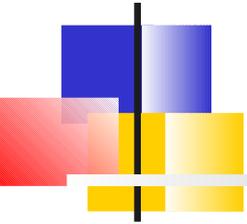


DEVS modeling of Traffic in AToM3

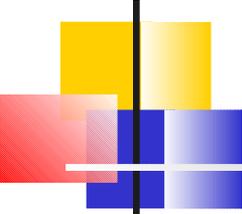


Presented by

Ximeng Sun

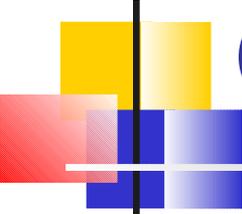
April 11, 2005





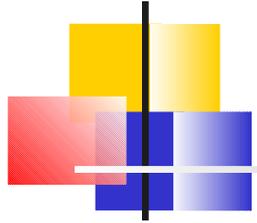
References

- [1] Bernard P. Zeigler, Herbert Praehofer, and Tag Gon Kim.
Theory of Modeling and Simulation.
Academic Press, 2000.
- [2] Hans Vangheluwe, Juan de Lara.
Computer Automated Multi-Paradigm Modelling for Analysis and Design of Traffic Networks.
Proceedings of the 2004 Winter Simulation Conference.
- [3] Ernesto Posse and Jean-Sebastien Bolduc.
Generation of DEVS Modeling and Simulation Environments.
Proceedings of the 2003 Summer Simulation MultiConference, 2003
- [4] Modelling, Simulation and Design Lab.
AToM3 V0.3: A Tool for Multi-formalism and Meta-Modelling
<http://msdl.cs.mcgill.ca/MSDL/research/>
- [5] Bernard P. Zeigler, Hessem S. Sarjoughian.
Introduction to DEVS Modeling and Simulation with JAVA.
<http://www.acims.arizona.edu/SOFTWARE/software.shtml#DEVSSJAVA>



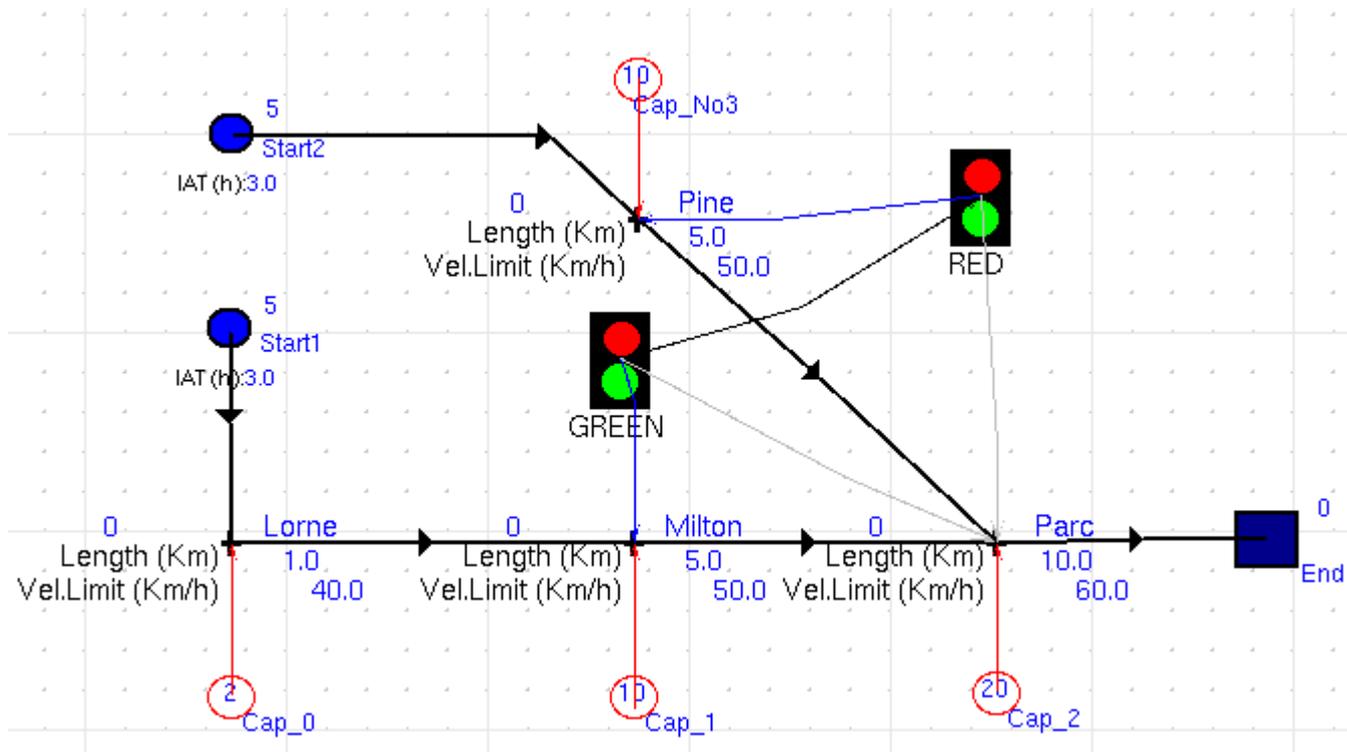
Outline

- Introduction
 - TimedTraffic Formalism
 - DEVS Formalism
- Map TimedTraffic to DEVS
 - Meta-Modeling
 - TimedTraffic Meta-Model
 - DEVS Meta-model
 - Model Transformation
 - Code Generation (Python and Java)
- Demo
- Conclusion



