

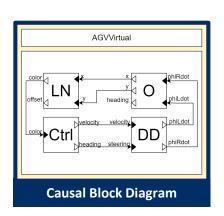
A Multi-Paradigm Modelling Foundation for Twinning Within the Context of Systems Engineering

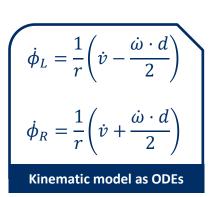


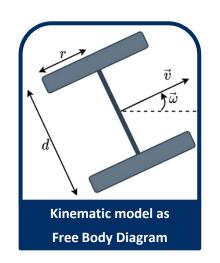
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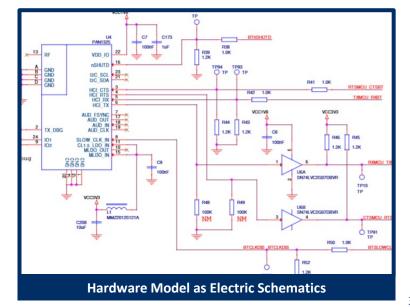








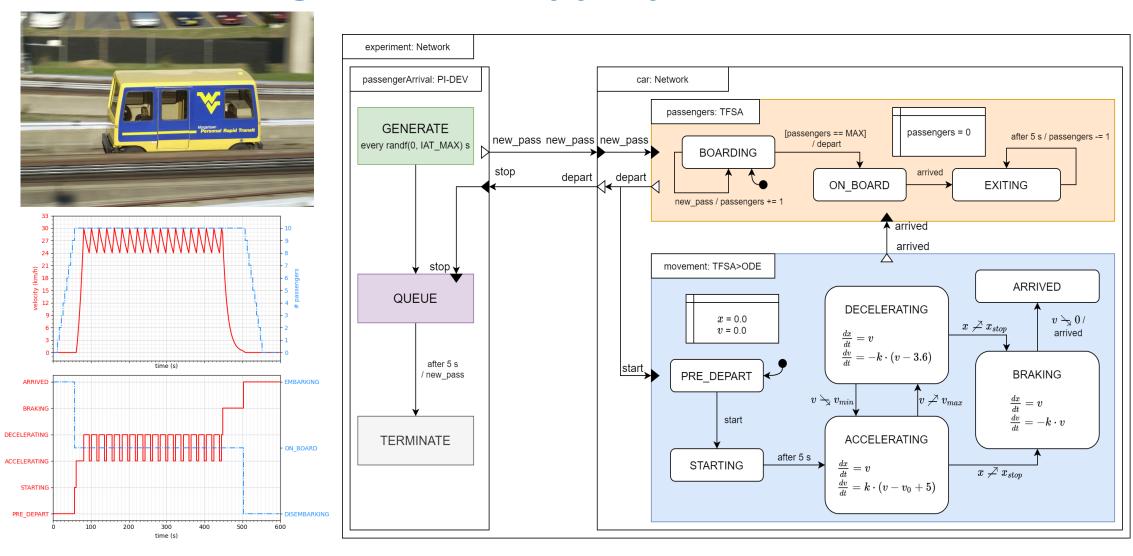






A Multi-Paradigm Modelling Foundation for Twinning Within the Context of Systems Engineering

MPM: Using the most appropriate...







