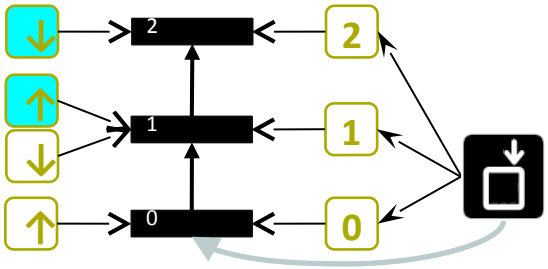


Modelling Language Engineering

Meta-modeling
(to specify language abstract syntax)

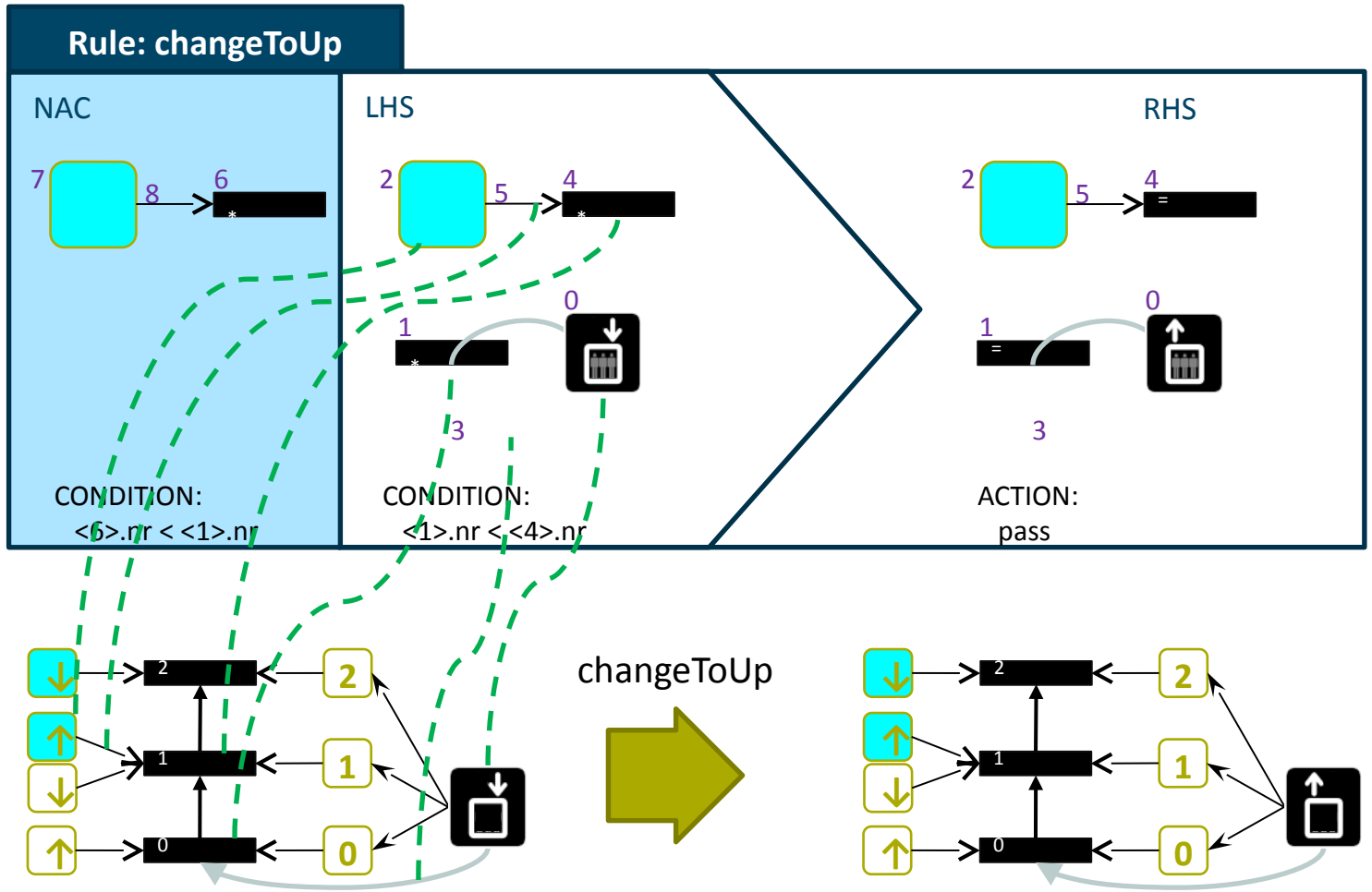


conforms to

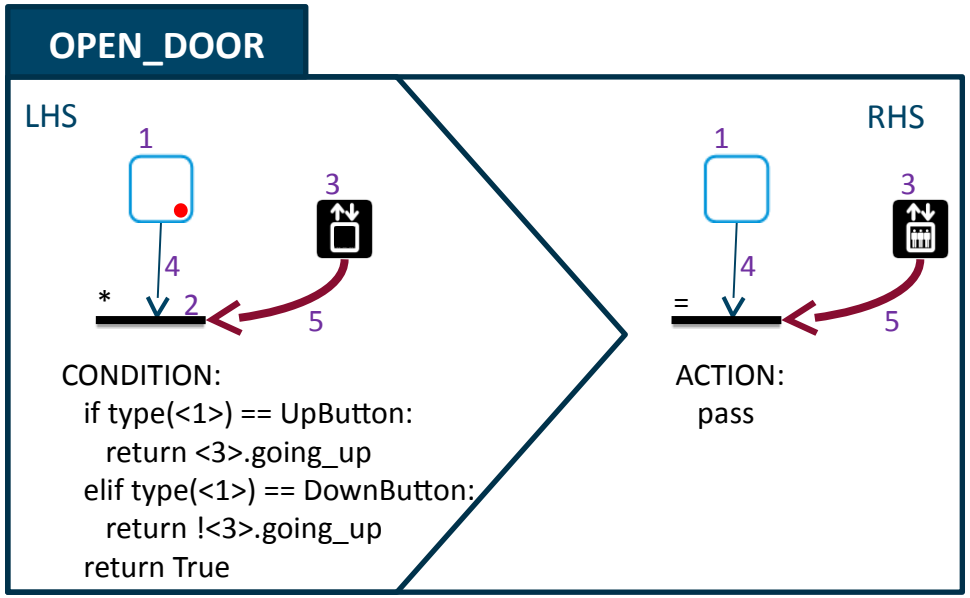


Model Transformation
(to specify language semantics)

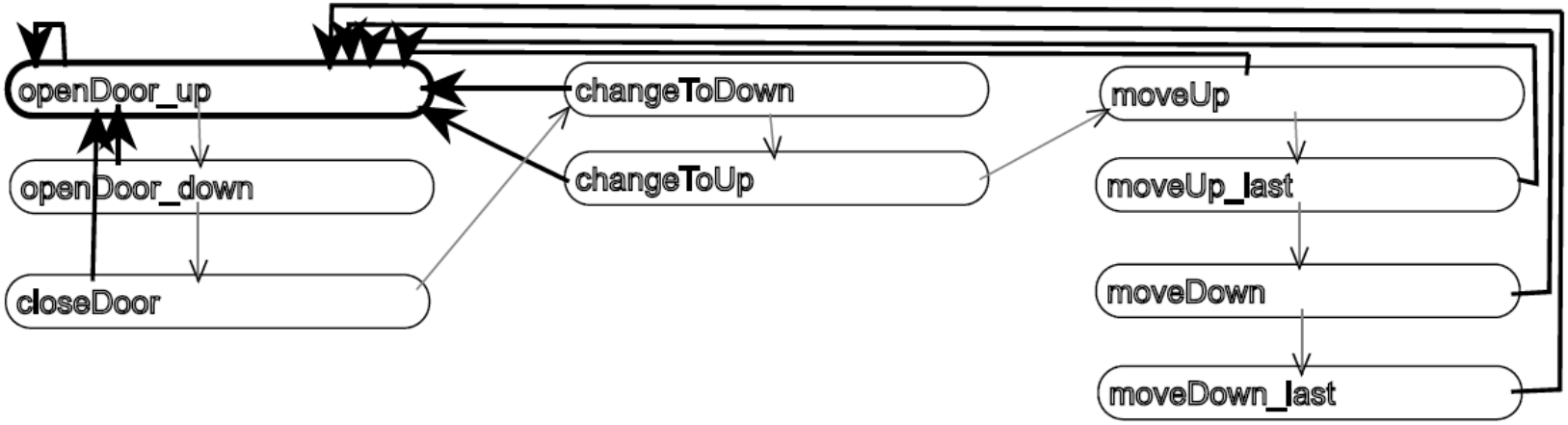
Rule-Based Transformation (rule)

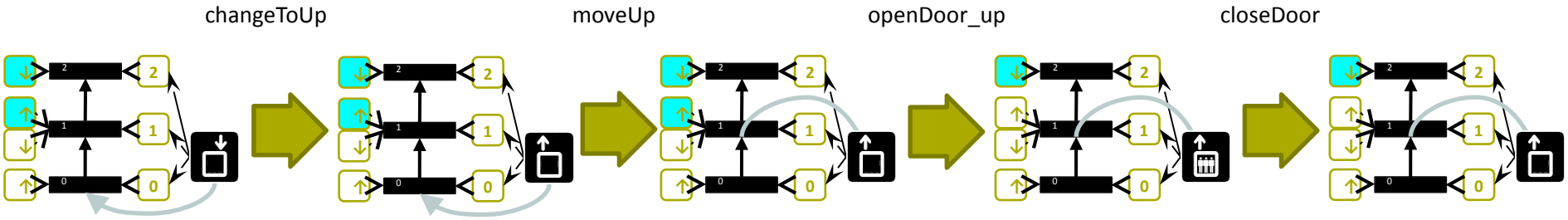


Rule-Based Transformation (rule)

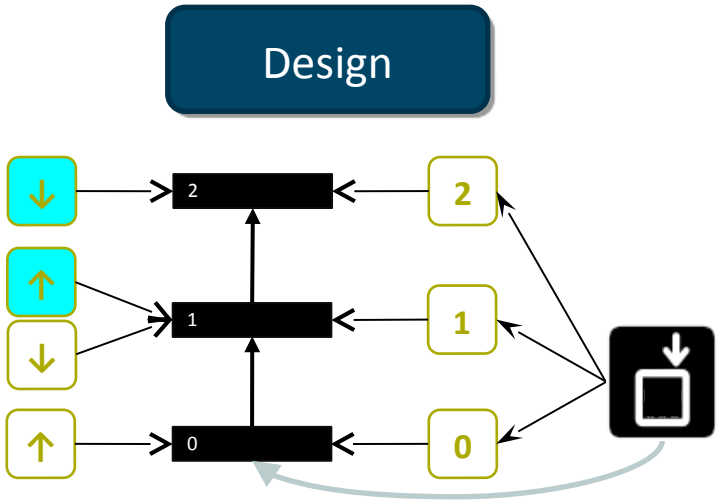


Rule-Based Transformation (schedule)