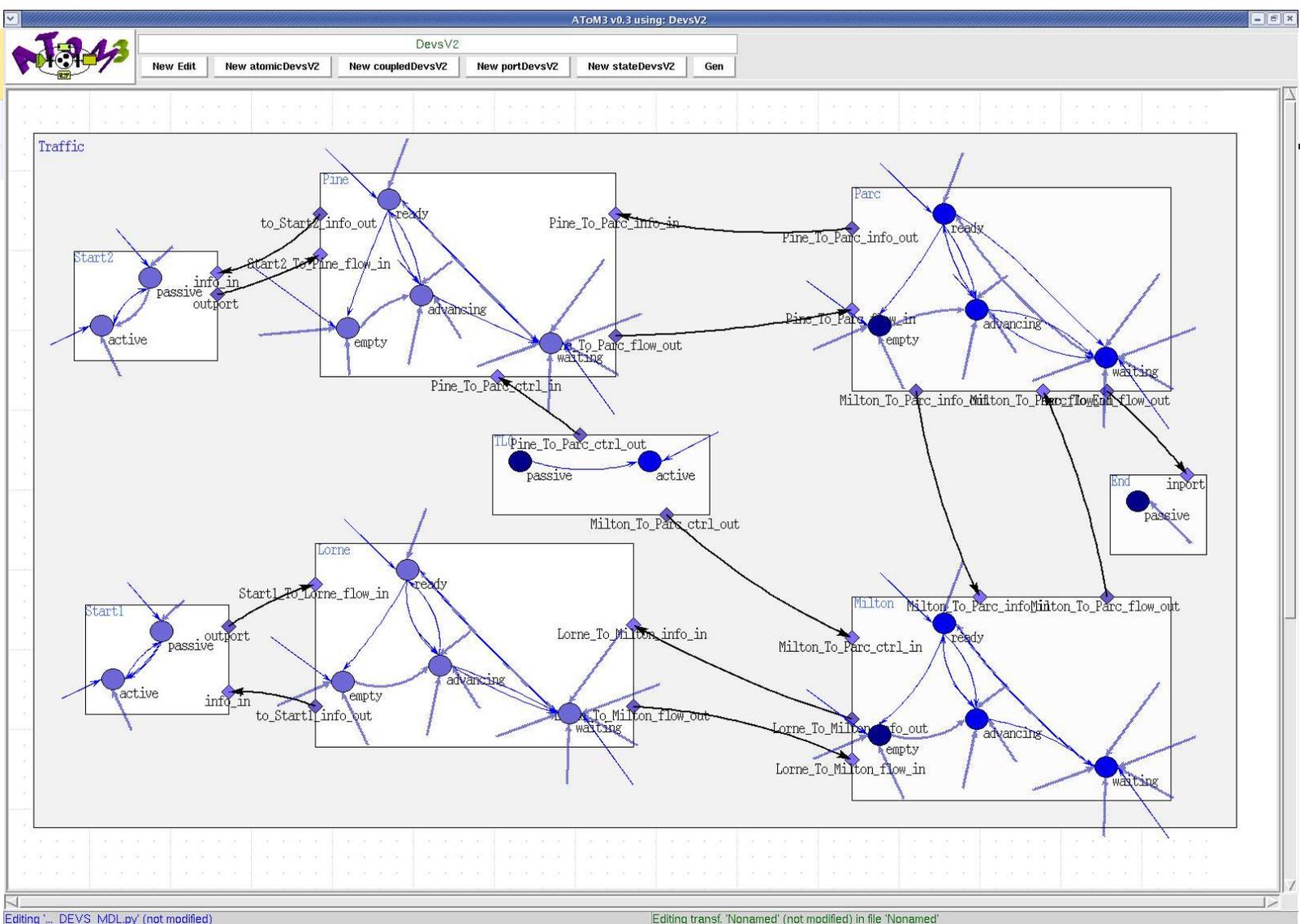
-
- Introduction
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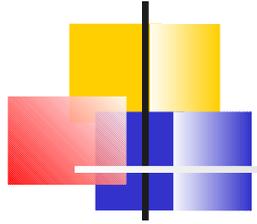
TimedTraffic Formalism



Based on models described in [2].