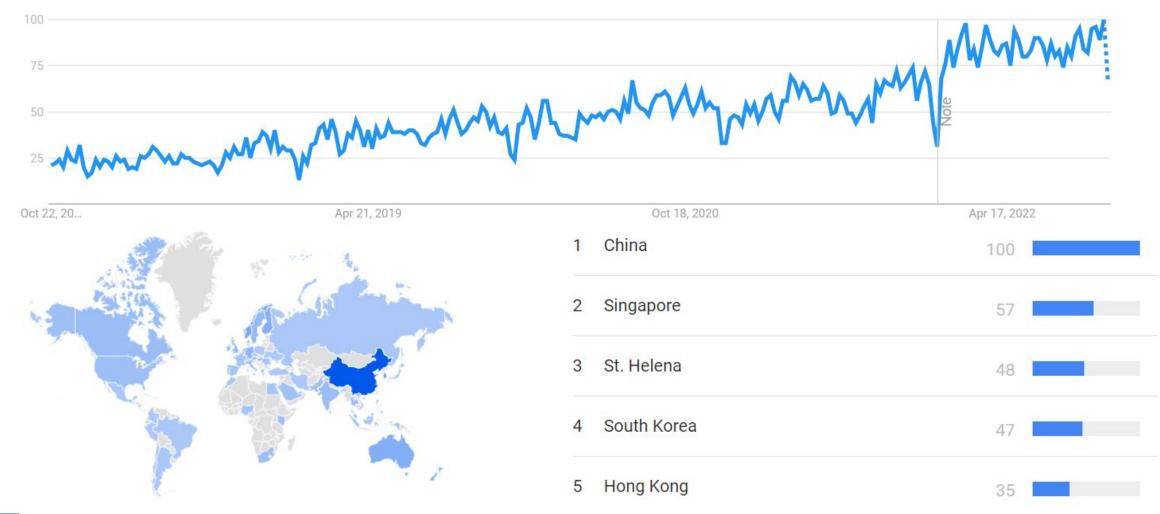


A Multi-Paradigm Modelling Foundation for Twinning

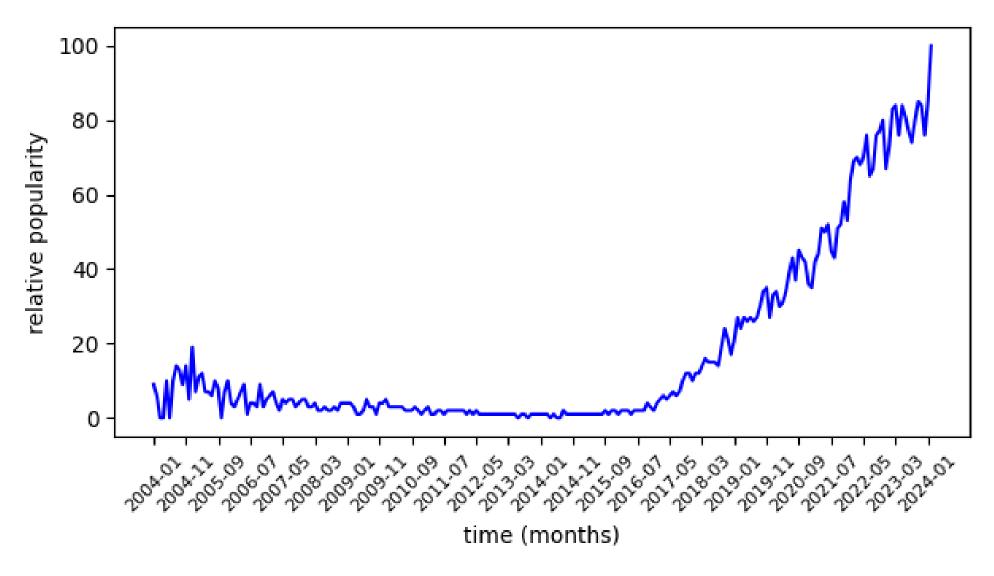
ontext of Systems Engineering

Digital Twin

Google Trends

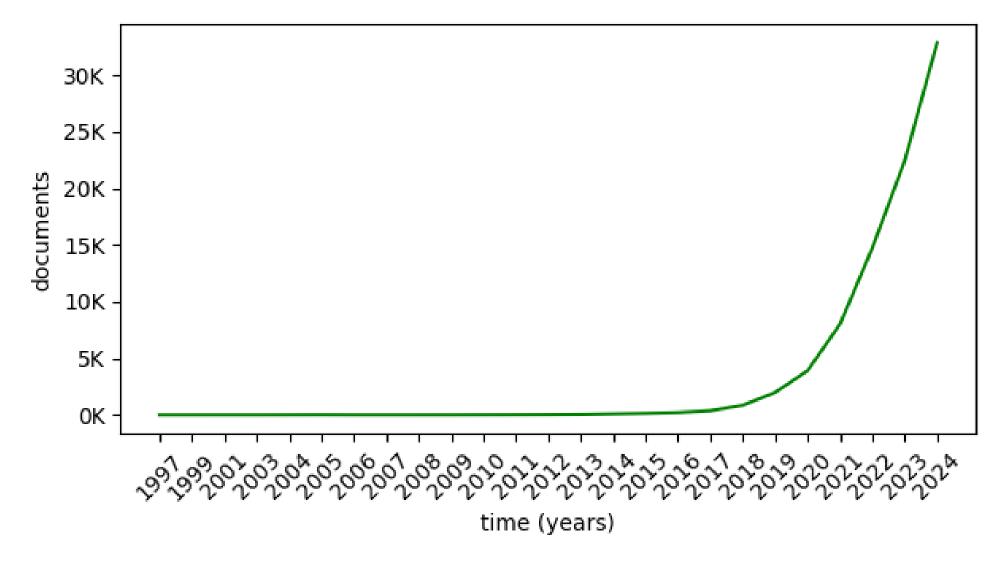


Google Trends





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Digital Twin?

Digital Twins consist of three components, a physical product, a virtual representation of that product, and the bi-directional data connections that feed data from the physical to the virtual representation, and information and processes from the virtual representation to the physical. [1]

A **Digital Twin** is an integrated multi-physics, multi-scale, probabilistic simulation of a vehicle or system that uses the best available physical models, sensor updates, fleet history, etc., to mirror the life of its flying twin. The digital twin is ultra-realistic and may consider one or more important and interdependent vehicle systems. **[5]**

A **Digital Twin** is a coupled model of the real machine that operates in the cloud platform and simulates the health condition with an integrated knowledge from both data driven analytical algorithms as well as other available physical knowledge. [7]

Digital Twins is a unified system model that can coordinate architecture, mechanical, electrical, software, verification, and other discipline-specific models across the system lifecycle, federating models in multiple vendor tools and configuration-controlled. [8]

Digital Twins are software systems comprising data, models and services to interact with a CPPS for a specific purpose. [9]



... and many more!

The **Digital Twin** is a set of virtual information constructs that fully describes a potential or actual physical manufactured product from the micro atomic level to the macro geometrical level. At its optimum, any information that could be obtained from inspecting a physical manufactured product can be obtained from its Digital Twin. [2]

Digital Twins are a virtual representation of the physical objects, processes and real-time data involved throughout a product lifecycle. [3]

A **Digital Twin** is an ultra-realistic virtual counterpart of a real-world object. [4]

A **Digital Twin** is an ultra-realistic, cradle-to-grave computer model of an aircraft structure that is used to assess the aircraft's ability to meet mission requirements. [6]

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Digital Twin Definitions

A collection of definitions of digital twins

As a side result of the largest literature survey on digital twins to date

. M. Dalibor, N. Jansen, B. Rumpe, D. Schmalzing, L. Wachtmeister, M. Wimmer, A. Wortmann: A Cross-Domain Systematic Mapping Study on Software Engineering for Digital Twins. In: Journal of Systems and Software 111361

we have produced a collection of 112 definitions of the term "digital twin" from the publications of our corpus. This collection is reproduced below

Definitions

- . "An always in sync digital model of existing manufacturing cells". B. A. Talkhestani, N. Jazdi, W. Schlögl, M. Wevrich. A concept in synchronization of virtual production system with real factory based on anchorpoint method. In: Procedia CIRP 2018
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Security 2018

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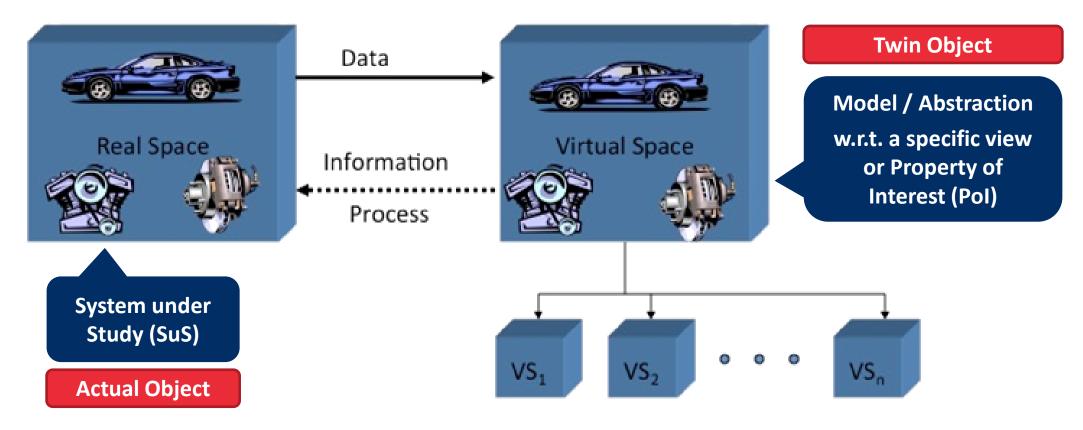
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• 'digital twins are virtual clones of real systems or subsystems.' W. Kuehn. Digital twins for decision https://awortmann.github.io/research/digital-twin-definitions/

Conceptual Ideal for PLM

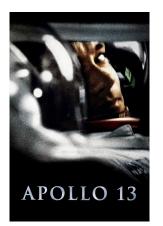


Digital Twin

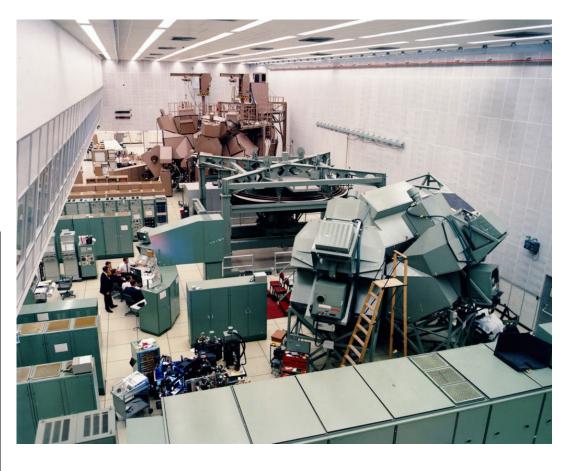
Apollo 13

Actual Object

Twin Object







Mastering the Nordschleife with

PORSCHE

hydrogen

Hydrogen Car

Actual Object

Twin Object



Porsche Engineering tested it in a luxury-segment reference vehicle with a relatively high total weight of 2,650 kg on the Nürburgring Nordschleife - albeit *entirely virtually*: the drive was carried out using what is known as a *digital twin*, i.e. a computer-based representation of the real vehicle.