Properties for DSMLs: State of the Art



$\models$

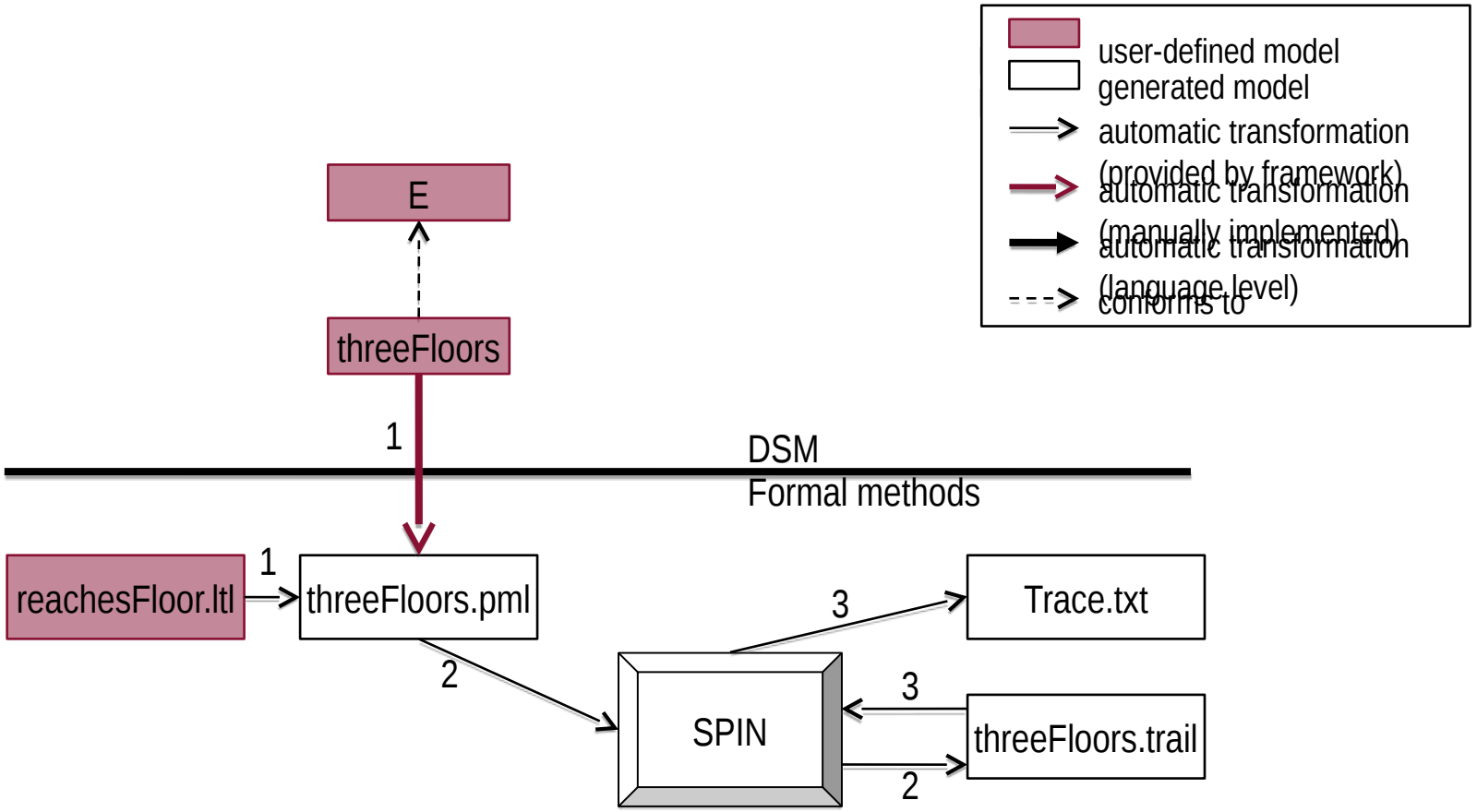
Property

$\models$

LTL formula

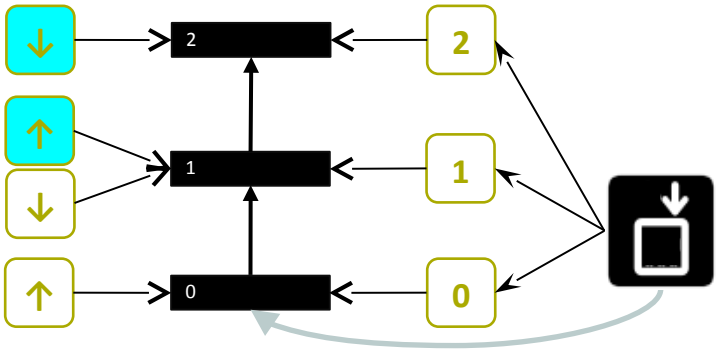
$$\Box(((go0 \wedge up0) \vee \Diamond(floor0 \vee idle)) \rightarrow ((\neg(floor0) \vee \neg(floor0 \vee idle)) \mathcal{U}((floor0 \vee idle) \wedge (((floor0) \vee \neg(floor0 \vee idle)) \mathcal{U}((floor0 \vee idle) \wedge ((\neg(floor0) \vee \neg(floor0 \vee idle)) \mathcal{U}((floor0 \vee idle) \wedge (((floor0) \vee \neg(floor0 \vee idle)) \mathcal{U}((floor0 \vee idle) \wedge (\neg(floor0) \mathcal{U}(floor0 \vee idle)))))))))) \vee \Box(((go1 \wedge up1 \wedge down1) \vee \Diamond(floor1 \vee idle)) \rightarrow ((\neg(floor1) \vee \neg(floor1 \vee idle)) \mathcal{U}((floor1 \vee idle) \wedge (((floor1) \vee \neg(floor1 \vee idle)) \mathcal{U}((floor1 \vee idle) \wedge ((\neg(floor1) \vee \neg(floor1 \vee idle)) \mathcal{U}((floor1 \vee idle) \wedge (((floor1) \vee \neg(floor1 \vee idle)) \mathcal{U}((floor1 \vee idle) \wedge (\neg(floor1) \mathcal{U}(floor1 \vee idle)))))))))) \vee \Box(((go2 \wedge down2) \vee \Diamond(floor2 \vee idle)) \rightarrow ((\neg(floor2) \vee \neg(floor2 \vee idle)) \mathcal{U}((floor2 \vee idle) \wedge (((floor2) \vee \neg(floor2 \vee idle)) \mathcal{U}((floor2 \vee idle) \wedge ((\neg(floor2) \vee \neg(floor2 \vee idle)) \mathcal{U}((floor2 \vee idle) \wedge (((floor2) \vee \neg(floor2 \vee idle)) \mathcal{U}((floor2 \vee idle) \wedge (\neg(floor2) \mathcal{U}(floor2 \vee idle)))))))))))$$