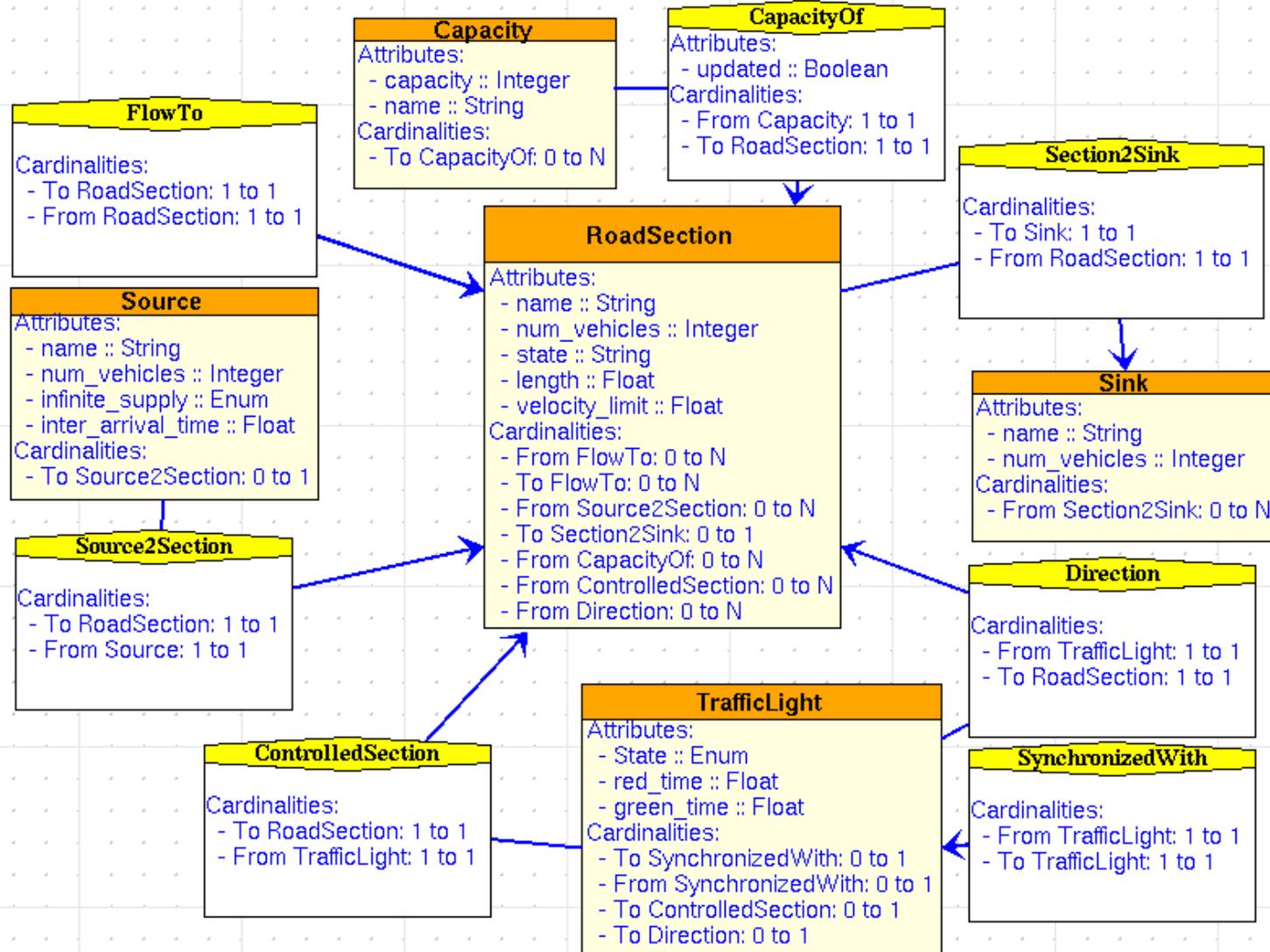
DEVS Formalism





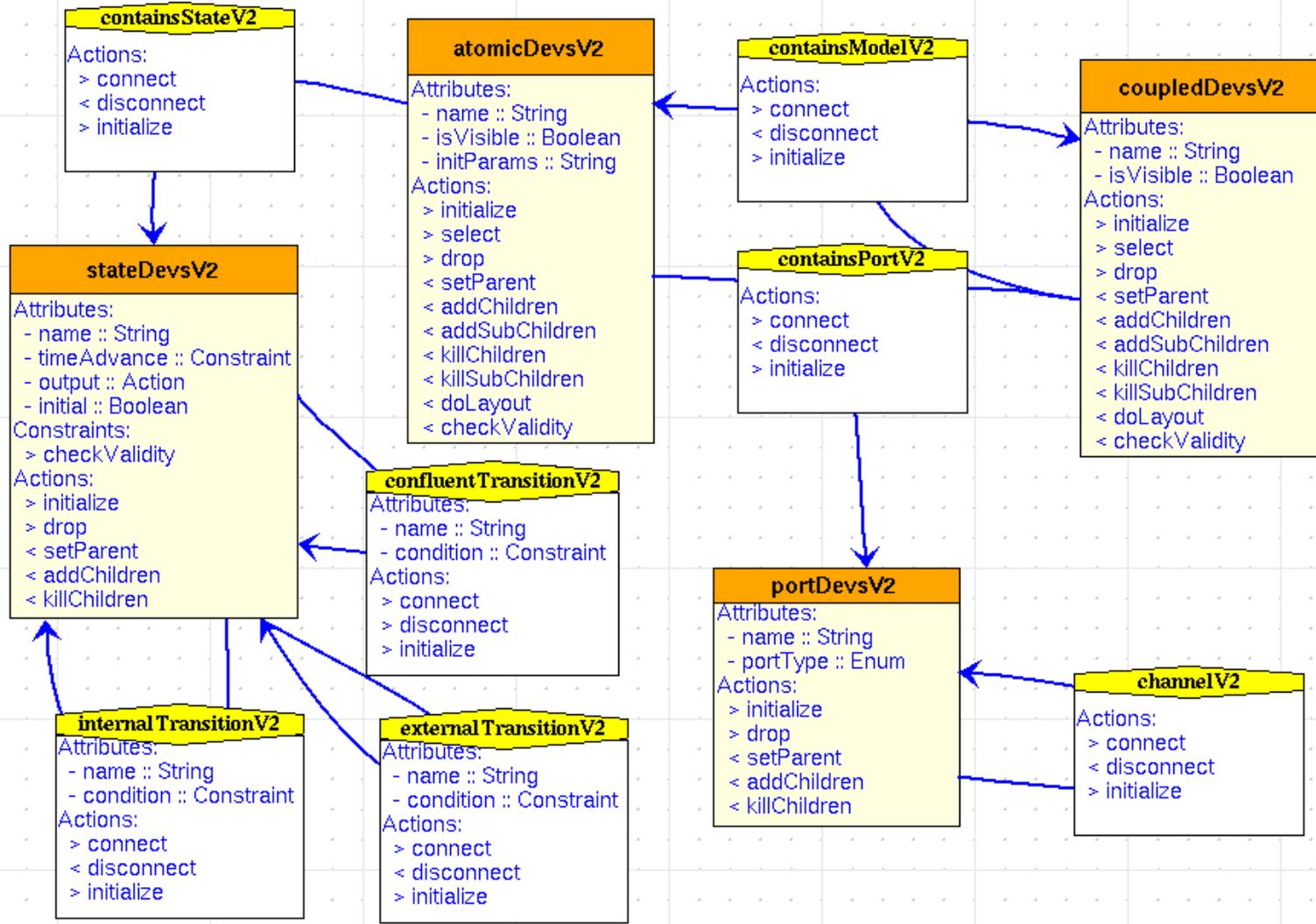
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TimedTraffic Meta-Model



Based on the meta-model described in [2].

DEVS Meta-Model

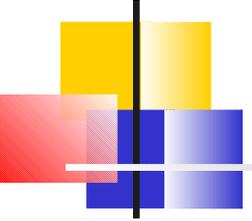


Based on the meta-model described in [3] and the work done by Denis Dube

(<http://moncs.cs.mcgill.ca/people/hv/teaching/MSBDesign/presentations/050324.DenisDube.pdf>)

TimedTraffic to DEVS Transformation Rules

- AToM3 can automatically generate nice documents for all transformation rules.



Rule 0: Initialization

Global initial action:

```
self.rootTrafficGenerated = False

for node in graph.listNodes["Source"]:
    node.sourceGeneratorGenerated = False

for node in graph.listNodes["Sink"]:
    node.sinkCollectorGenerated = False

for node in graph.listNodes["RoadSection"]:
    node.roadAtomicGenerated = False

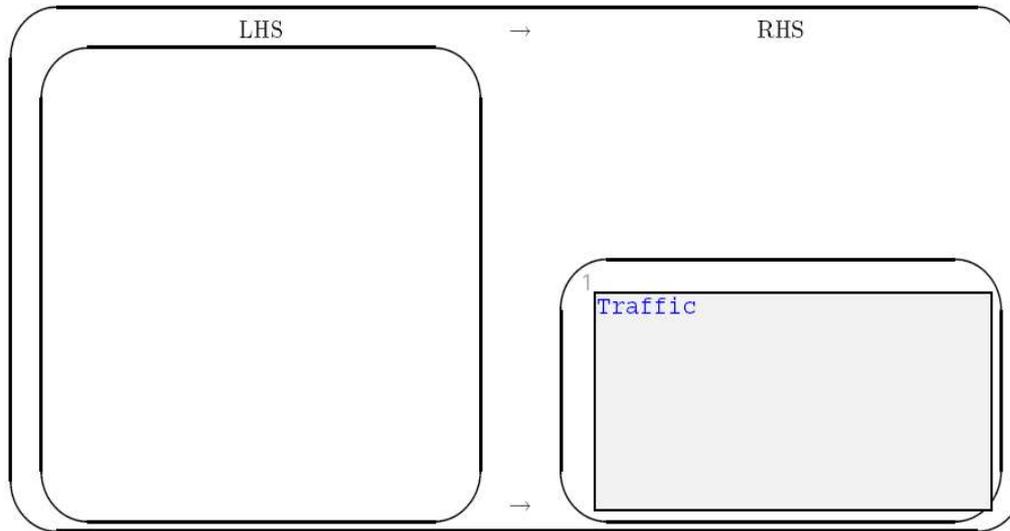
for node in graph.listNodes["Capacity"]:
    node.capacityInfoGenerated = False

for node in graph.listNodes["TrafficLight"]:
    node.trafficLightWithRoadGenerated = False
    node.trafficLightSyncGenerated = False

self.TL_count = 0
```