many definitions/alternatives of "Digital Twin" → use "**Twinning**" to cover all definitions

Sensing ← ... everything in between ... → Simulation









A Multi-Paradigm Modelling Foundation for Twinning Within the Context of Systems Engineering

- RQ1: What are the most common reasons/definitions for (creating)
 Digital Twins (DTs)?
- RQ2: Given the large number of existing DTs in the literature, can we unify?
- RQ3: What is the relationship between specific DT requirements, the system architecture, the used models, and the eventual deployment?
- RQ4: How to quantitatively support deployment choices?
- RQ5: How can we combine multiple DTs into a larger system?



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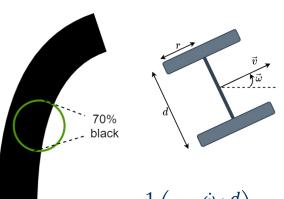


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Proof-of-Concept: Line Following Robot

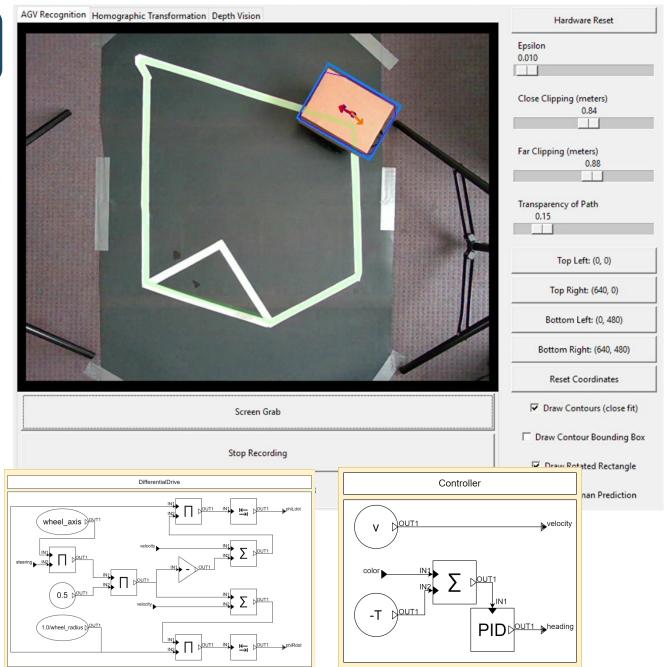


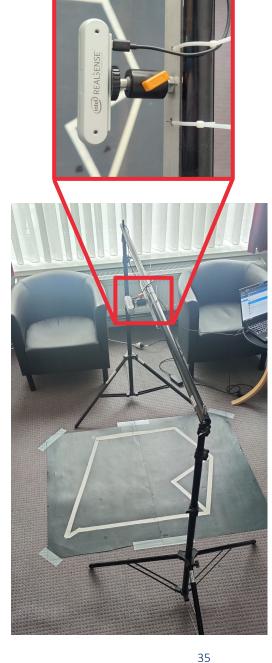


$$\dot{\phi}_L = \frac{1}{r} \left(\dot{v} - \frac{\dot{\omega} \cdot d}{2} \right)$$

$$\dot{\phi}_R = \frac{1}{r} \left(\dot{v} + \frac{\dot{\omega} \cdot d}{2} \right)$$



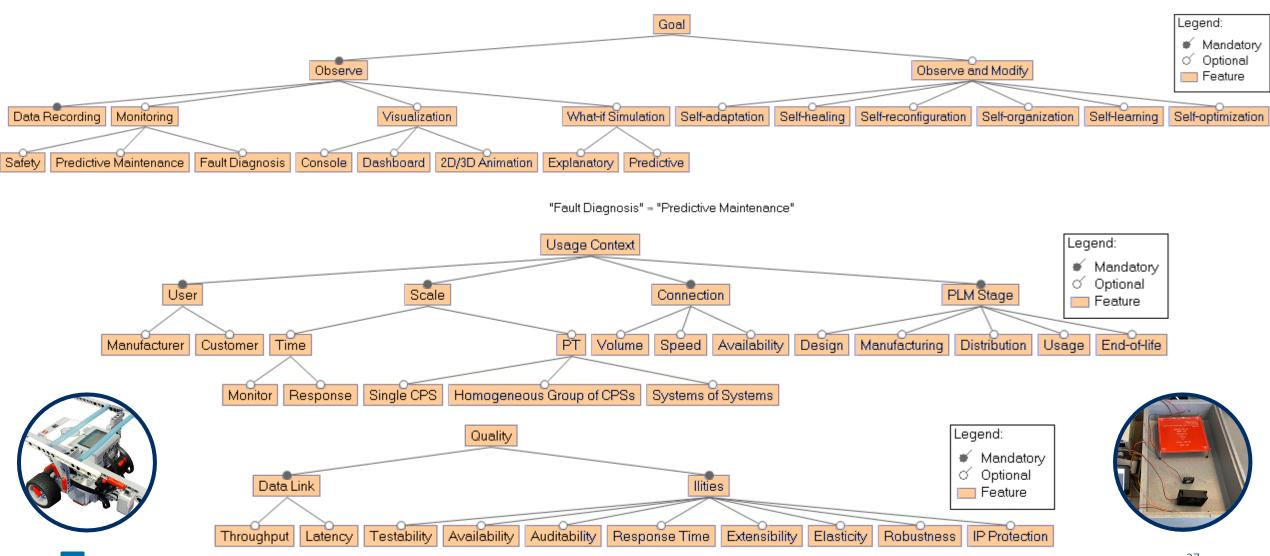








LFR vs Incubator

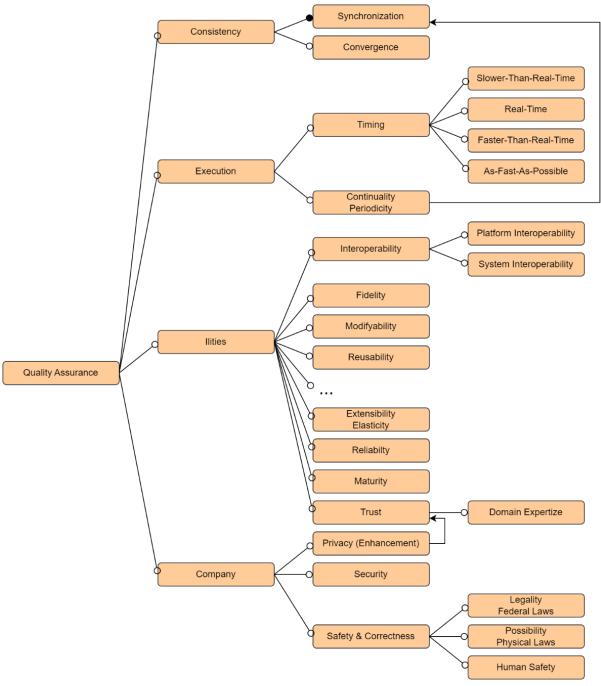


Goals w.r.t. their Properties of Interest (Pols)