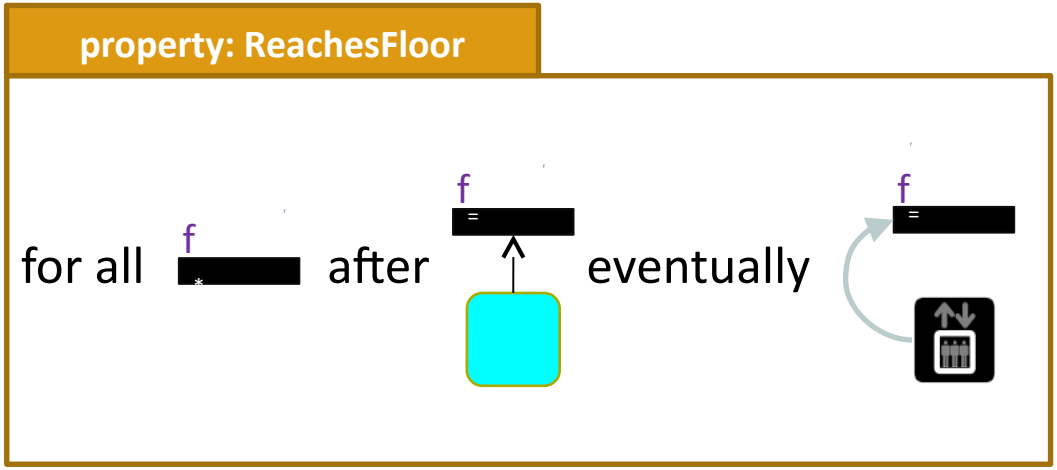
State of the Art: Architecture



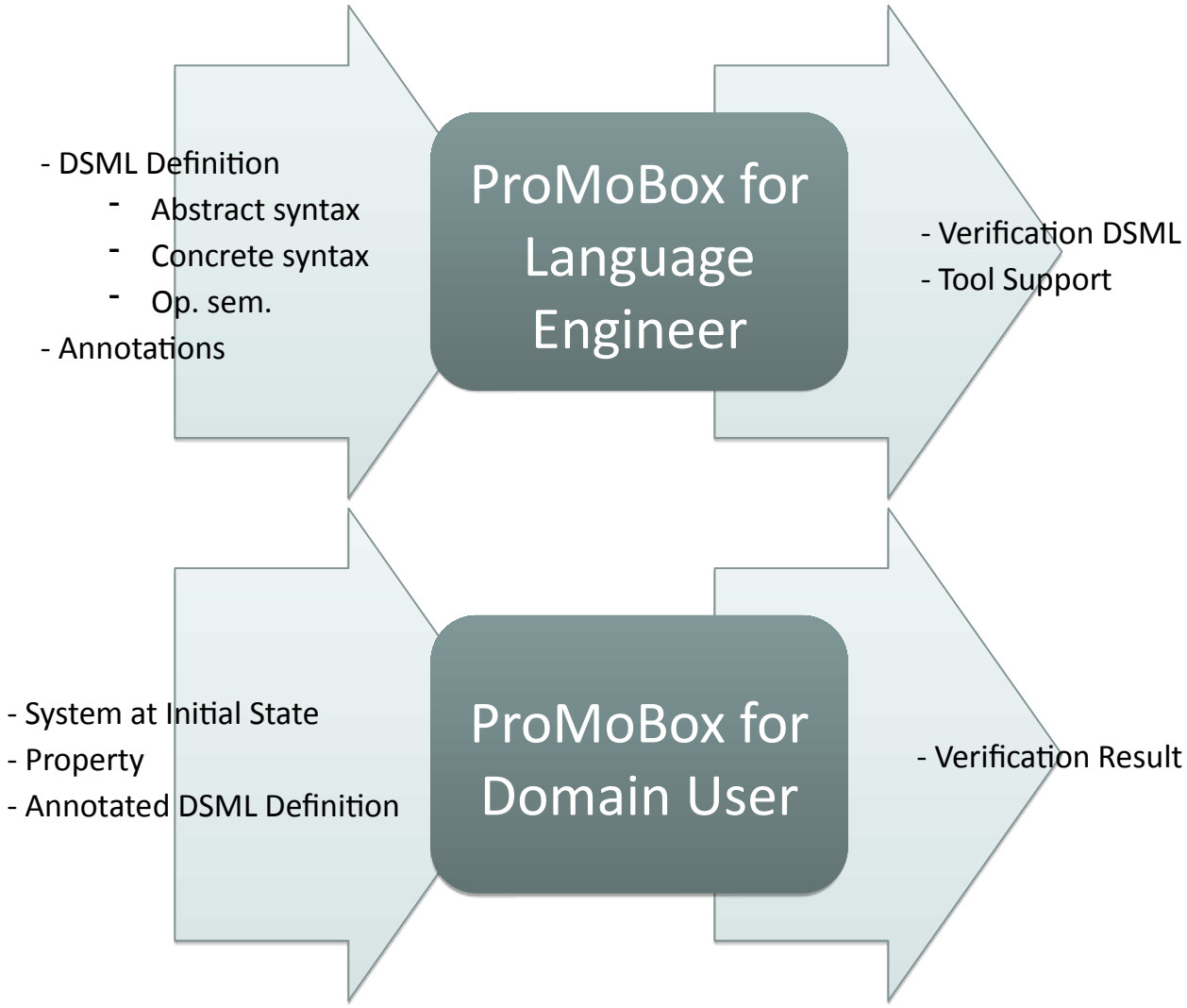
Properties for DSMLs: Property DSML

Design ⊨ Property

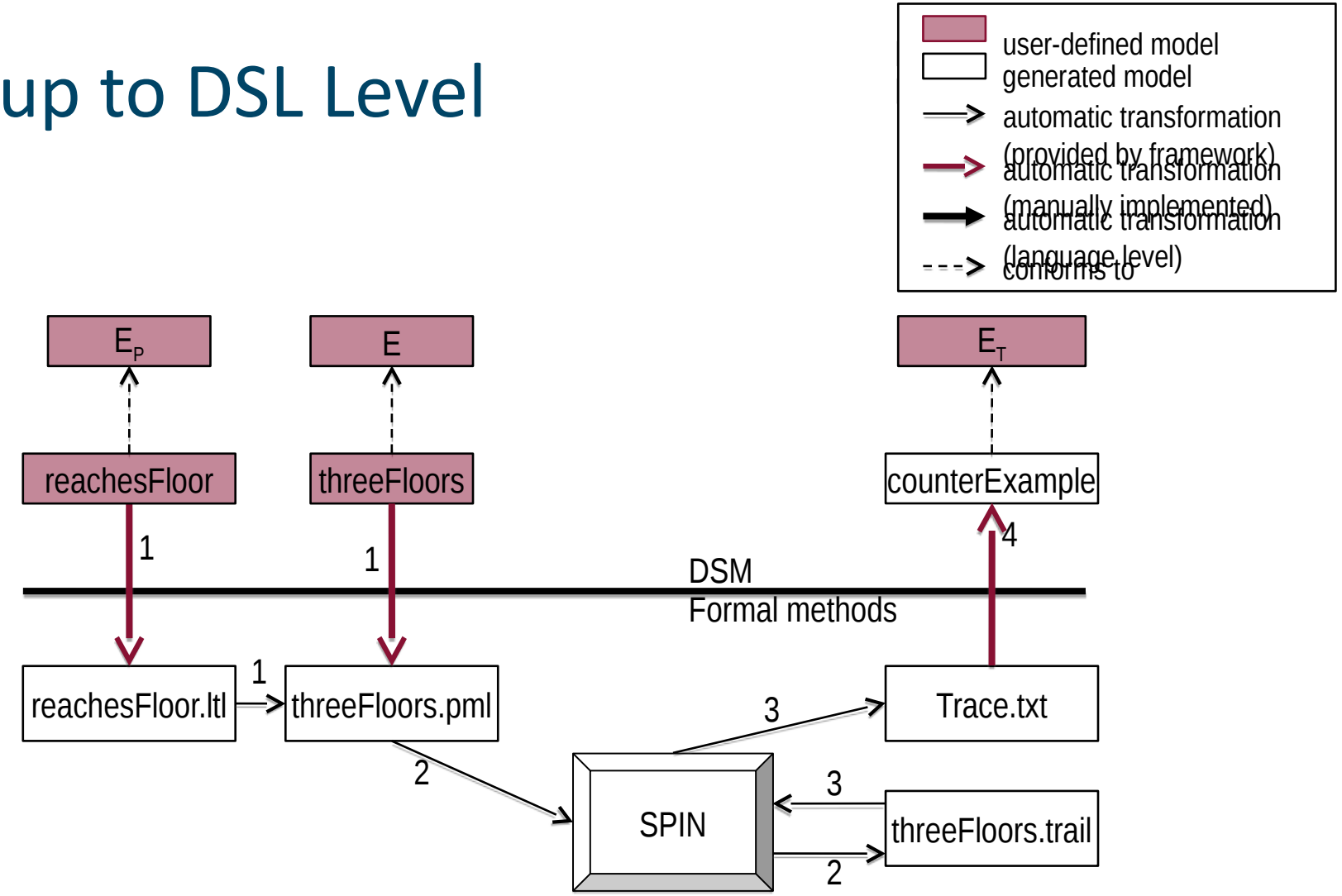




Verification Support for DSMLs



Pull up to DSL Level

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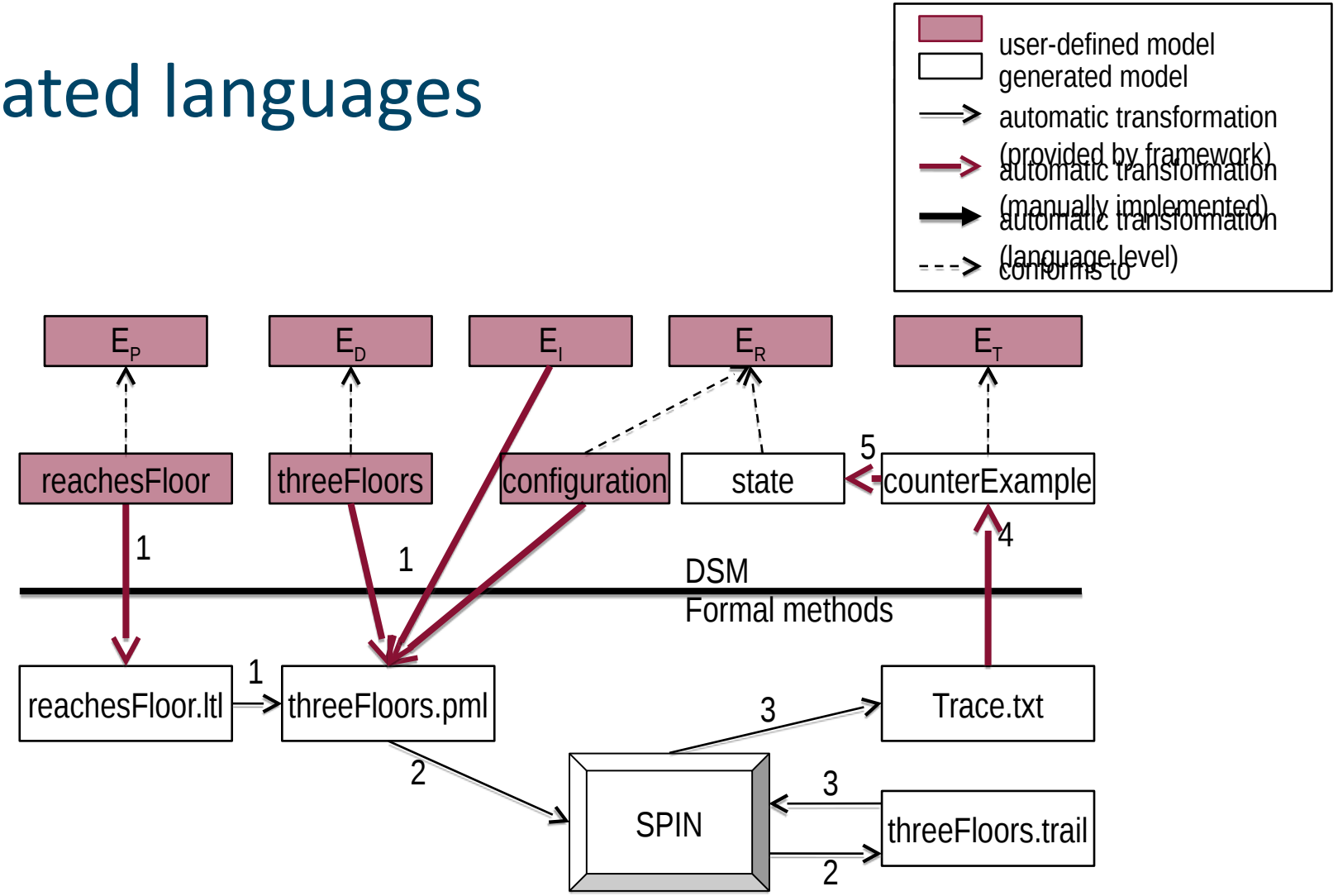
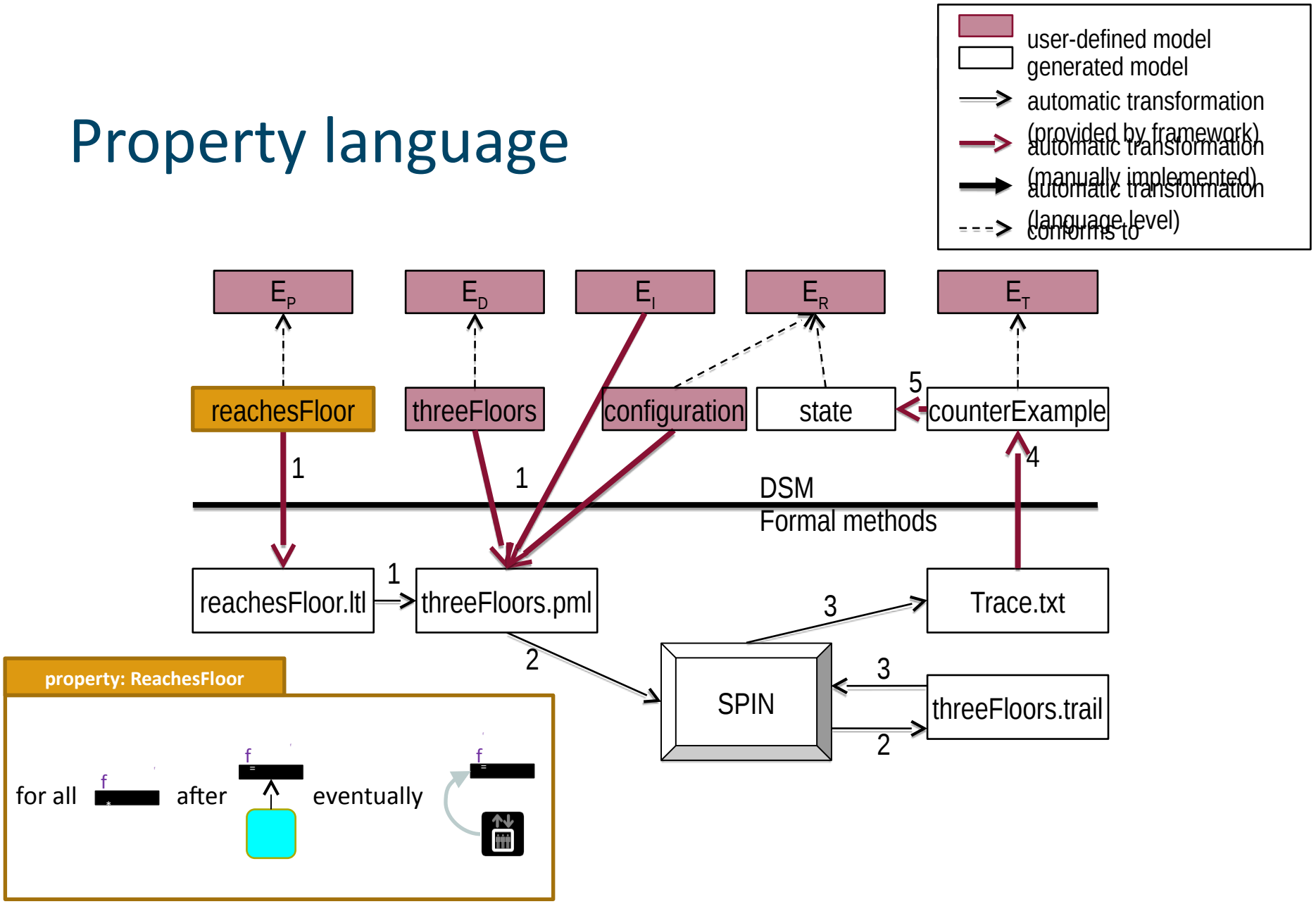
language
engineering
with ProMoBox