Rule 1: Generate Top-level “Traffic” Coupled DEVS

Rule 1 (Order 1): RootTraffic



Precondition:

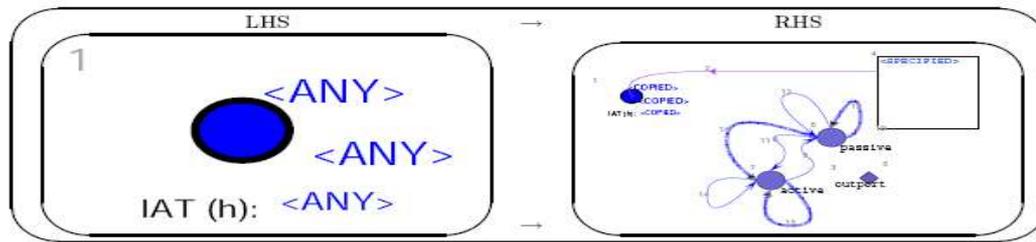
```
return not self.graphGrammar.rootTrafficGenerated
```

Post action:

```
self.graphGrammar.rootTrafficGenerated = True
```

Rule 2: Transform “Source” to “Generator” Atomic DEVS

Rule 2 (Order 2): Source2Generator



Precondition:

```
node = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
return not node.sourceGeneratorGenerated
```

Post action:

```
node_1 = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
node_4 = self.getMatched(graphID, self.RHS.nodeWithLabel(4))

node_1.sourceGeneratorGenerated = True

node_4.connectedWithCoupled = False
node_4.model_type = "generator"
```

Specify: *atomicDevsV2* #4

```
node_1 = self.getMatched(graphID, self.LHS.nodeWithLabel(1))

str_retrun = "    self.num_vehicles = " + str(node_1.num_vehicles.getValue()) + chr(10)
+ "    self.inter_arrival_time = " + str(node_1.inter_arrival_time.getValue()) + chr(10)
+ "    self.ahead_status = \"empty\" + chr(10)
+ "    self.time_left = " + str(node_1.inter_arrival_time.getValue()) + chr(10)
+ "    self.remain_vehichles = "

if node_1.infinite_supply.getValue() == True:
    str_retrun = str_retrun + str(99999)
else:
    str_retrun = str_retrun + str(node_1.num_vehicles.getValue())

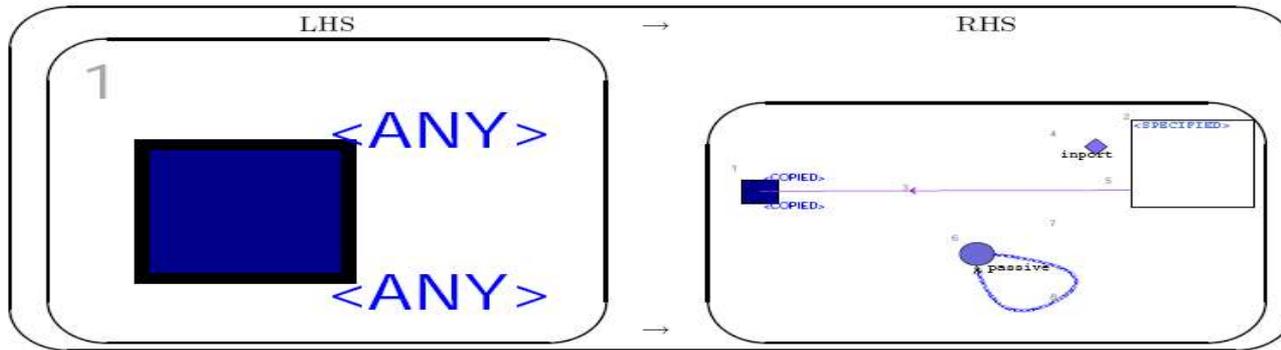
return str_retrun
```

Specify: *atomicDevsV2* #4

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue()
```

Rule 3: Transform “Sink” to “Collector” Atomic DEVS

Rule 3 (Order 3): Sink2Collector



Precondition:

```
node = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
return not node.sinkCollectorGenerated
```

Post action:

```
node_1 = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
node_2 = self.getMatched(graphID, self.RHS.nodeWithLabel(2))

node_1.sinkCollectorGenerated = True

node_2.connectedWithCoupled = False
node_2.model_type = "collector"
```

Specify: *atomicDevsV2* #2

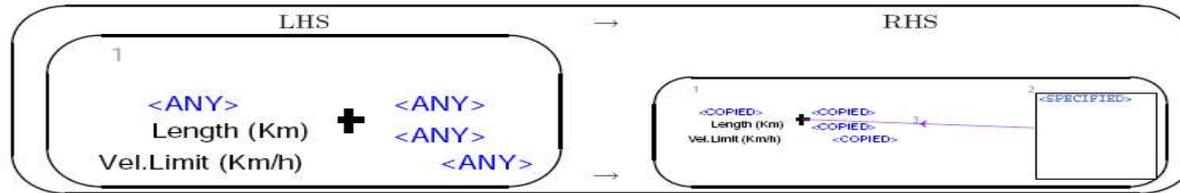
```
return " self.arrived = 0" + chr(10) + " self.current_time = 0" + chr(10) + " self.average = 0" + chr(10)
```

Specify: *atomicDevsV2* #2

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue()
```

Rule 4: Transform “RoadSection” to “Road” Atomic DEVS

Rule 4 (Order 4): Road2Road



Precondition:

```
node = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
return not node.roadAtomicGenerated
```

Post action:

```
node_1 = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
node_2 = self.getMatched(graphID, self.RHS.nodeWithLabel(2))

node_1.roadAtomicGenerated = True

node_2.connectedWithCoupled = False
node_2.model_type = "road"
```