Virtual Proptotyping Design Variation Analysis **Design Space Exploration** Memorization Data Allocation Data Recording Knowledge Collection Verification & Validation Consistency Monitoring State Estimation Data Processing Data Analysis **Anomaly Detection** Fault Tolerance **Fault Detection** Operation Fault Diagnosis **Behaviour Prediction Process Prediction** Forecasting What-If Simulation Purpose Control Modification Optimalization Console Static Visualization Dashboard Visualization 2D Animation Live Plots Dynamic Visualization 3D Animation Mixed Reality AR / VR / XR Predictive Maintenance Fatigue Testing Maintenance Damage Evaluation Lifecycle Management

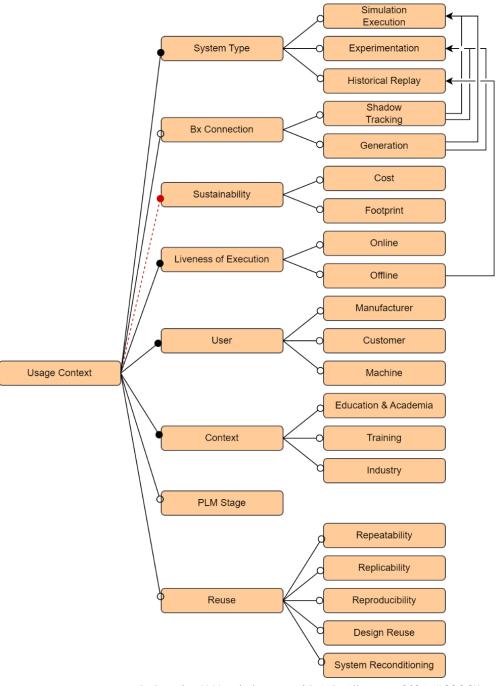


Quality Assurance





Usage Context

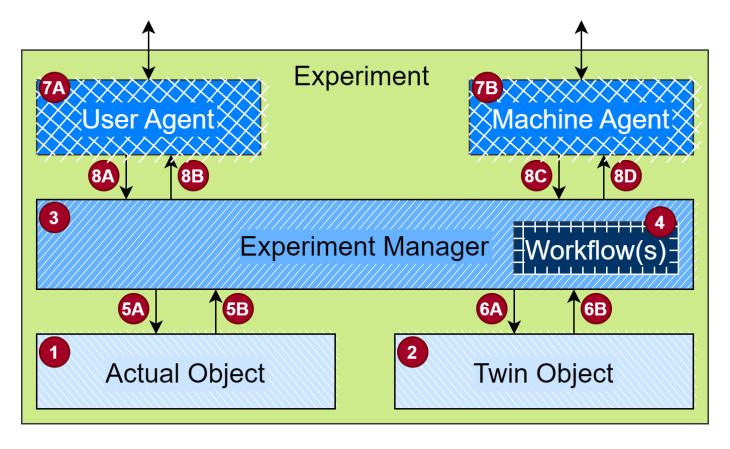




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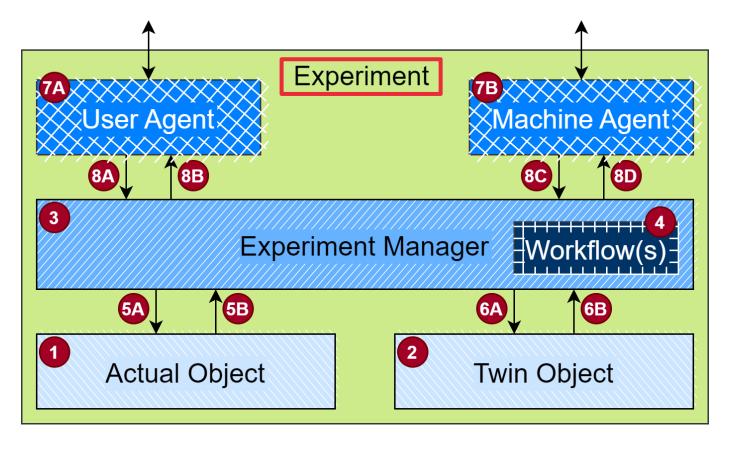
Conceptual Architecture(s)



presence conditions to capture variability



Conceptual Architecture(s)



presence conditions to capture variability

An **experiment** is an intentional set of (possibly hierarchically composed) activities, carried out on a specific SuS in order to accomplish a specific set of goals.

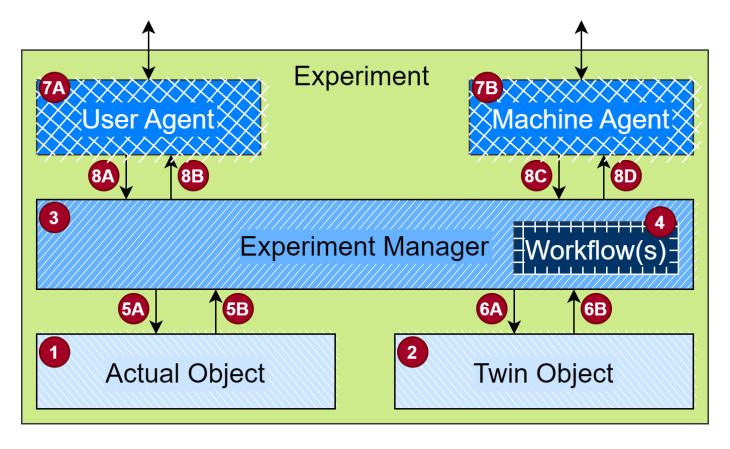


Goals w.r.t. their Properties of Interest (Pols)

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Conceptual Architecture(s)

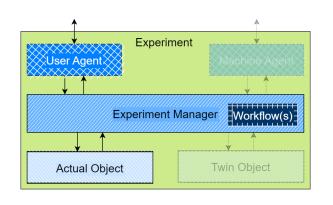


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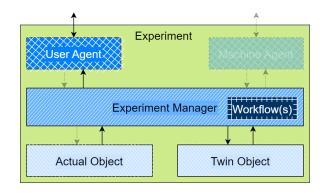