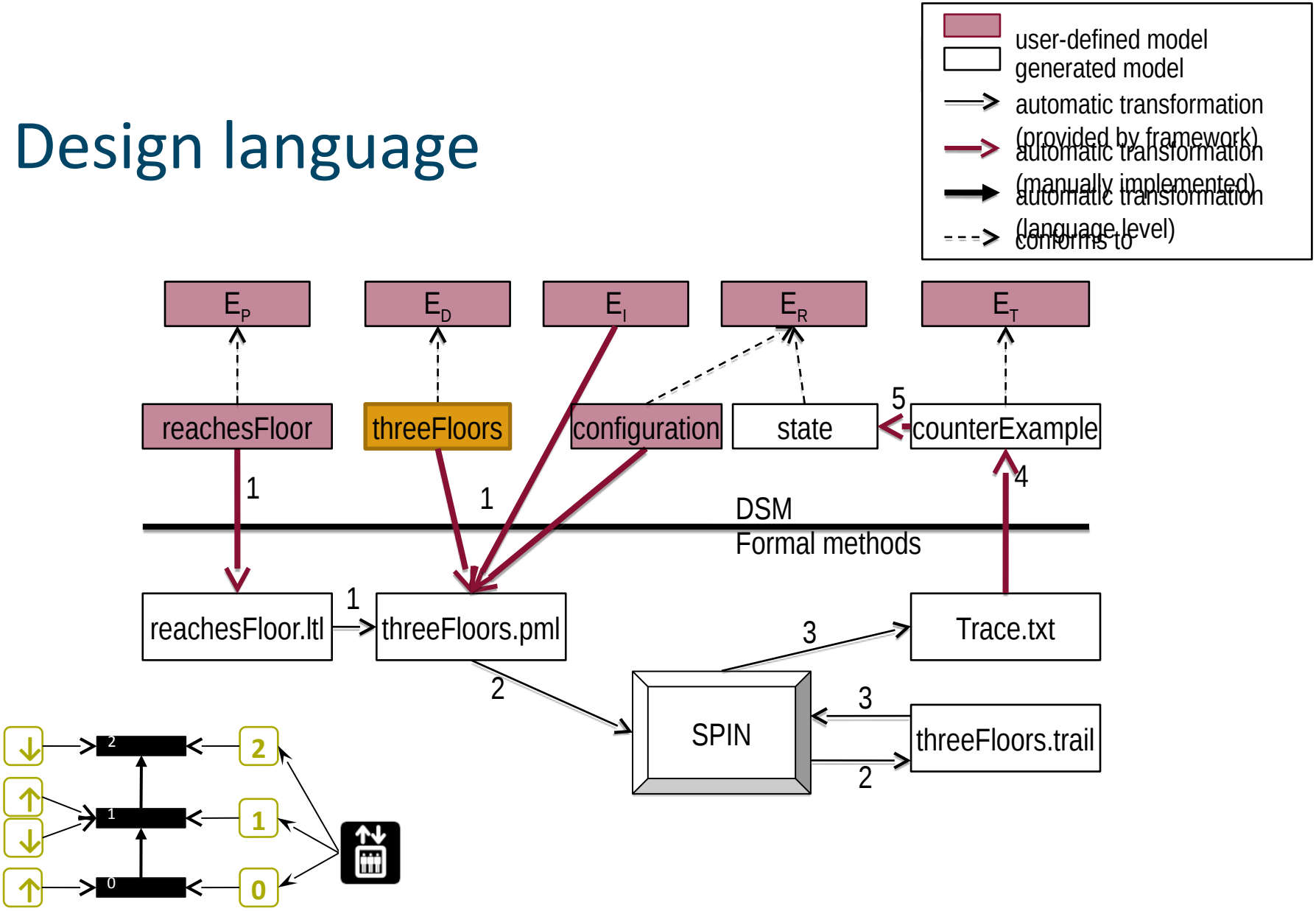
5 related languages



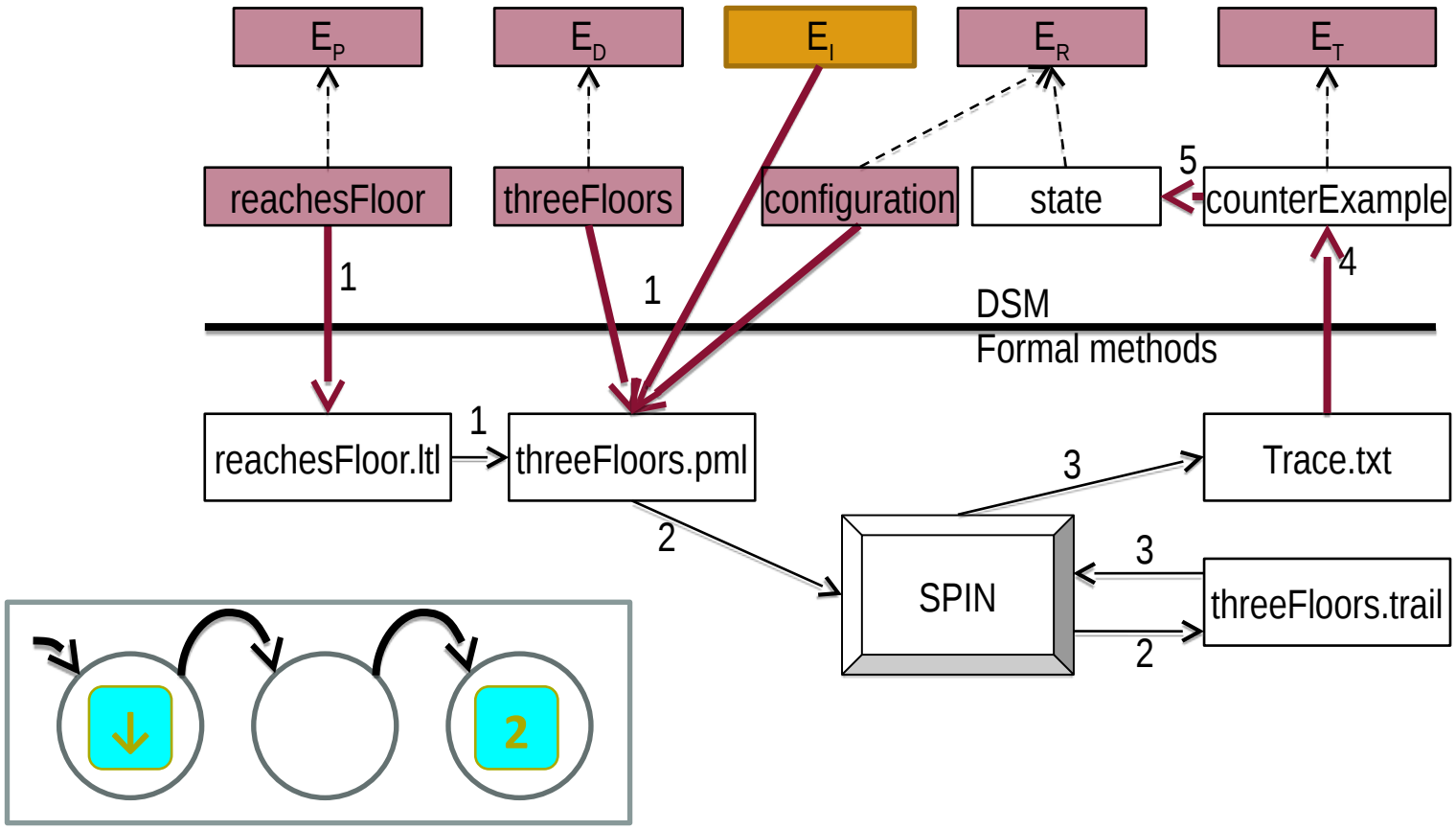
Property language



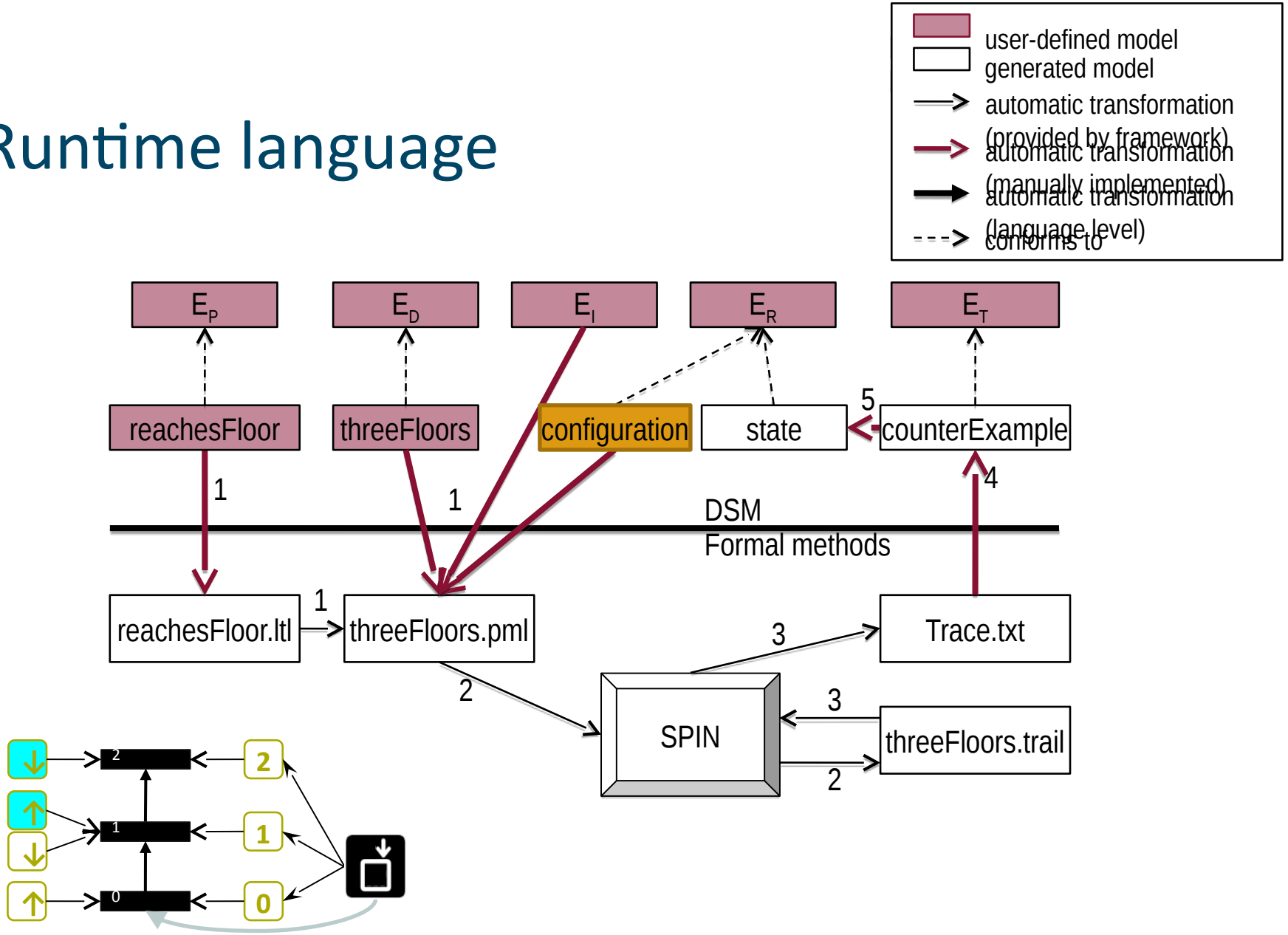
Design language



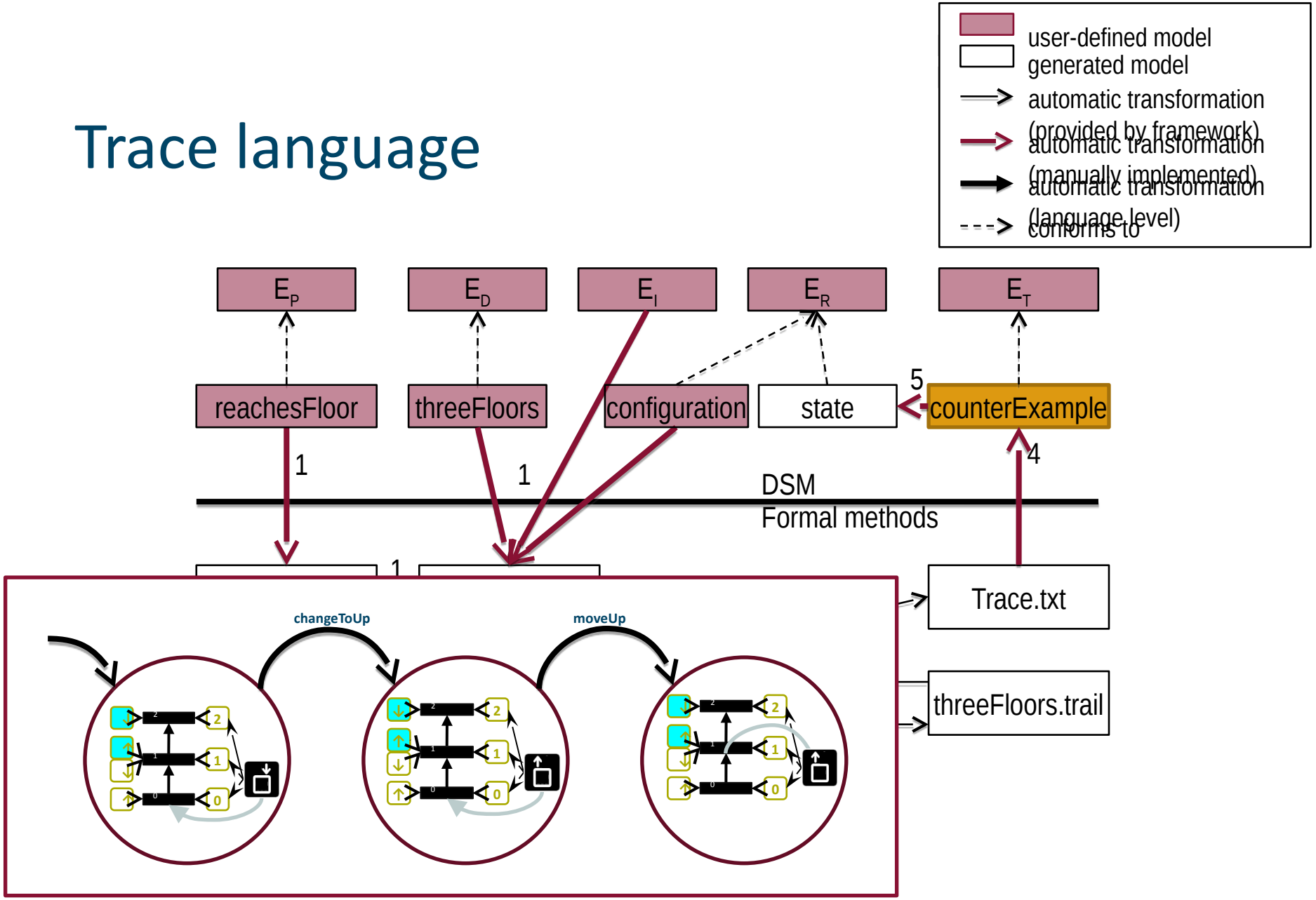
Input language



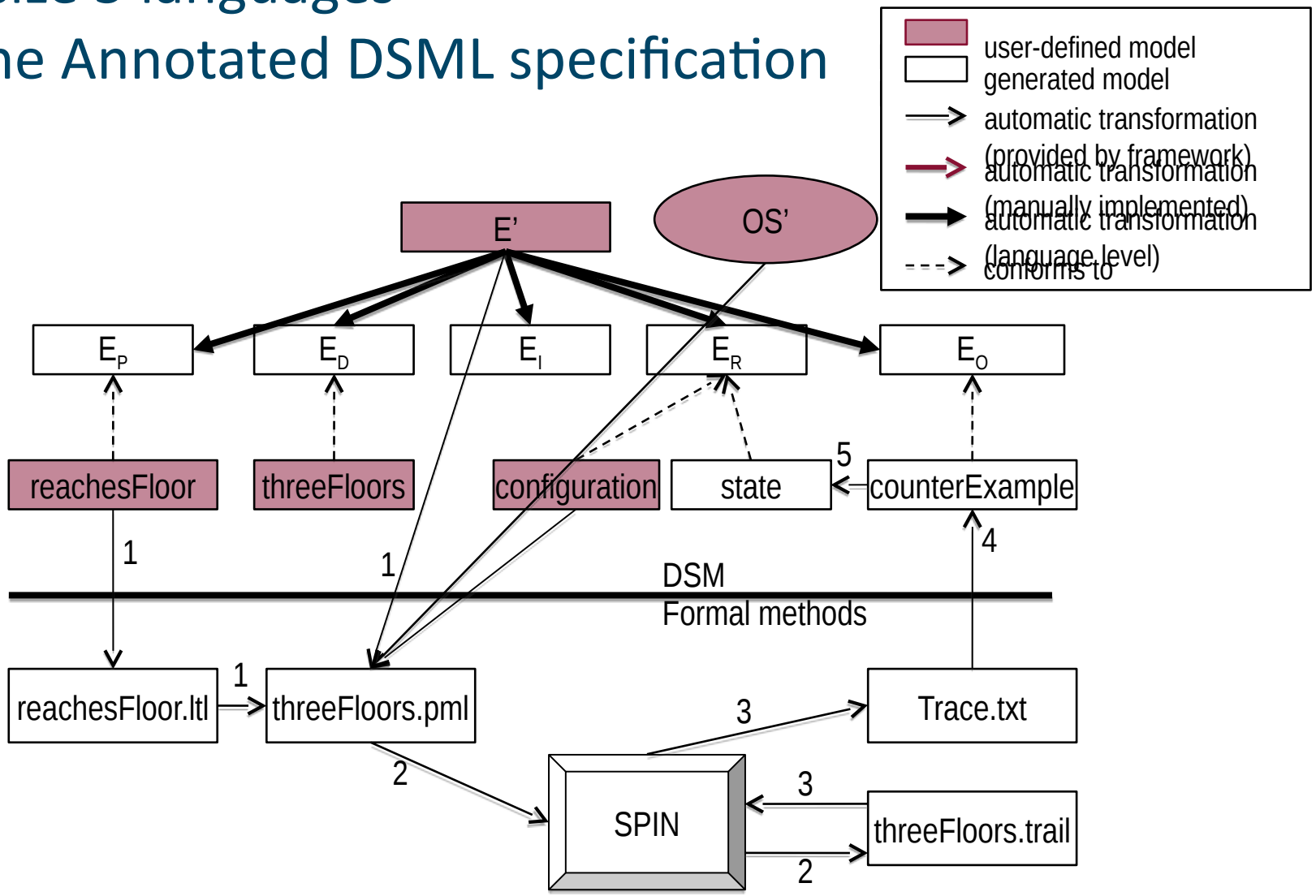
Runtime language



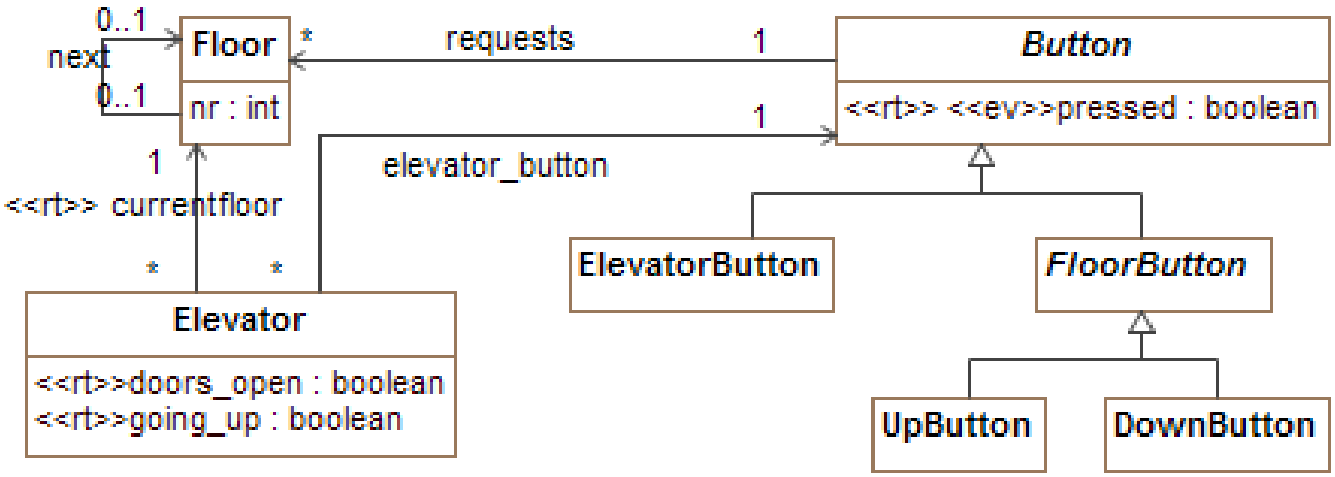
Trace language



Synthesize 5 languages from one Annotated DSML specification

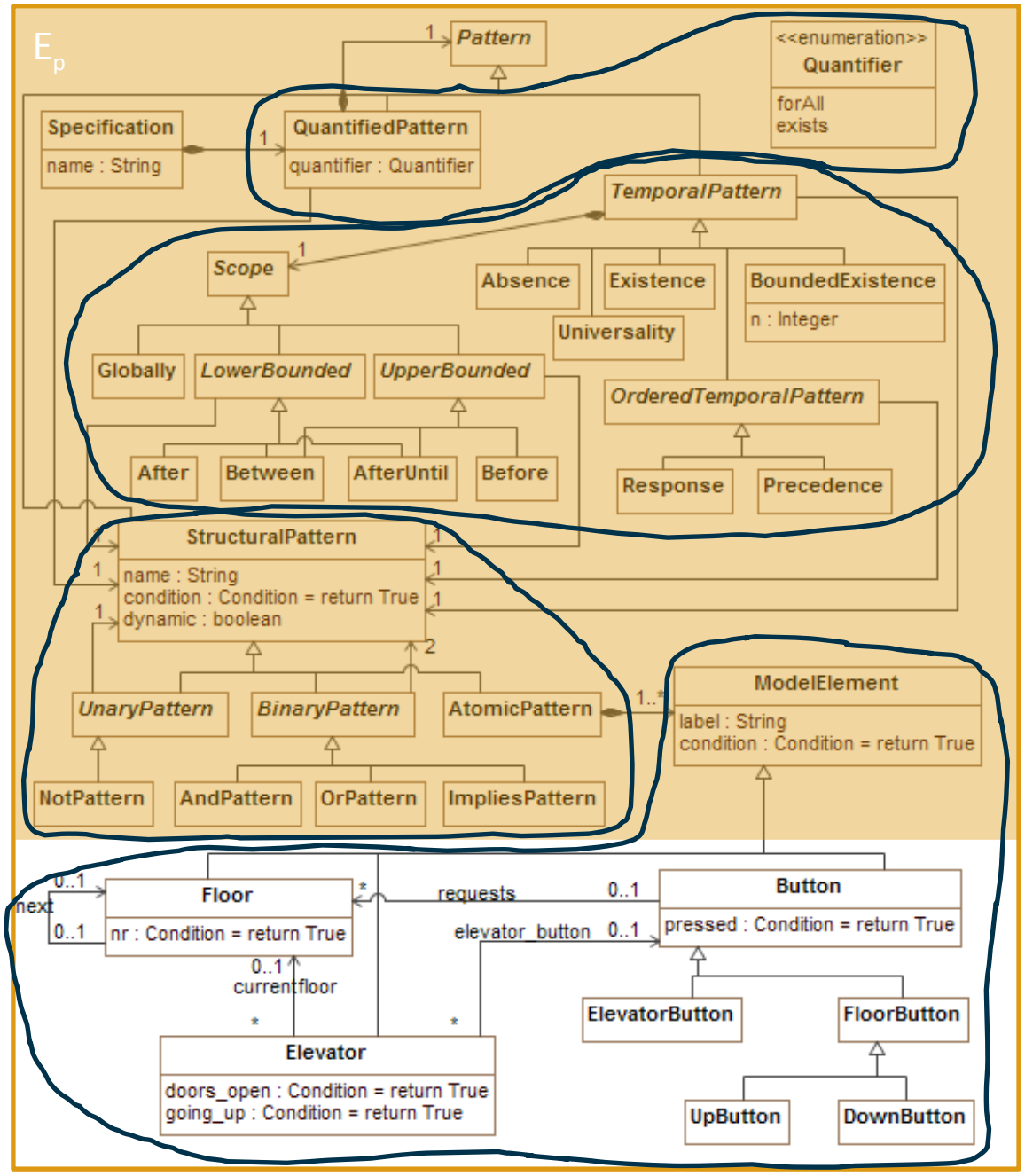


Annotated metamodel



Annotation	Design	Runtime	Input	Output	Property
	x	x		x	x
<<rt>>		x		x	x
<<ev>>			x		
<<tr>>	x	x	x	x	x

E_p



Quantification

Matthew B. Dwyer, George S. Avrunin, James C. Corbett. Patterns in Property Specifications for Finite-State Verification. ICSE 1999: 411-420

Temporal Patterns

Structural Patterns

DSL-specific Elements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language
engineering
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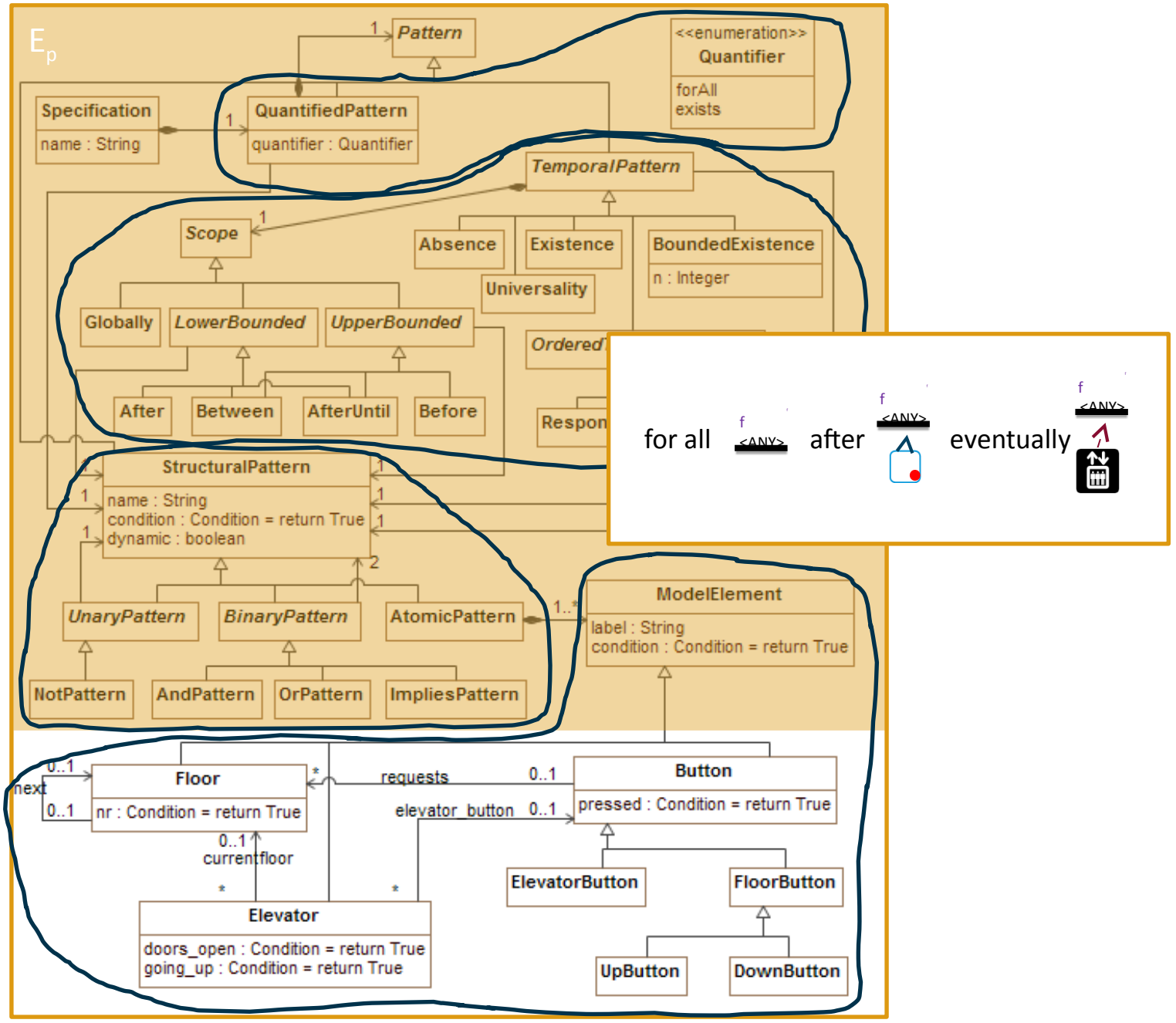