Specify: *atomicDevsV2 #2*

```
node_1 = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
node_2 = self.getMatched(graphID, self.RHS.nodeWithLabel(2))

str_return = "    self.length = " + str(node_1.length.getValue()) + chr(10)
+ "    self.velocity_limit = " + str(node_1.velocity_limit.getValue()) + chr(10)
+ "    self.queue = []" + chr(10) + "    self.traffic_light = \"green\"" + chr(10)
+ "    self.ahead_status = \"empty\"" + chr(10) + "    self.changed = \"false\"" + chr(10)
+ "    self.current_time = 0" + chr(10) + "    self.time_left = 99999" + chr(10)
+ "    self.capacity = 99999" + chr(10)

return str_return
```

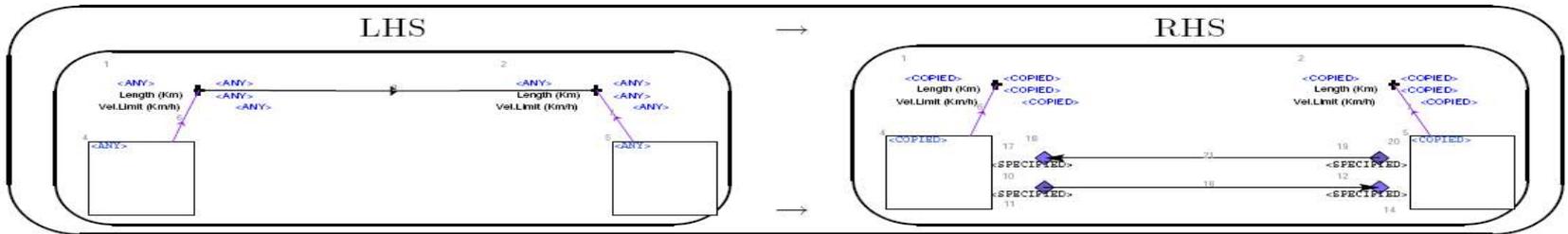
Specify: *atomicDevsV2 #2*

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue()
```


Rule 7: Transform “FlowTo” to

“Channel”

Rule 7 (Order 7): Flow2Channel



Specify: *portDevsV2* #10

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue() + '_To_' + self.getMatched(graphID, self.LHS.nodeWithLabel(2)).name.getValue() + '_flow_out'
```

Specify: *portDevsV2* #12

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue() + '_To_' + self.getMatched(graphID, self.LHS.nodeWithLabel(2)).name.getValue() + '_flow_in'
```

Specify: *portDevsV2* #17

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue() + '_To_' + self.getMatched(graphID, self.LHS.nodeWithLabel(2)).name.getValue() + '_info_in'
```