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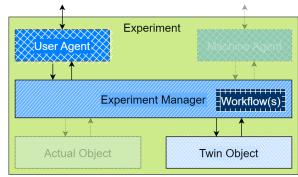
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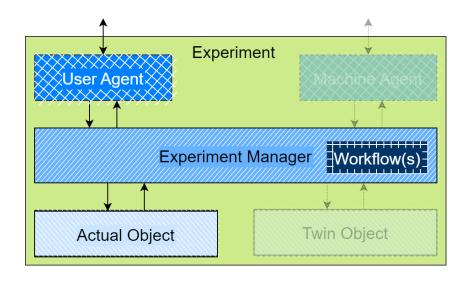


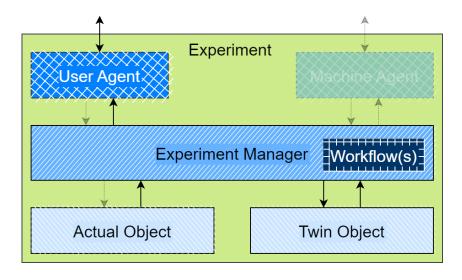


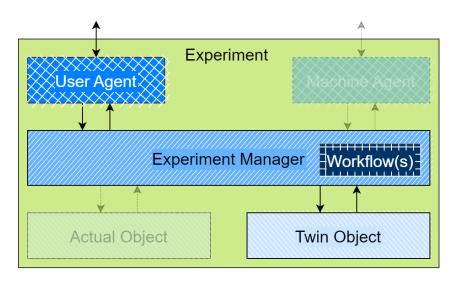


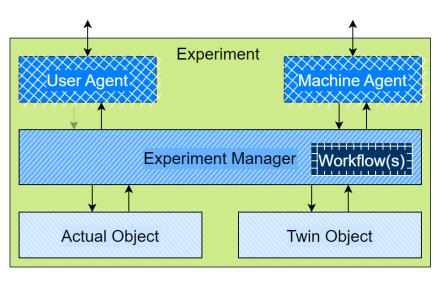


Conceptual Architecture Example(s)









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"feature model" to capture variability

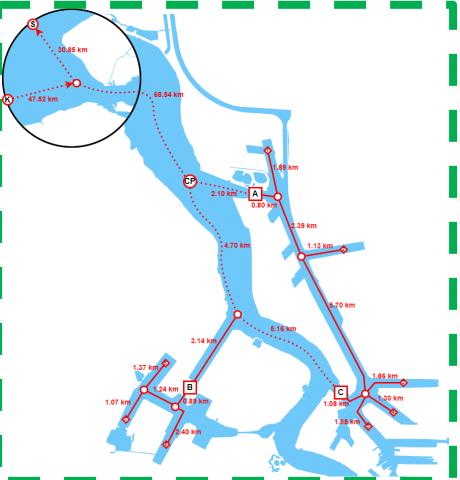


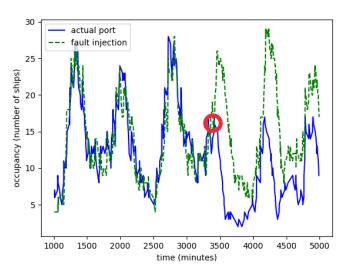
Workflow(s)

