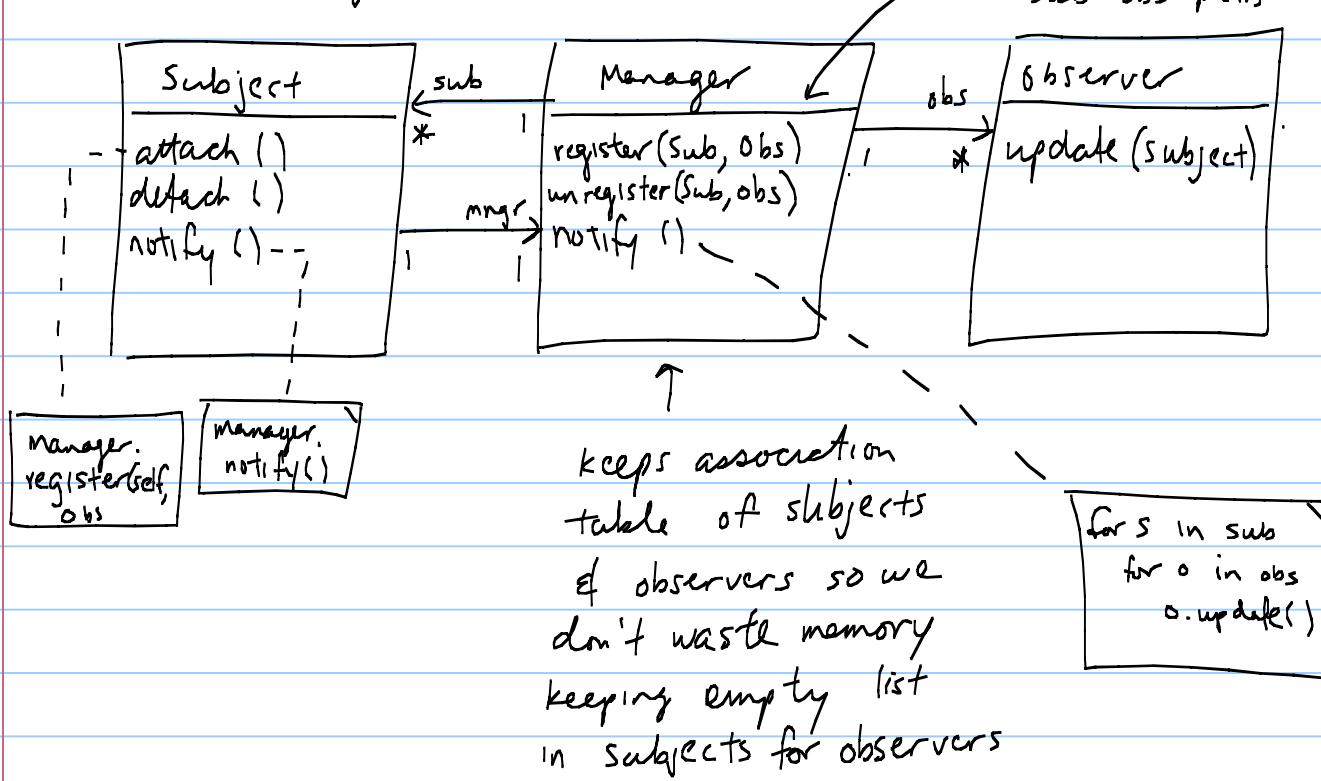
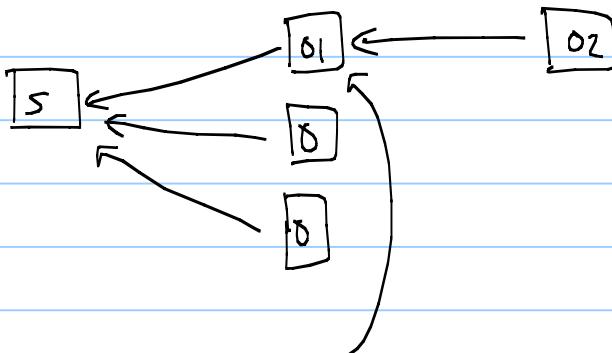


## 8) Encapsulating Update Semantics

attribute list for  
sub-obs pairs

## a) Both a subject &amp; an observer



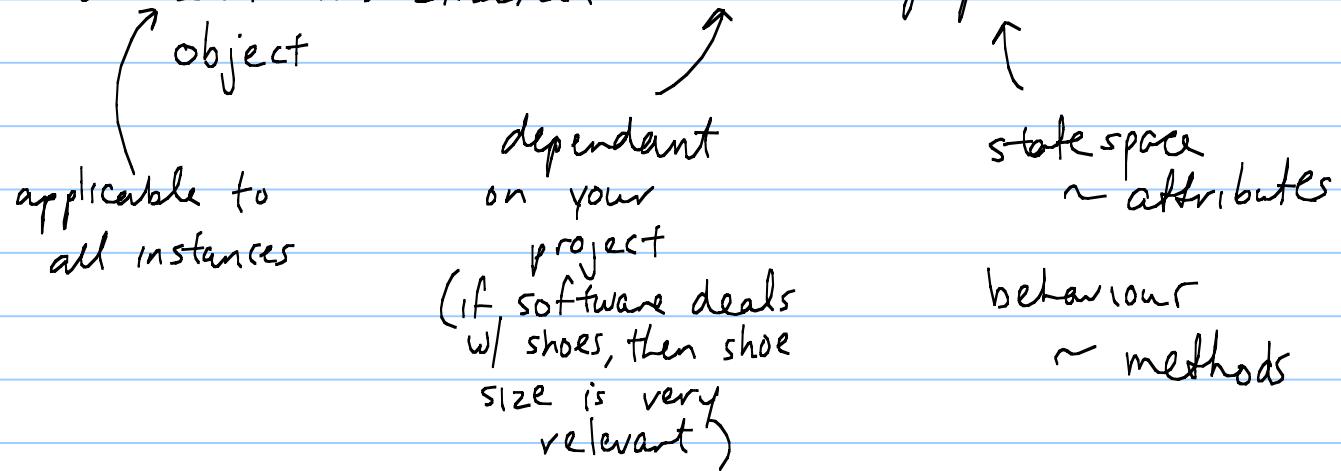
this is a subject &amp; observer

Fine, when O1 does getstate, it will do setstate, so there will be a notify to O2 so, getstate & setstate again.

What if s observed O2? then there would be a cycle of notifies & get/set states. Make a special Manager class to handle this.

## State Space & Behavior ("Good Design")

Class: uniform abstraction of relevant properties of an



State Space of Class C is the set of all permitted states of any object of class C

i.e.: if we have a class Square w/ attributes x, y and size.

Square
$x \in \{0, 1, 2, 3, \dots, 7\}$
$y \in \{0, 1, 2, \dots, 5\}$
$\text{size} \in [1, 3]$

So, to depict a state, we must give a tuple  $(x, y, \text{size})$ .  
 $(2, 2, 2, 2)$  is a valid state  
 $(2, 7, 1)$  is not since y is out of range. A method may also violate a state space. So, BEFORE & AFTER a method, state space must be valid.

$$\begin{aligned}\text{So, StateSpace(Square)} &= \{(x, y, \text{size}) \mid x \in \{0, 1, \dots, 7\}, y \in \{0, 1, \dots, 5\} \\ &\quad \text{size} \in [1, 3]\} \\ &= \{0, 1, \dots, 7\} \times \{0, 1, \dots, 5\} \times [1, 3]\end{aligned}$$

since  $A \times B$  is all combinations.

We can also draw a state space on a graph.