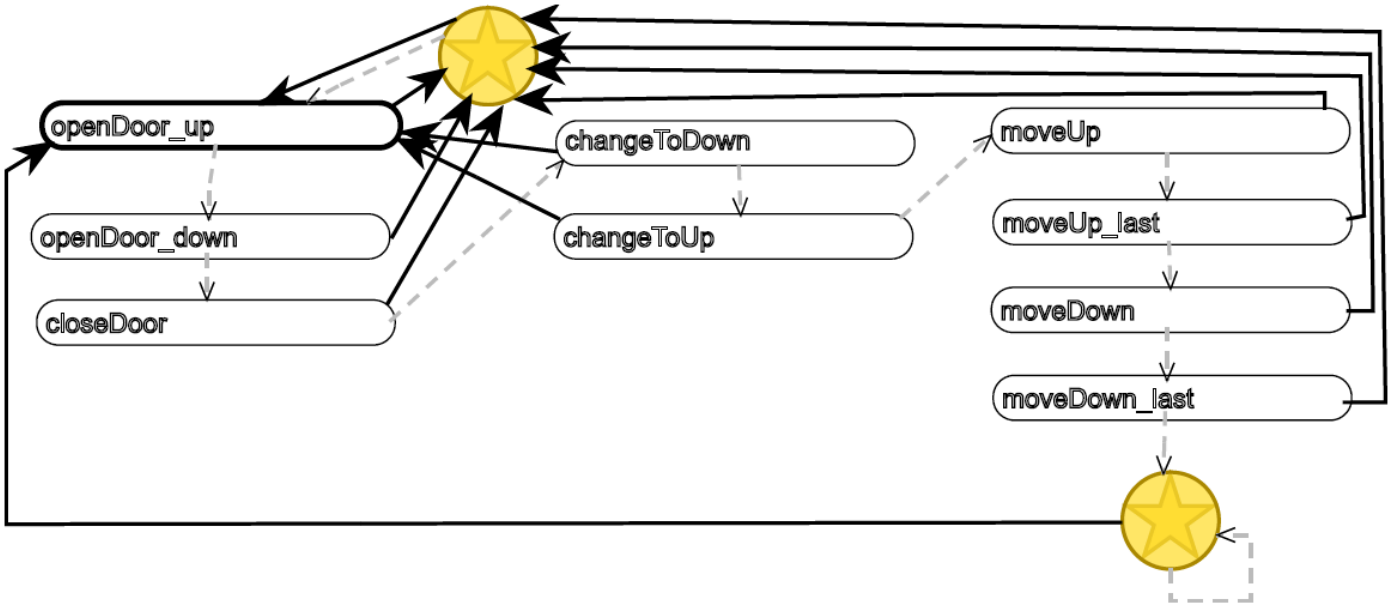
E_p

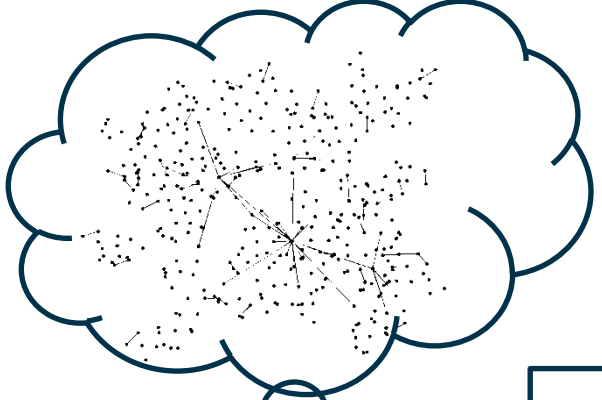

Ep
Pattern
1
<<enumeration>>
Quantifier
forAll
exists
Specification
name : String
1
QuantifiedPattern
quantifier : Quantifier
TemporalPattern
Scope
1
Absence
Existence
BoundedExistence
n : Integer
Universality
Globally
LowerBounded
UpperBounded
Ordered
After
Between
AfterUntil
Before
Respon
StructuralPattern
name : String
condition : Condition = return True
dynamic : boolean
1
2
UnaryPattern
BinaryPattern
AtomicPattern
NotPattern
AndPattern
OrPattern
ImpliesPattern
1..*
ModelElement
label : String
condition : Condition = return True
for all
f
<ANY>
after
f
<ANY>
eventually
f
<ANY>
0..1
next
0..1
Floor
nr : Condition = return True
*
requests
0..1
Button
pressed : Condition = return True
elevator_button
0..1
0..1
currentfloor
*
*
Elevator
doors_open : Condition = return True
going_up : Condition = return True
ElevatorButton
FloorButton
UpButton
DownButton