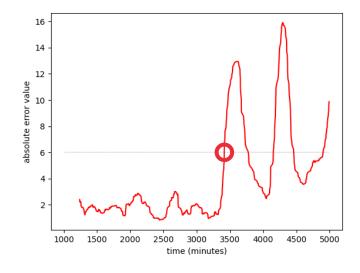
Proof-of-Concept: Port of Antwerp

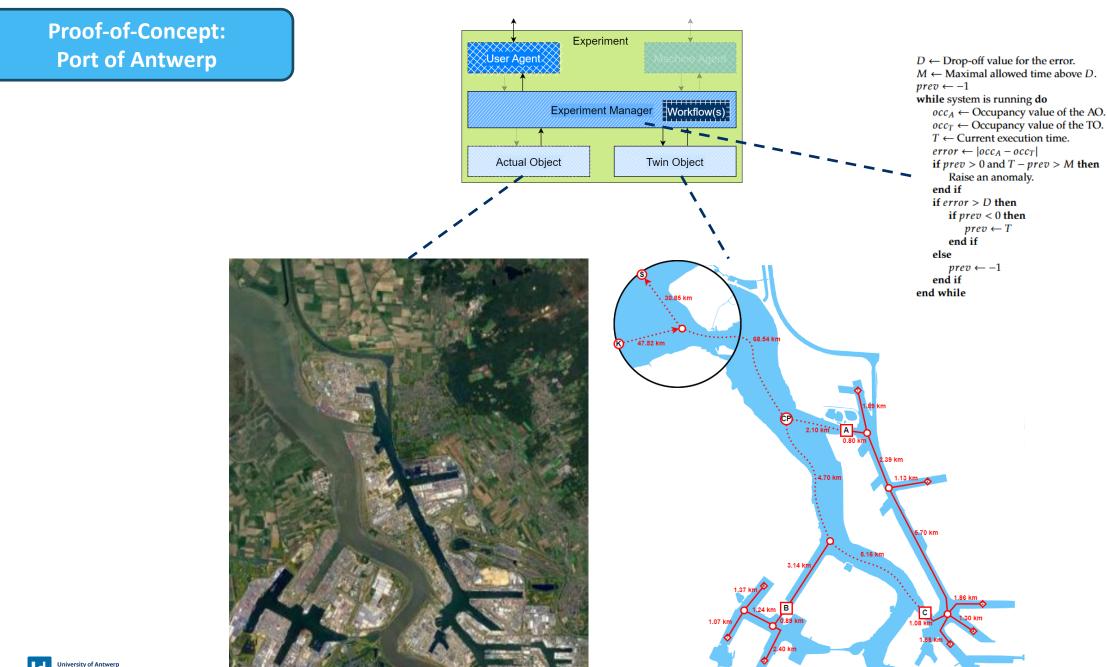
Anomaly Detection











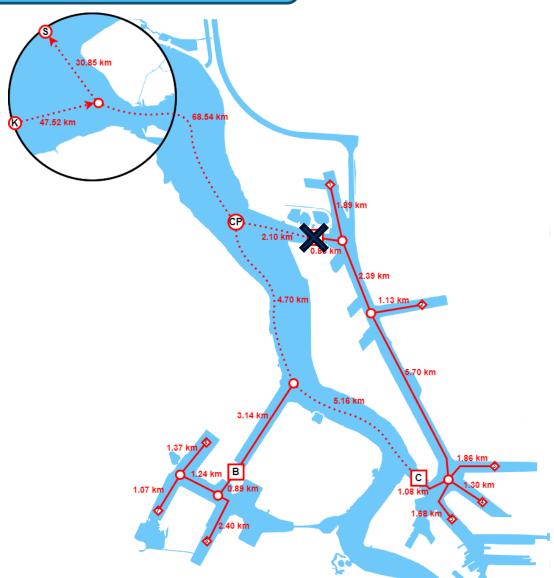
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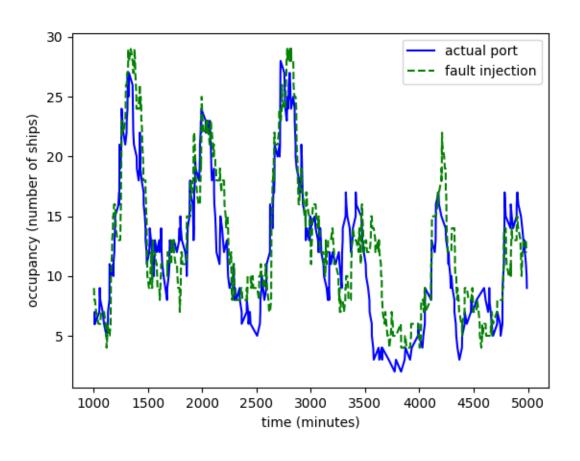
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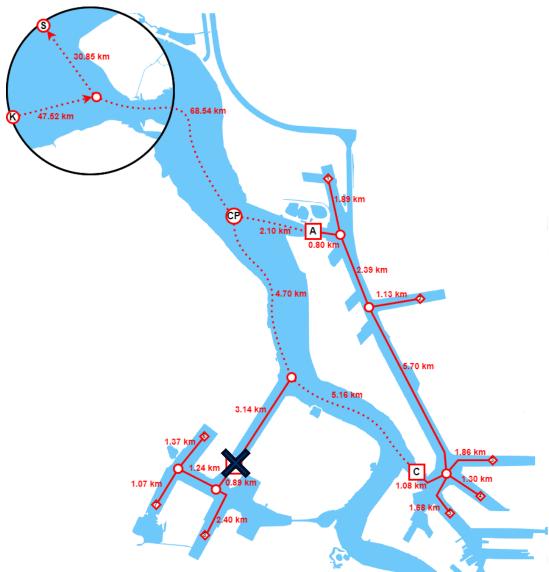
Proof-of-Concept: Port of Antwerp



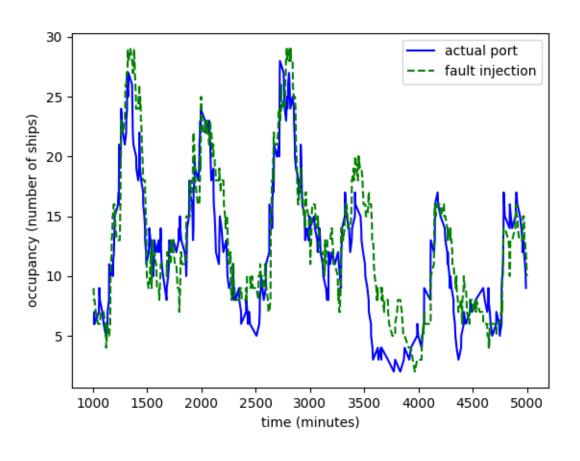
DTW Score = 317 NDW Score = 437.25



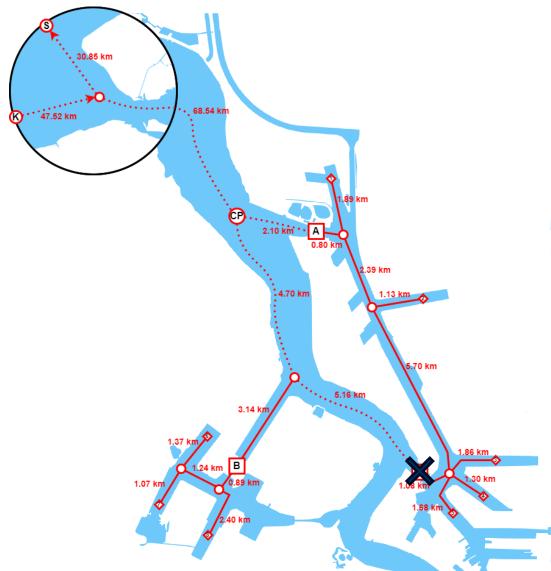
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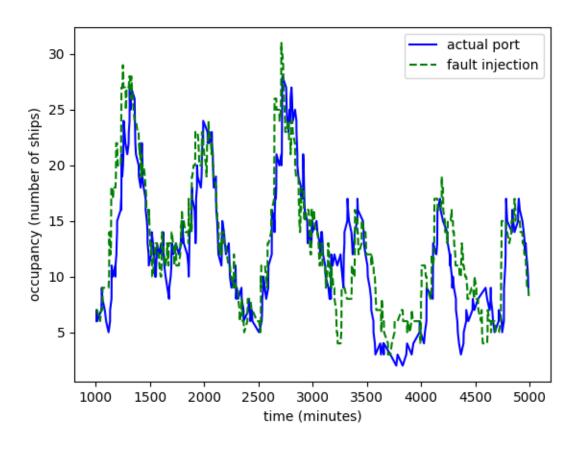
DTW Score = 288 NDW Score = 436.91