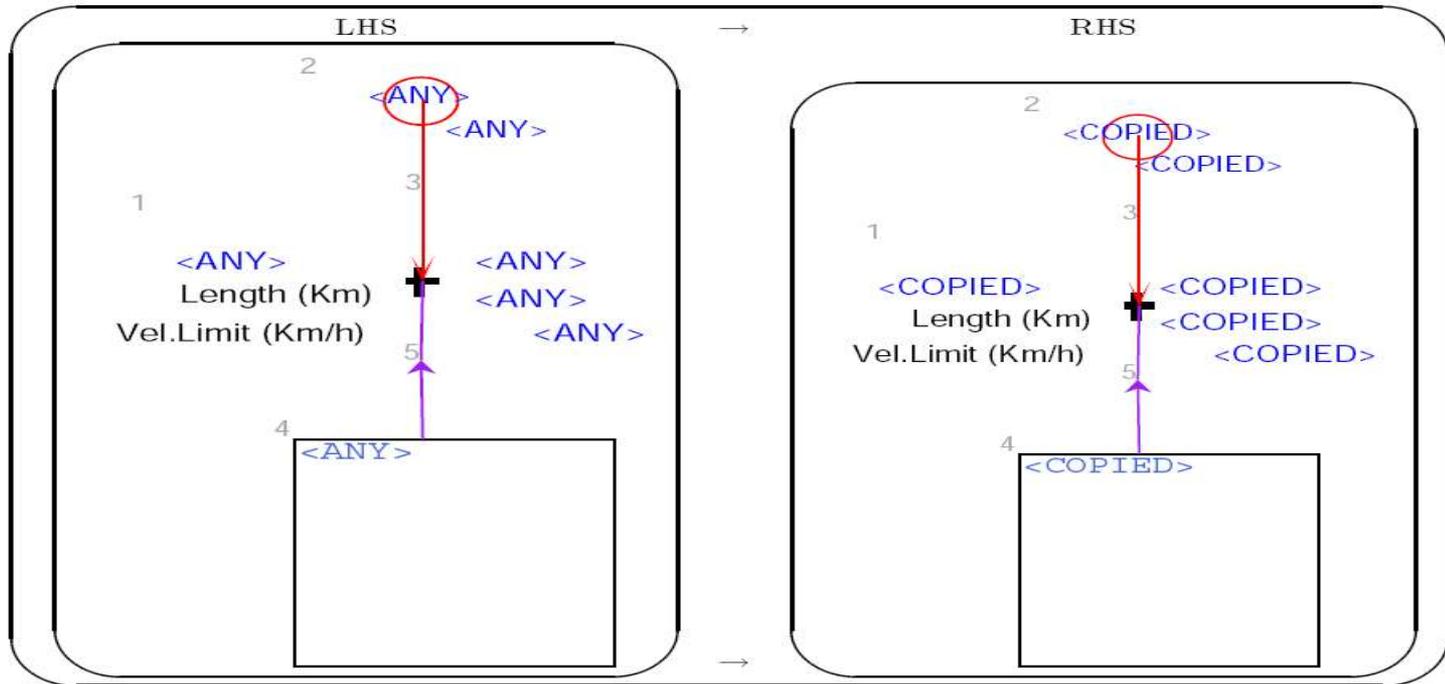
Specify: *portDevsV2* #19

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue() + '_To_' + self.getMatched(graphID, self.LHS.nodeWithLabel(2)).name.getValue() + '_info_out'
```

Rule 8: Copy “Capacity”

information into “Road”

Rule 8 (Order 8): CapacityWithRoad



Precondition:

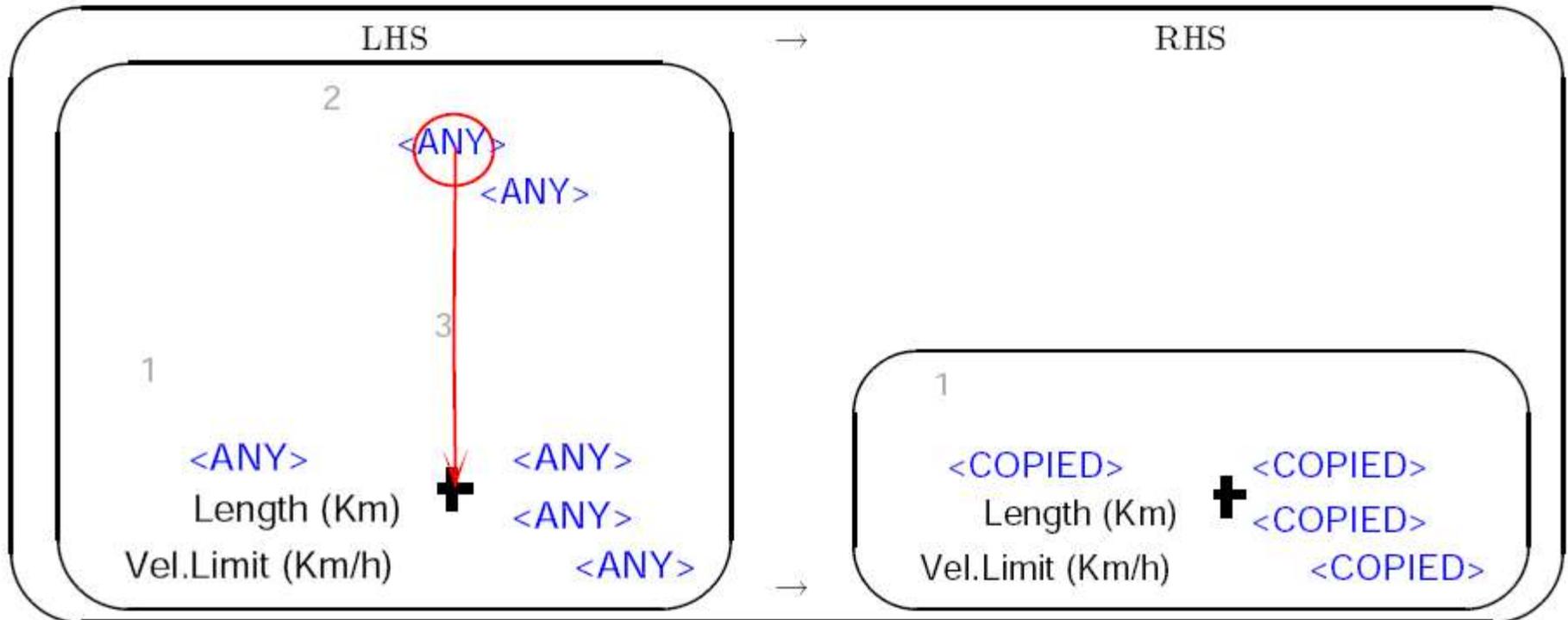
```
node = self.getMatched(graphID, self.LHS.nodeWithLabel(2))
return not node.capacityInfoGenerated
```

Post action:

```
self.getMatched(graphID, self.LHS.nodeWithLabel(2)).capacityInfoGenerated = True
```

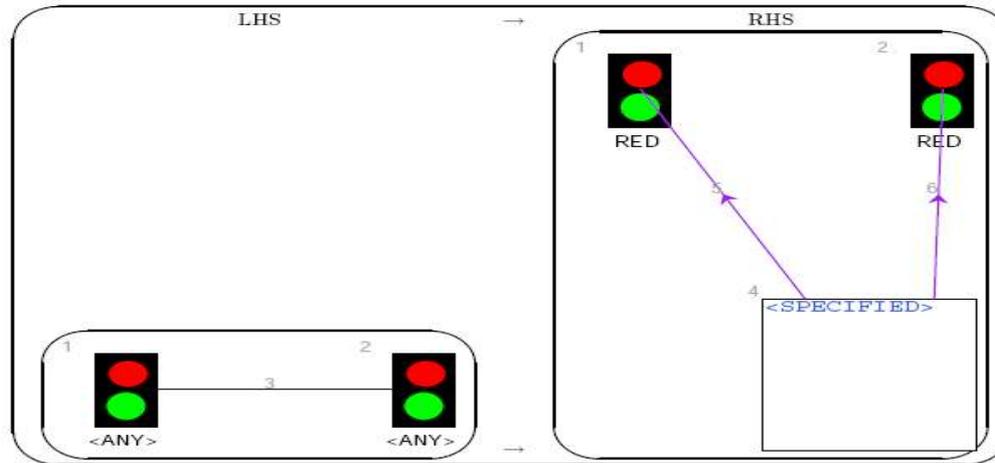
Rule 9: Remove “Capacity”

Rule 9 (Order 9): CapacityCleanup



Rule 10: Transform “TrafficLight” to “TrafficLight” Atomic DEVS (double)

Rule 10 (Order 10): TrafficLightSync1



Precondition:

```
node1 = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
node2 = self.getMatched(graphID, self.LHS.nodeWithLabel(2))
return (not node1.trafficLightSyncGenerated) and (not node2.trafficLightSyncGenerated)
```

Post action:

```
self.getMatched(graphID, self.LHS.nodeWithLabel(1)).trafficLightSyncGenerated = True
self.getMatched(graphID, self.LHS.nodeWithLabel(2)).trafficLightSyncGenerated = True

node_4 = self.getMatched(graphID, self.RHS.nodeWithLabel(4))
node_4.connectedWithCoupled = False
node_4.model_type = "trafficLight"

self.graphGrammar.TL_count = self.graphGrammar.TL_count + 1
```

Specify: *atomicDevsV2 #4*