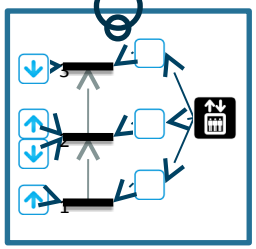
Annotated Operational Semantics

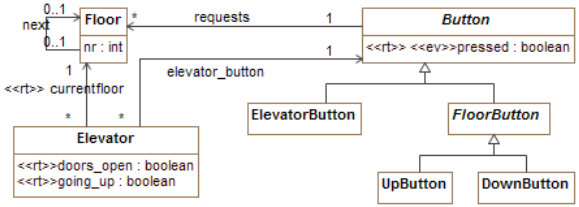


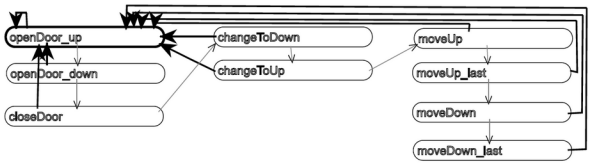
Specify:

- **Input step**: when can an input event occur?
- **Output step**: what does a trace look like?










```
        else:
            return str(val)

    def create_typedef(self, clazz):
        self.writeln("typedef %s {" % clazz)
        self.inc()
        # get all subclasses
        subclasses = [clazz] + self.mm.subclasses[clazz]
        #print [getAttr(self.NAME, sc) for sc in subclasses]
        # add __subtype attribute
        self.writeln("%s %s;" % ("short", "__subtype"))
        # get all attributes, in/outlinks (but not yet their maximum cardinaliti
        # attributes
        for attr in [item for sublist in [self.mm.attributes[sc] for sc in subcl
            type = self.get_type(attr[self.mm.ATTRTYPE])
            name = attr[self.mm.ATTRNAME]
            cardinalities_placeholder = ""#"$%s.%s$" % (getAttr(self.NAME, clazz
            self.writeln("%s %s%s;" % (type, name, cardinalities_placeholder))
        # associations
        for link in [item for sublist in [self.mm.associations[sc] for sc in sub
            dir = "out" if link["dir"] == self.mm.OUT else "in"
            name = "%s_%s" % (link["name"], dir)
            cardinalities_placeholder = "$%s.%s$" % (clazz, name)
            target_class = link["type"]
            self.writeln("short %s%s; // %s %s" % (name, cardinalities_placehold
        self.dec()
        self.writeln("}")
        self.writeln()

    # compiles metamodel: creates typedefs that kind of serve as metamodel (leav
    def compile_metamodel(self):
        self.set_stream(self.metamodel)
        self.metamodel.clear()
        self.mm = MMABS()
        print self.mm
        self.writeln("/*******************************")
        self.writeln("METAMODEL")
        self.writeln("*******************************/")
        self.writeln()
        self.writeln()
```

Generic code generator

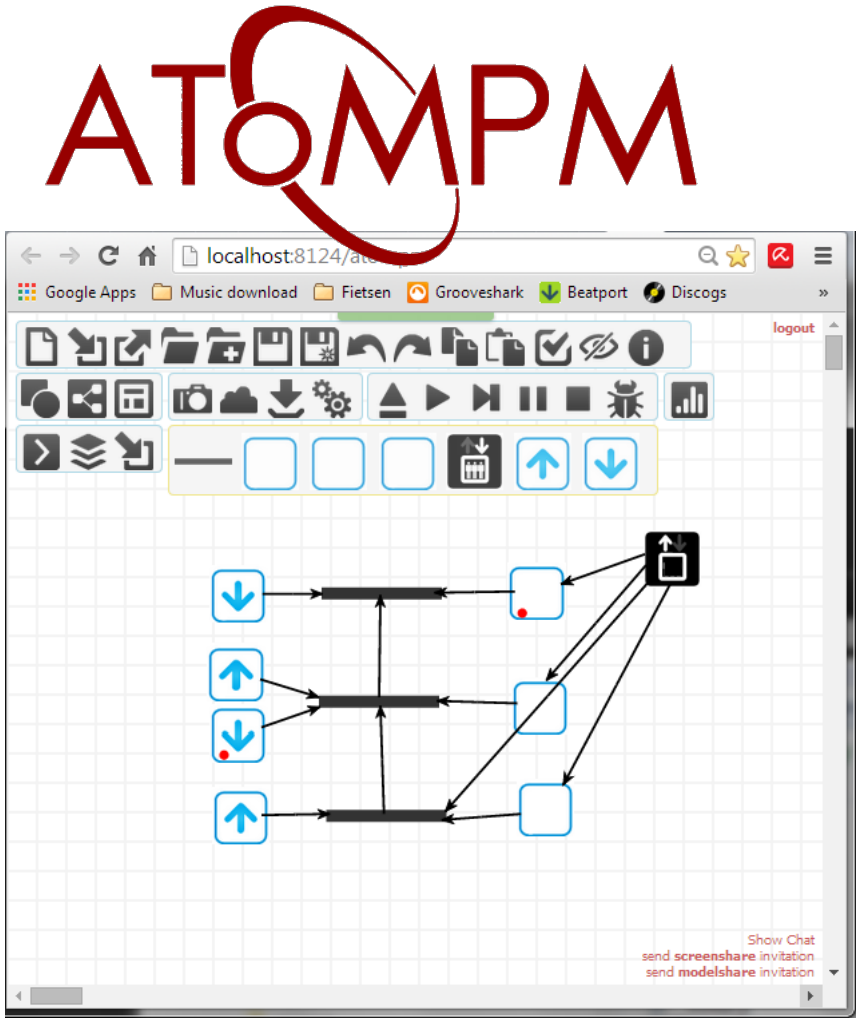
Optimizations!

Can use valuable system- and property-specific information

```
    MOVEUP_schedule:
    if
      :: (success == 1) -> // when successful
         rule = moveup_;
         nextrule = environmentstep1_;
         goto OUTPUT;
      :: else -> // when not applicable
         nextrule = moveup_last_;
         goto NEXTSTEP;
    fi;
    CLOSEDOOR_schedule:
    if
      :: (success == 1) -> // when successful
         rule = closedoor_;
         nextrule = environmentstep1_;
         goto OUTPUT;
      :: else -> // when not applicable
         nextrule = moveup_;
         goto NEXTSTEP;
    fi;
    ENVIRONMENTSTEP2_schedule:
    if
      :: (success == 1) -> // when successful
         rule = environmentstep2_;
         nextrule = opendoor_up_;
         goto OUTPUT;
      :: else -> // when not applicable
         nextrule = environmentstep2_;
         goto NEXTSTEP;
    fi;
    ENVIRONMENTSTEP1_schedule:
    if
      :: (success == 1) -> // when successful
         rule = environmentstep1_;
         nextrule = opendoor_up_;
         goto OUTPUT;
      :: else -> // when not applicable
         nextrule = opendoor_up_;
         goto NEXTSTEP;
    fi;
MOVEUP:
    success = 0;
    // looking for node elevator5 type Elevator, Elevator from None by
    // looking for node floor1 type Floor, Floor from elevator5 by foll
    // looking for node floor2 type Floor, Floor from floor1 by followi
    // looking for node button3 type Button, Button from None by follow
    // looking for node floor0 type Floor, Floor from button3 by follow
    elevator5 = 0; // this is the only Elevator so index must be 0
    button3_max = 7;
    button3_index_map[0] = 0;
    button3_index_map[1] = 1;
    button3_index_map[2] = 2;
    button3_index_map[3] = 3;
    button3_index_map[4] = 4;
    button3_index_map[5] = 5;
    button3_index_map[6] = 6;
    do
    :: ((elevator5 >= 0) && (s.elevator_[elevator5].__subtype == Elevat
(r.elevator_[elevator5].going_up == 1) && r.elevator_[elevator5].curren
(s.floor_[r.elevator_[elevator5].currentfloor_out].__subtype == FloorTy
(s.floor_[r.elevator_[elevator5].currentfloor_out].next_out != r.elevat
(s.floor_[s.floor_[r.elevator_[elevator5].currentfloor_out].next_out].__
       if
       :: ((button3_max > 0) && (button3_index_map[0] >= 0) && (s.button
s.button_[button3_index_map[0]].__subtype == DownButtonType || s.button
(r.button_[button3_index_map[0]].pressed == 1) && (elevator5 >= 0) && (
(r.elevator_[elevator5].doors_open == 0) && (r.elevator_[elevator5].goi
(r.elevator_[elevator5].currentfloor_out >= 0) && (s.floor_[r.elevator_
(s.floor_[r.elevator_[elevator5].currentfloor_out].next_out >= 0) && (s
r.elevator_[elevator5].currentfloor_out) && (s.floor_[s.floor_[r.elevat
(s.button_[button3_index_map[0]].requests_out >= 0) && (s.button_[butto
s.floor_[r.elevator_[elevator5].currentfloor_out].next_out) && (s.butto
r.elevator_[elevator5].currentfloor_out) && (s.floor_[s.button_[button3
(s.floor_[s.button_[button3_index_map[0]].requests_out].nr > s.floor_[r
       :: ((button3_max > 1) && (button3_index_map[1] >= 0) && (s.button
```

DSM implementation

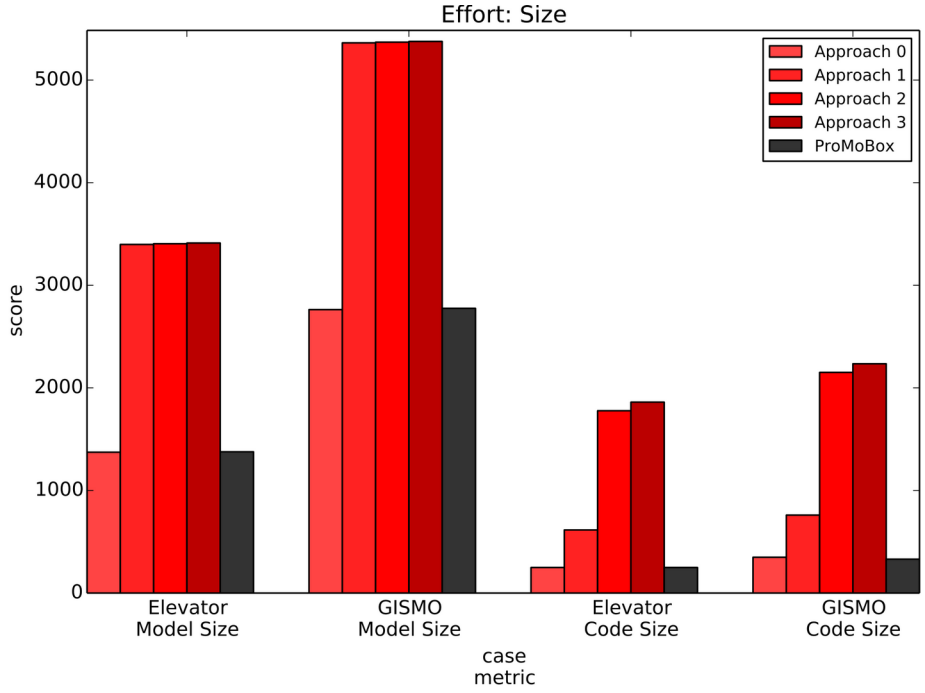
- "A Tool for Multi-Paradigm Modeling"
- Successor to AToM^3
- Cloud- and browser based
- Model everything!
  - At the most appropriate level(s) of abstraction
  - Using the most appropriate formalism(s)

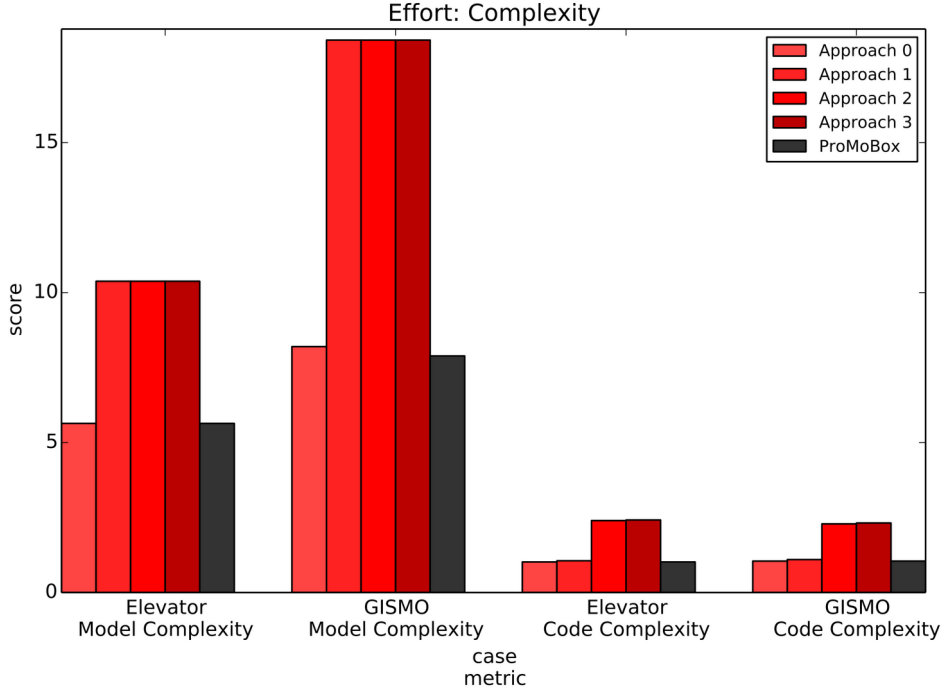


Evaluation (modelling effort)