Proof-of-Concept: Port of Antwerp



DTW Score = 252 NDW Score = 433.66

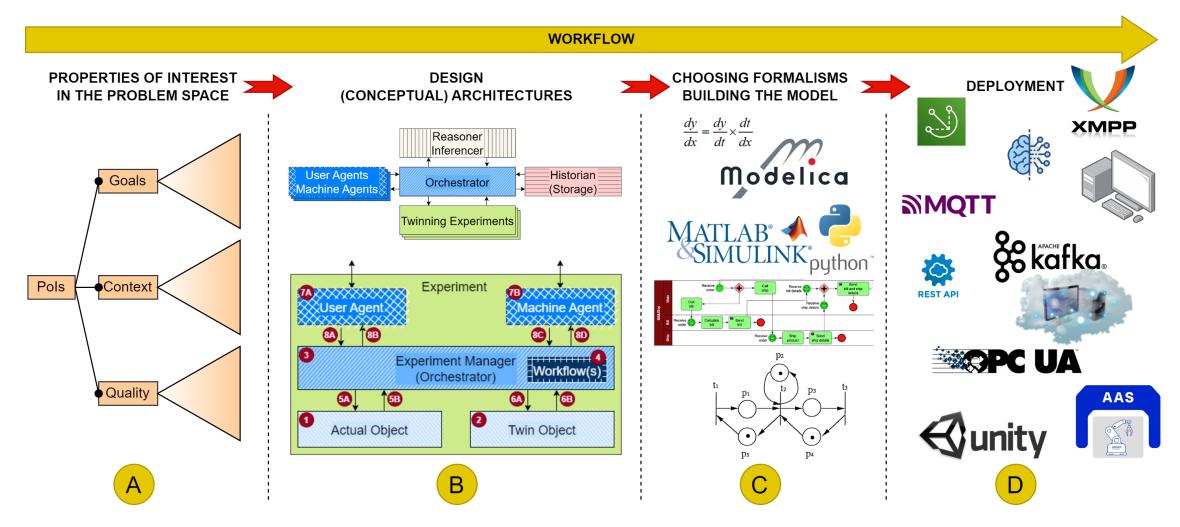


Research Questions

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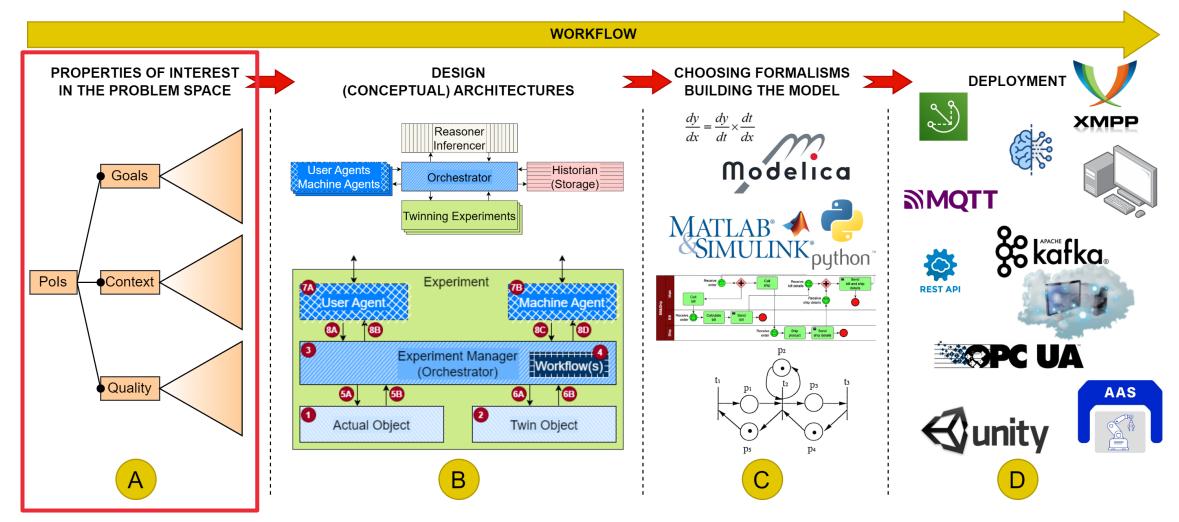


Stages of Twinning Variability



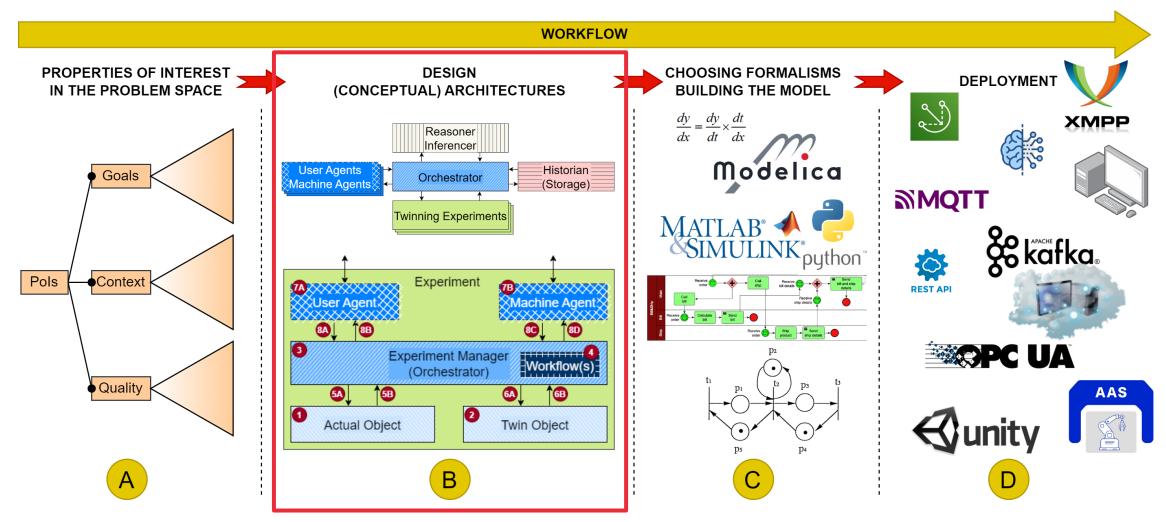


Stages of Twinning Variability – The Problem Space

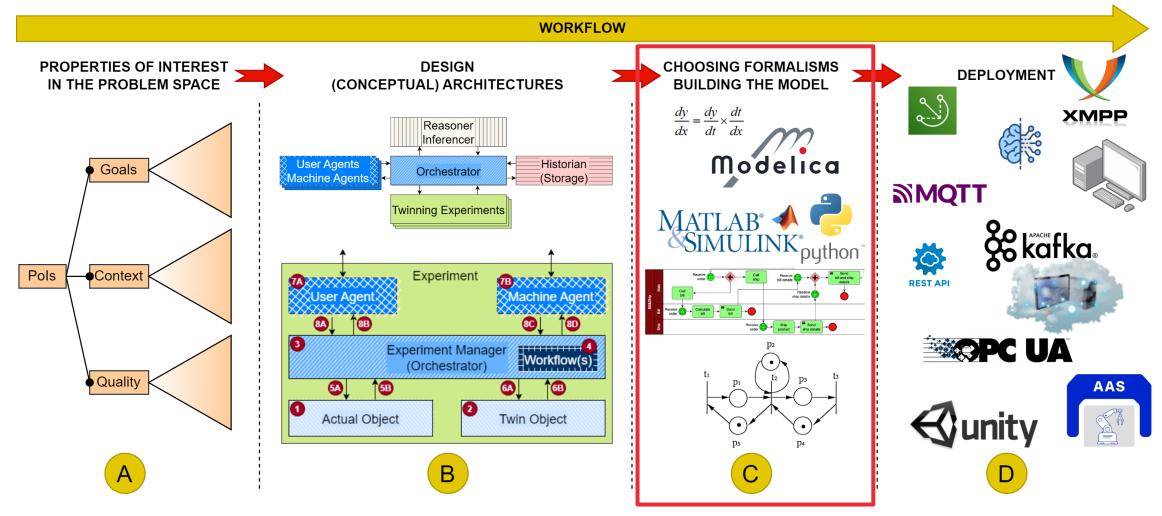




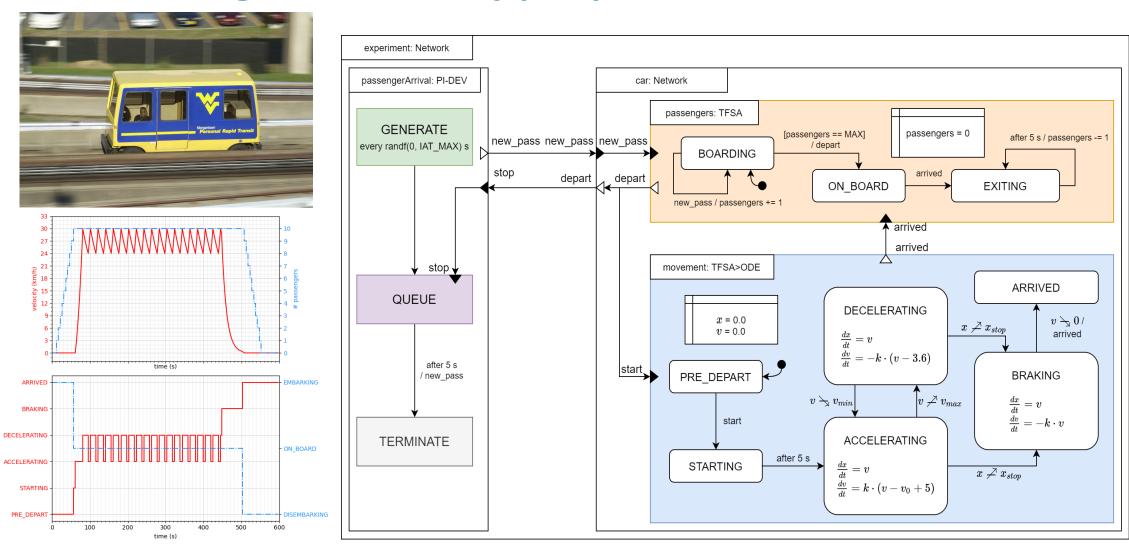
Stages of Twinning Variability – Architectures