```
return ""
```

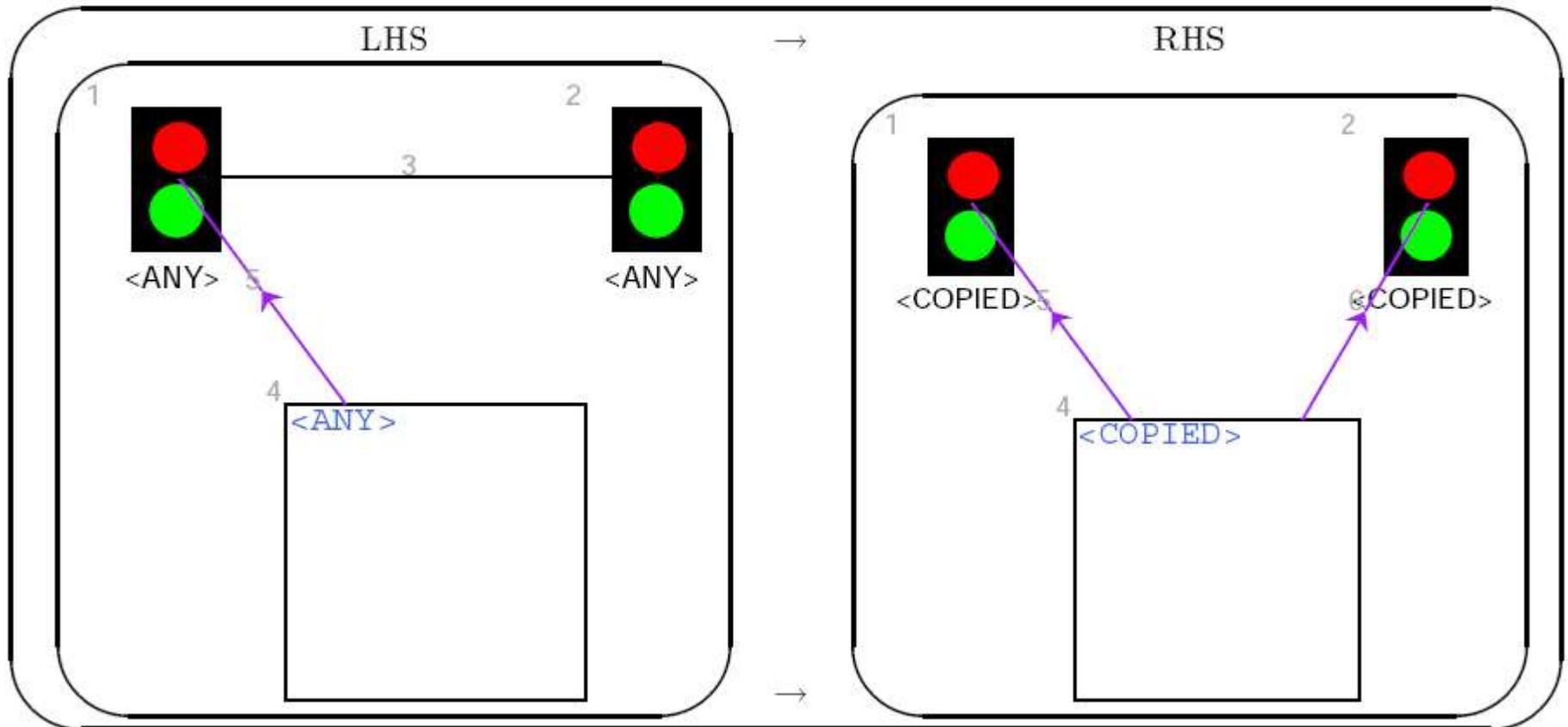
Specify: *atomicDevsV2 #4*

```
return "TL" + str(self.graphGrammar.TL_count)
```

Rule 11: Transform “SyncWith”

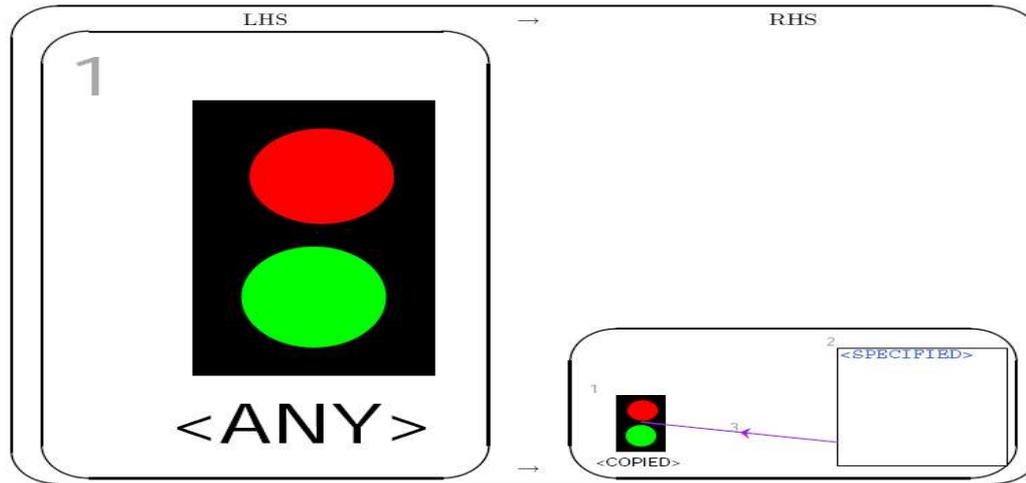
relation

Rule 11 (Order 11): TrafficLightSync2



Rule 12: Transform “TrafficLight” to “TrafficLight” Atomic DEVS (single)

Rule 12 (Order 12): TrafficLightSync3



Precondition:

```
node1 = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
return not node1.trafficLightSyncGenerated
```

Post action:

```
self.getMatched(graphID, self.LHS.nodeWithLabel(1)).trafficLightSyncGenerated = True

node_2 = self.getMatched(graphID, self.RHS.nodeWithLabel(2))
node_2.connectedWithCoupled = False
node_2.model_type = "trafficLight"

self.graphGrammar.TL_count = self.graphGrammar.TL_count + 1
```

Specify: *atomicDevsV2 #2*

```
return ""
```

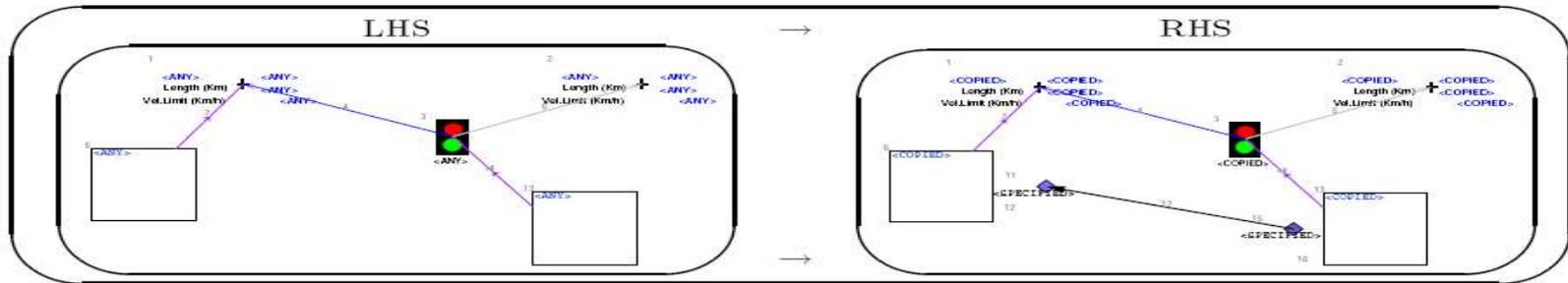
Specify: *atomicDevsV2 #2*