In comparison with existing approaches:

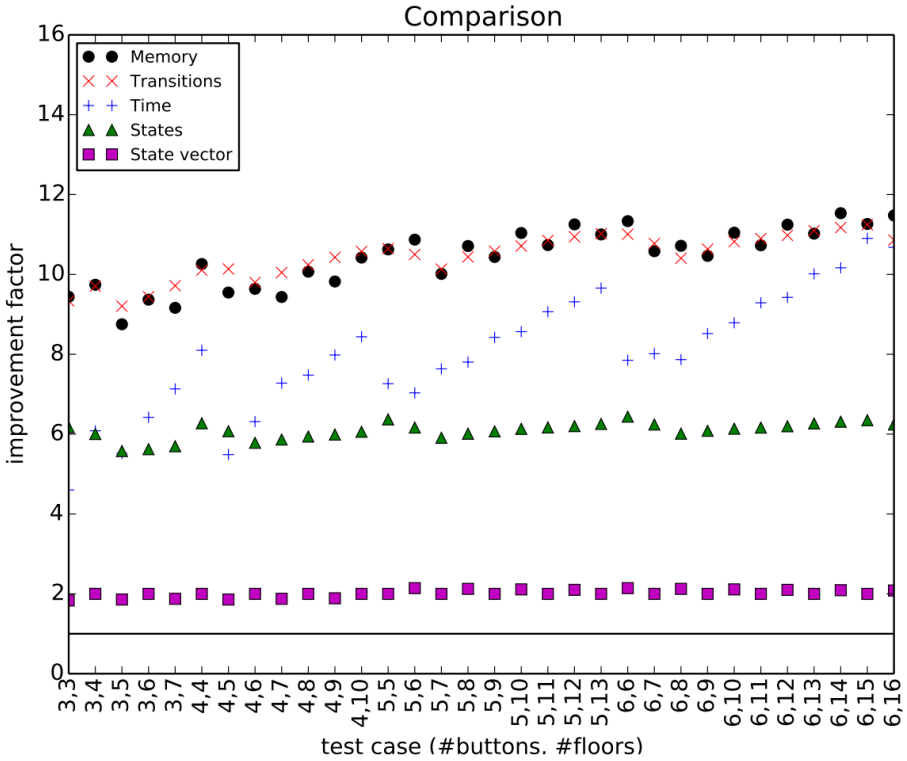
- ***Approach 1***: no DSML for properties is available. Instead, properties are directly modelled in logic, but there is a mapping to a formal language
- ***Approach 2***: a DSML for properties is created including a mapping to a verification backbone, but no counterexample parsing is supported
- ***Approach 3***: a DSML for properties is created including a mapping to and counterexample parsing from a verification backbone. This is in fact the only approach that offers the same functionality as *ProMoBox*





Evaluation (model checking performance)

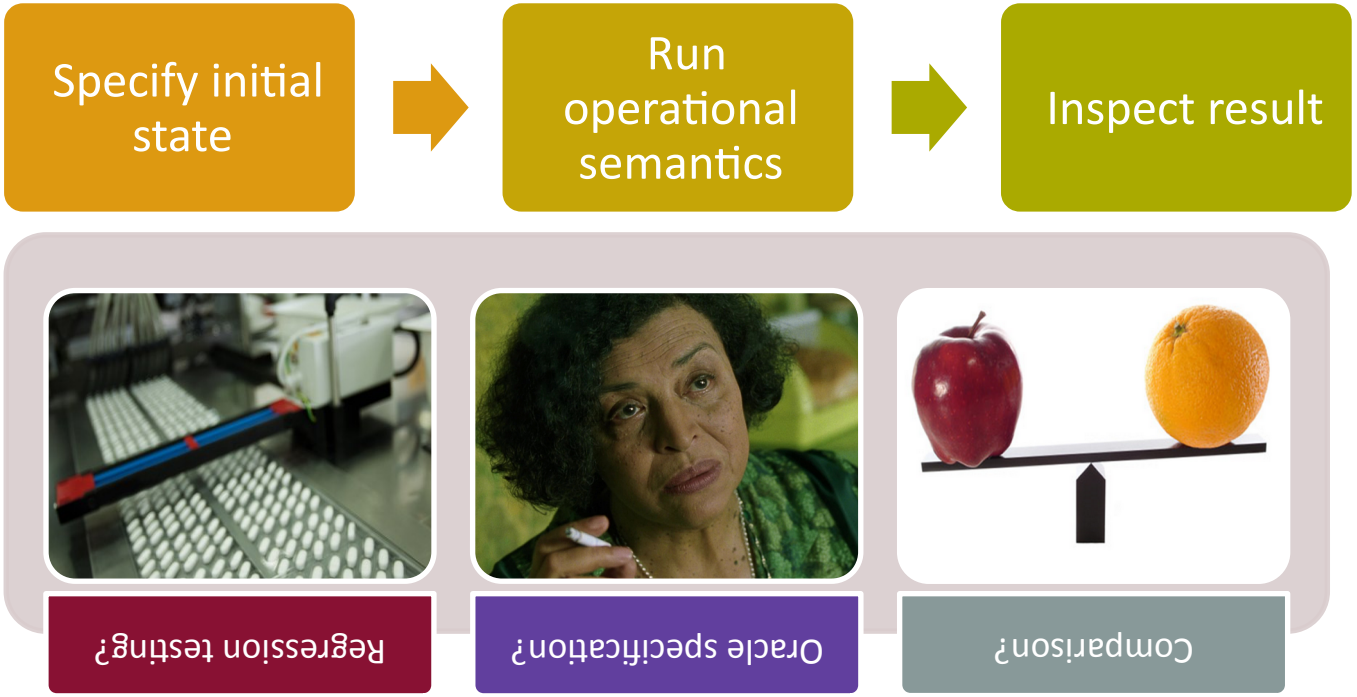
Elevator case study, in comparison with an adapted elevator implementation from the literature [merz08]



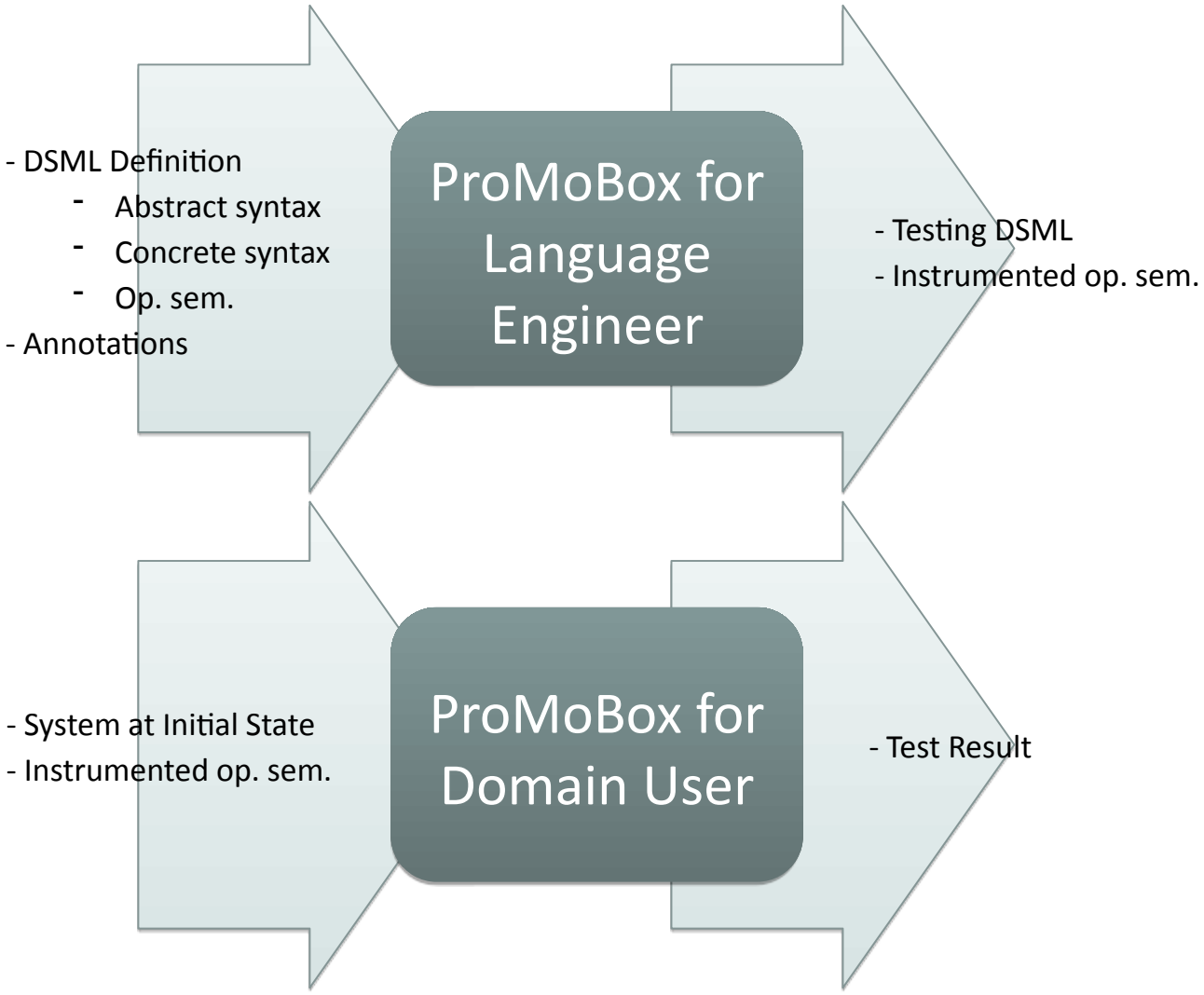
[merz08] Stephan Merz. An introduction to model checking. In Stephan Merz and Nicolas Navet, editors, Modeling and Verification of Real-Time Systems - Formalisms and Software Tools, pages 81–116. ISTE Publishing, 2008.


State Space Explosion
Problem

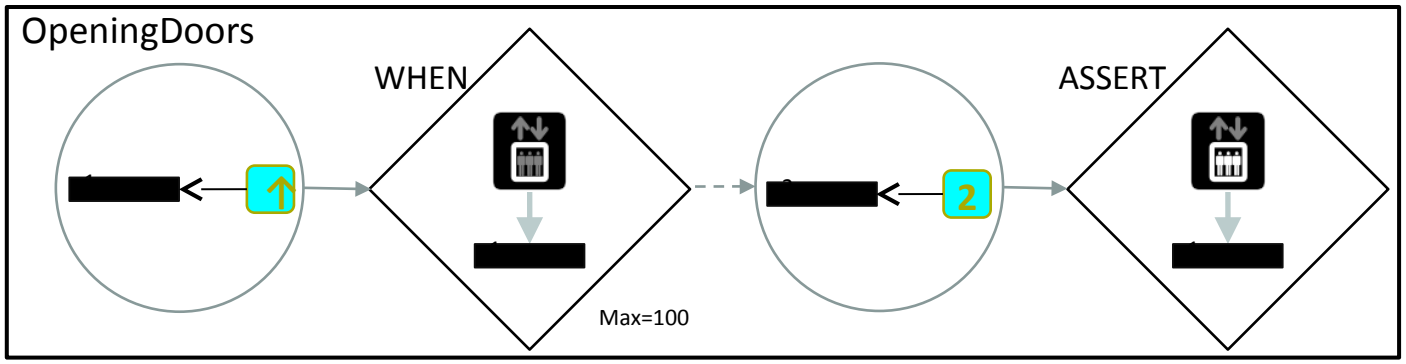
Testing in DSM?