Stages of Twinning Variability – Modelling

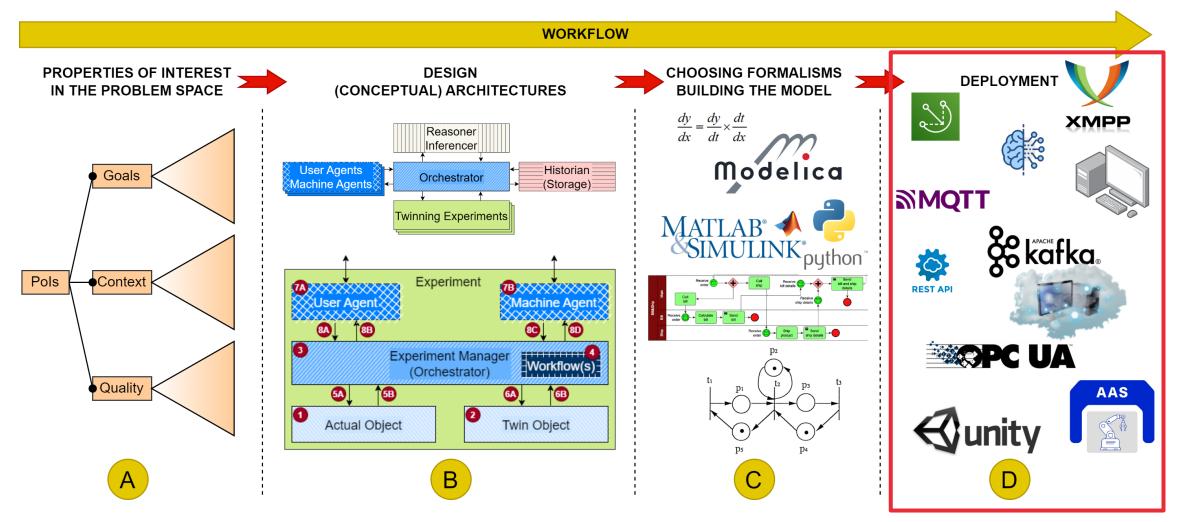


MPM: Using the most appropriate...





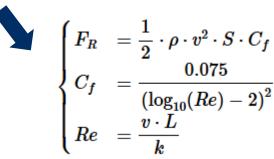
Stages of Twinning Variability – Deployment



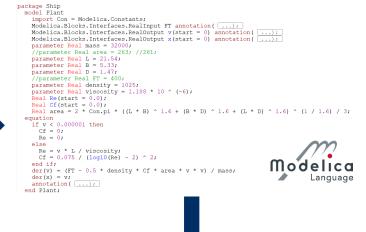
Proof-of-Concept: 1D Behaviour of a Ship

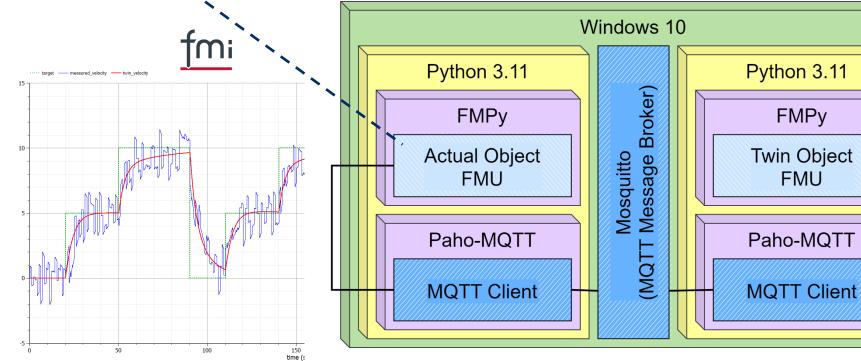






Deployment







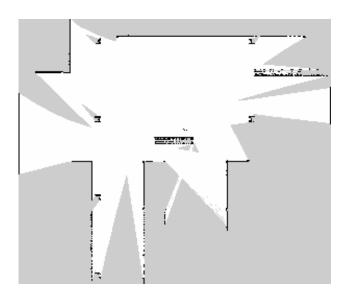
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Proof-of-Concept: Turtlebot



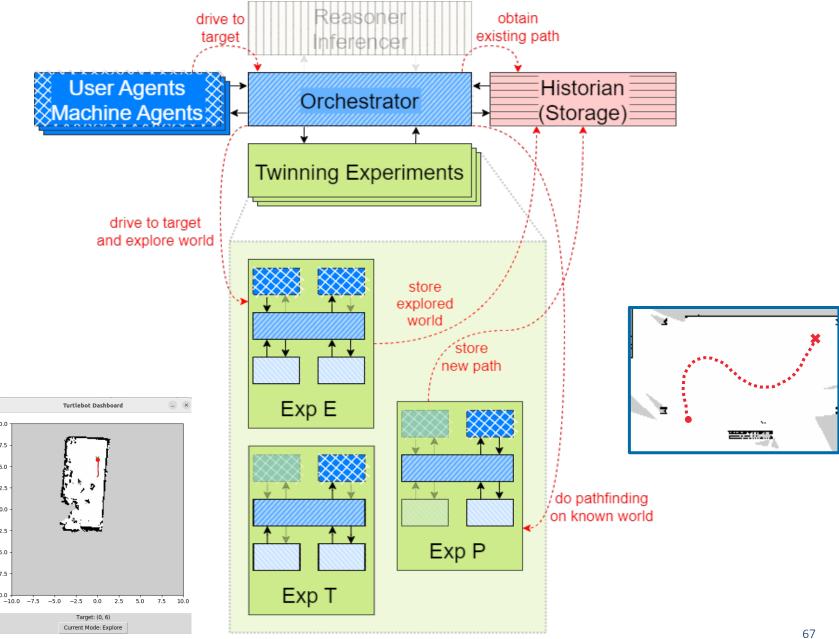


7.5 -

2.5 -

0.0 -

-2.5 -









https://shorturl.at/0lXEl

Stages of Twinning Variability