Test Support for DSMLs



Test case in Testing models in a DSML (caveat: not testing the DSML)



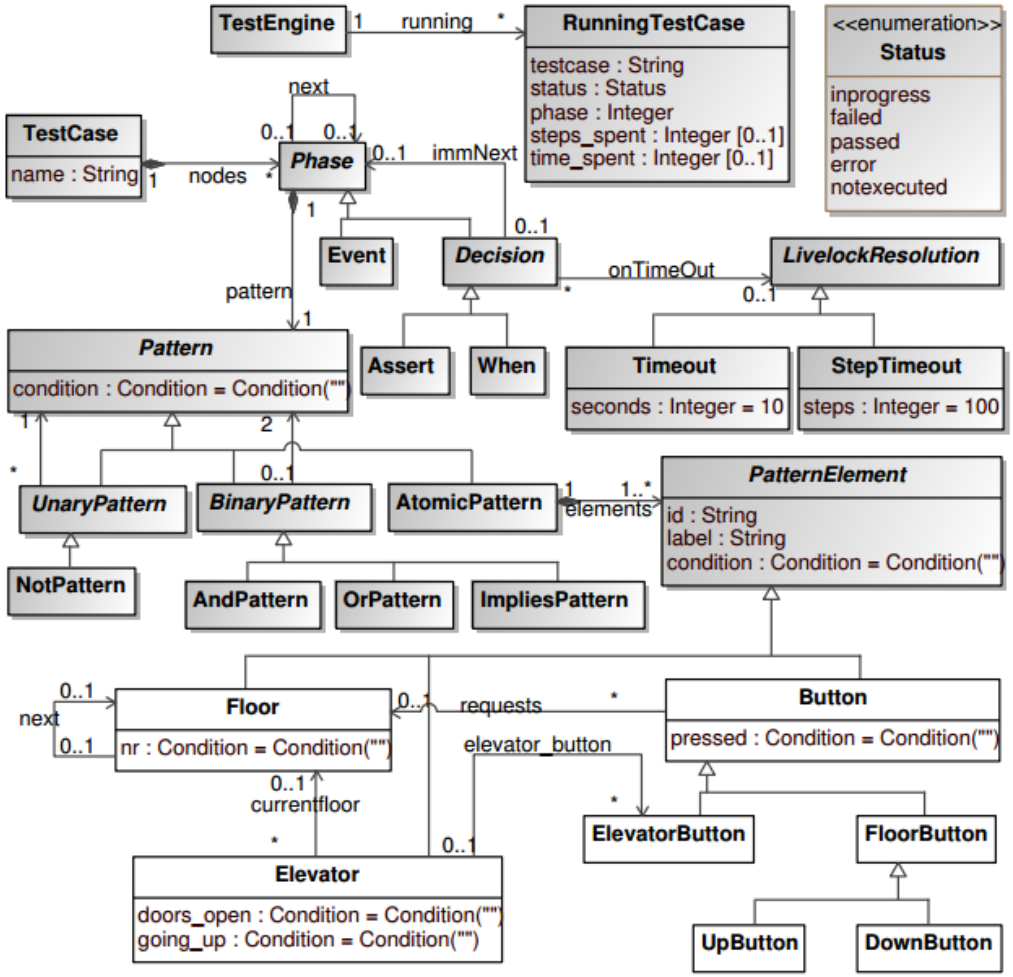
Inspired by unit testing

Domain-specific syntax

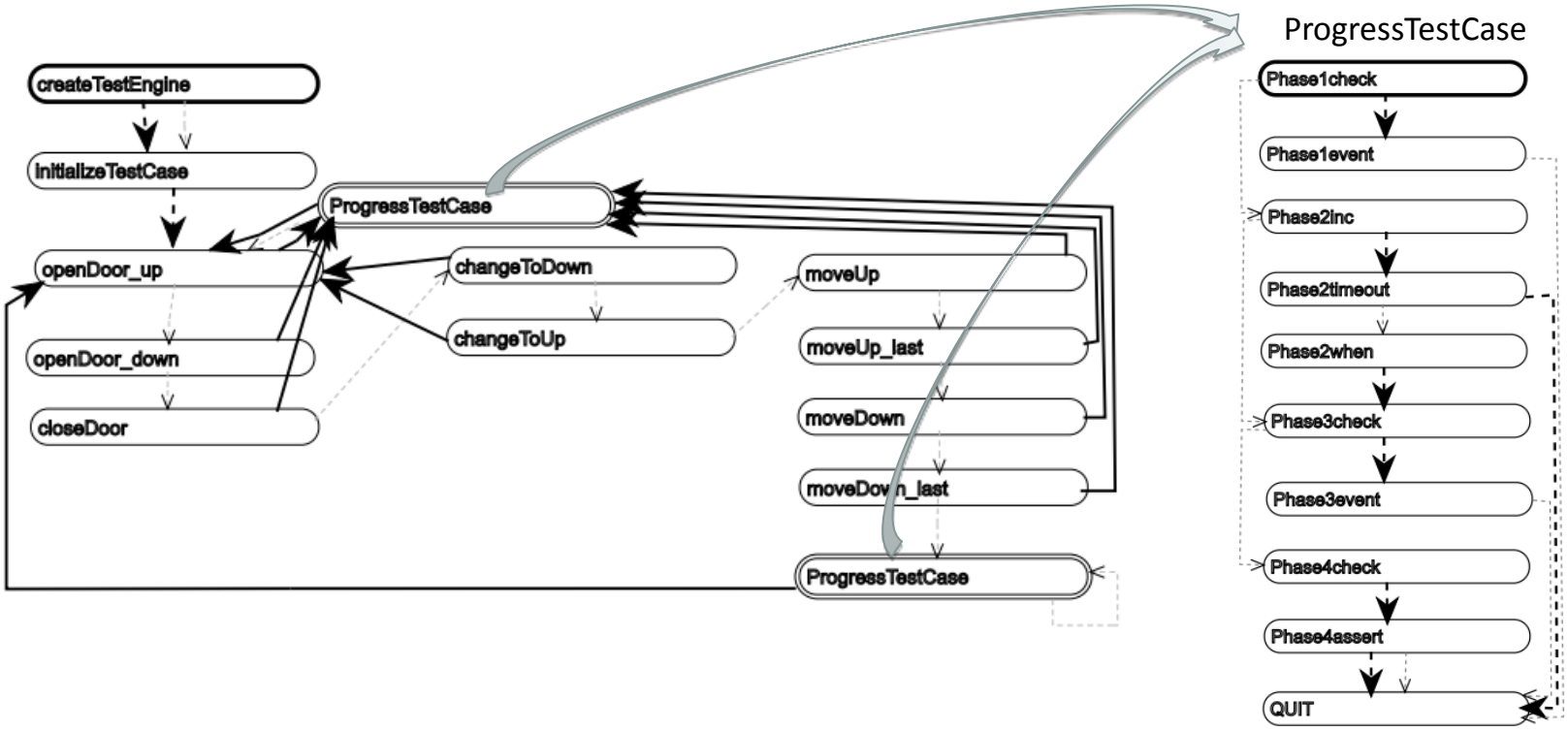
Includes oracle

Can also be used for runtime monitoring (~ trace-matches)

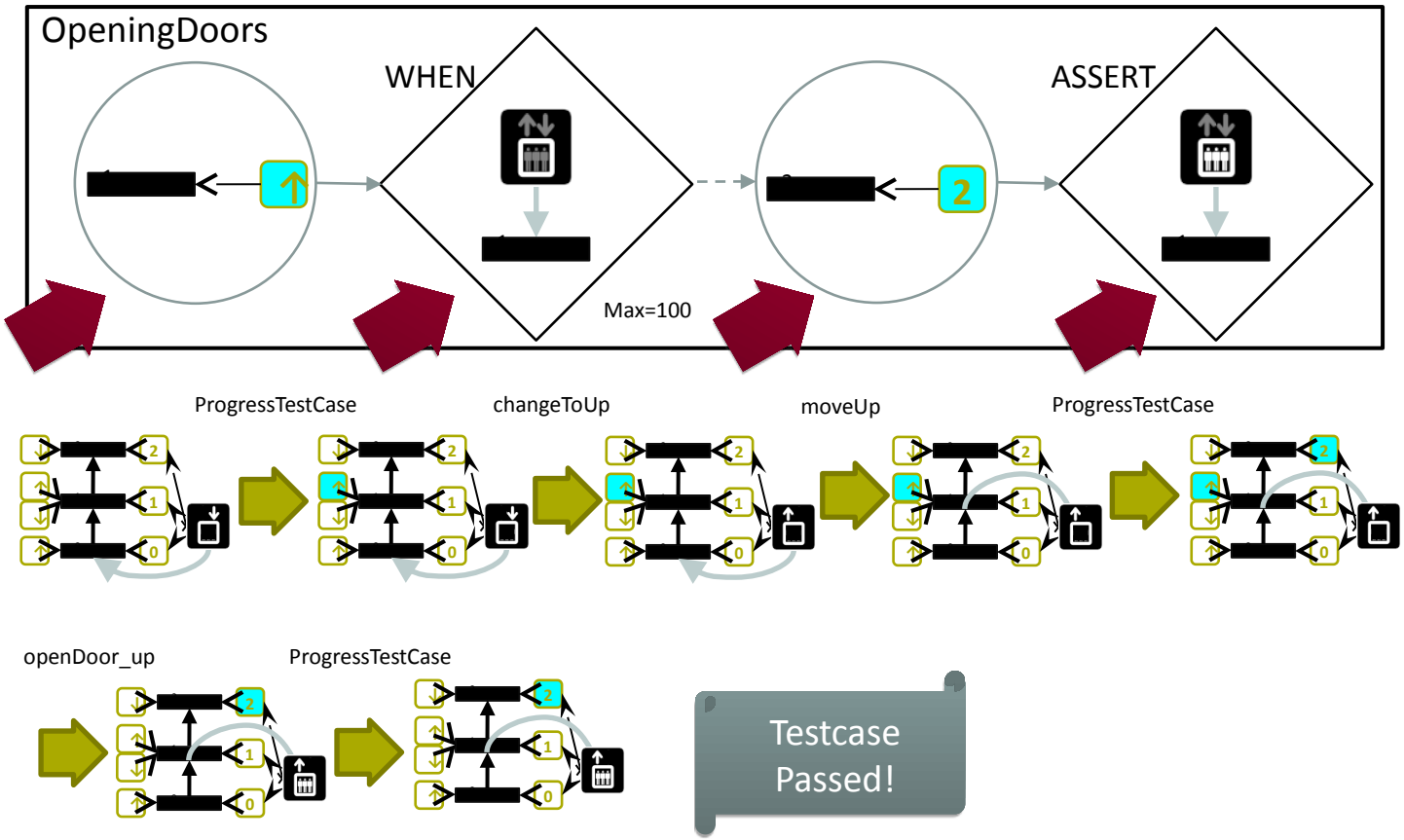
Testing DSML (generated)



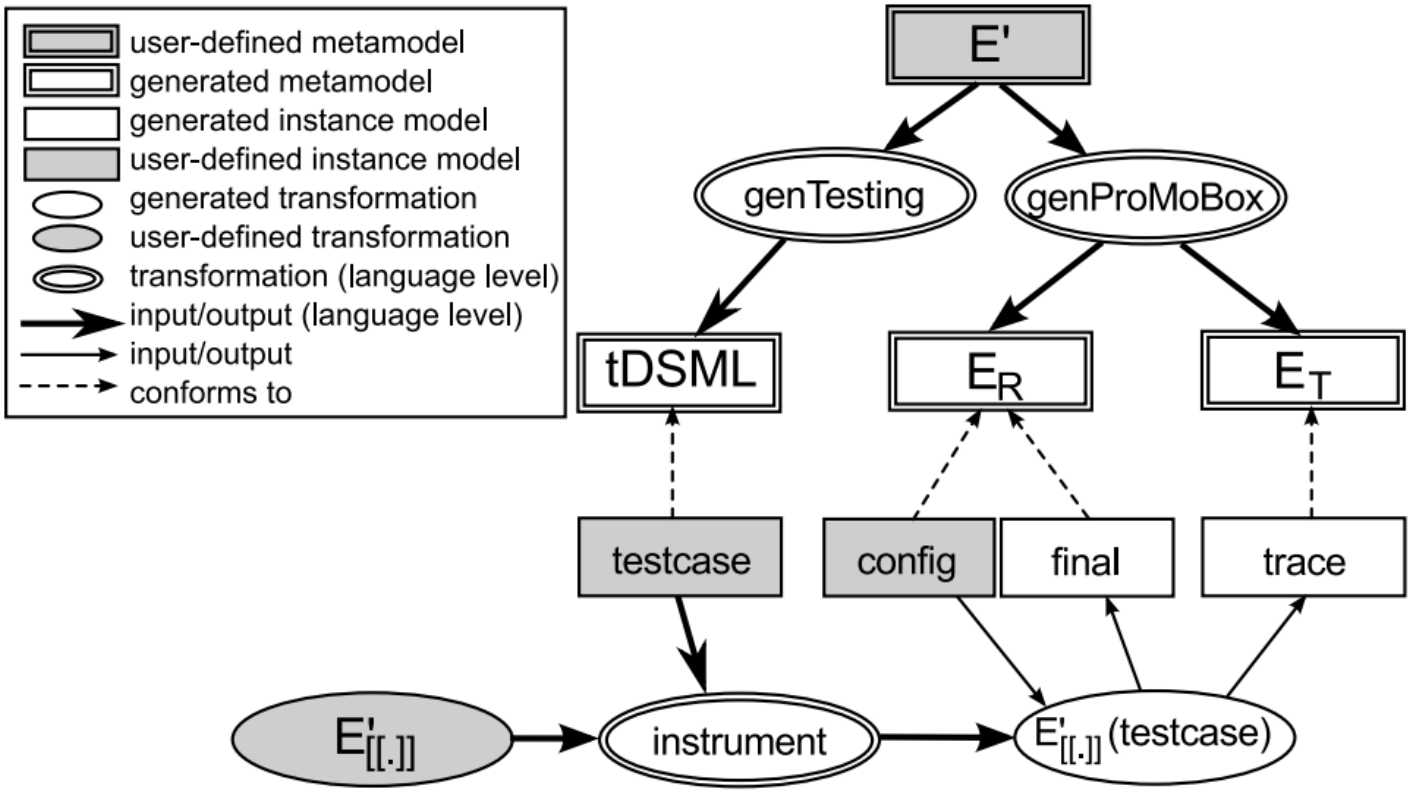
Instrumented Operational Semantics (generated)



Test Case Execution



Architecture of the Approach



Conclusion

- Definition of **family** of five related domain-specific sublanguages
- **Generative** approach
  - Language generation
  - Generic compiler
- **Insight** in and **support** for various tasks, e.g.,
  - Simulation
  - Model checking
  - Test case generation
- Future Work: Test Case Generation(with good coverage) from properties
- Future Work: Application to Design Space Exploration
  - Generate a language for specifying DSE optimization rules
  - Generate tool support

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