```
return "TL" + str(self.graphGrammar.TL_count)
```

Rule 13: Connect “TrafficLight”

with “Road”

Rule 13 (Order 13): TrafficLightWithRoad



Precondition:

```
node = self.getMatched(graphID, self.LHS.nodeWithLabel(3))
return not node.trafficLightWithRoadGenerated
```

Post action:

```
self.getMatched(graphID, self.LHS.nodeWithLabel(3)).trafficLightWithRoadGenerated = True
```

Specify: *portDevsV2 #11*

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue() + '_To_'
+ self.getMatched(graphID, self.LHS.nodeWithLabel(2)).name.getValue() + '_ctrl_in'
```

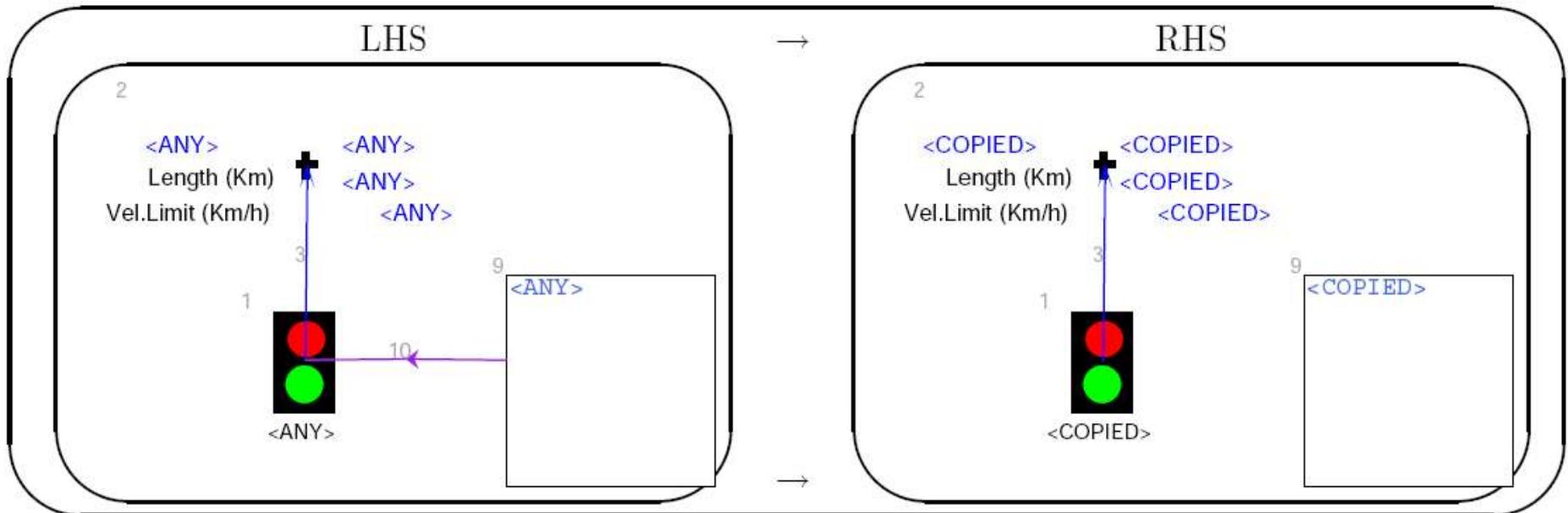
Specify: *portDevsV2 #15*

```
return self.getMatched(graphID, self.LHS.nodeWithLabel(1)).name.getValue() + '_To_'
+ self.getMatched(graphID, self.LHS.nodeWithLabel(2)).name.getValue() + '_ctrl_out'
```

Rule 14: Remove “TrafficLight”

(step 1)

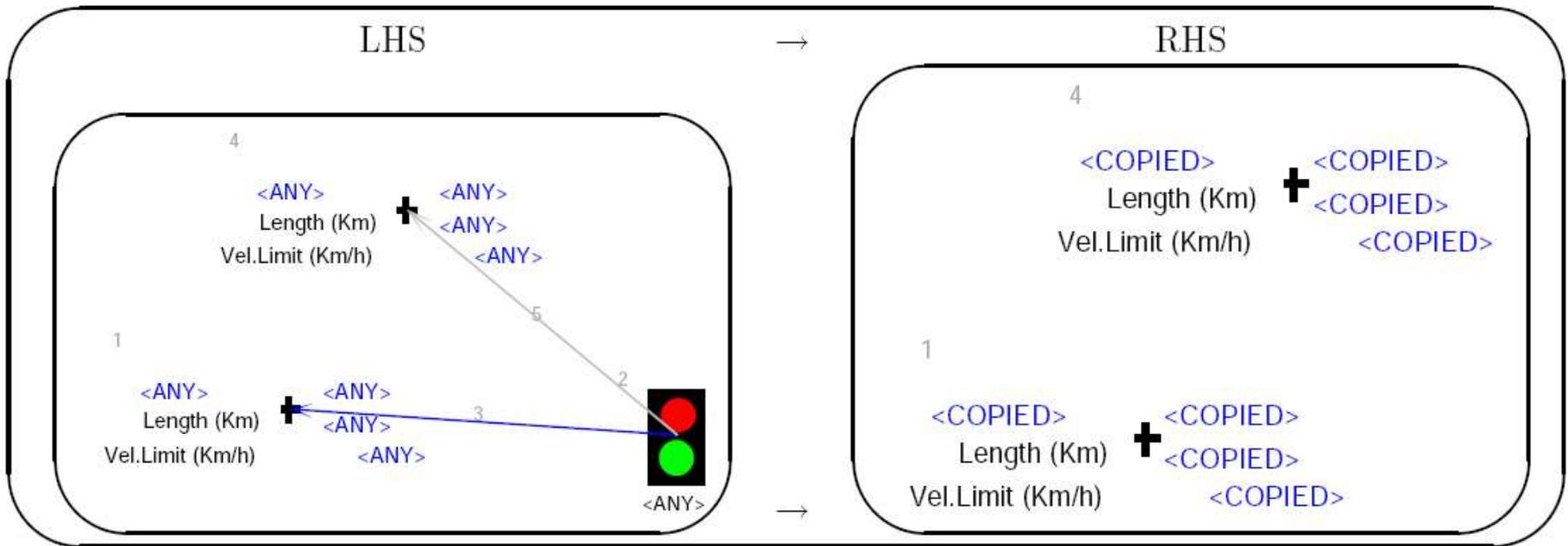
Rule 14 (Order 14): TrafficLightCleanup1



Rule 15: Remove “TrafficLight”

(step 2)

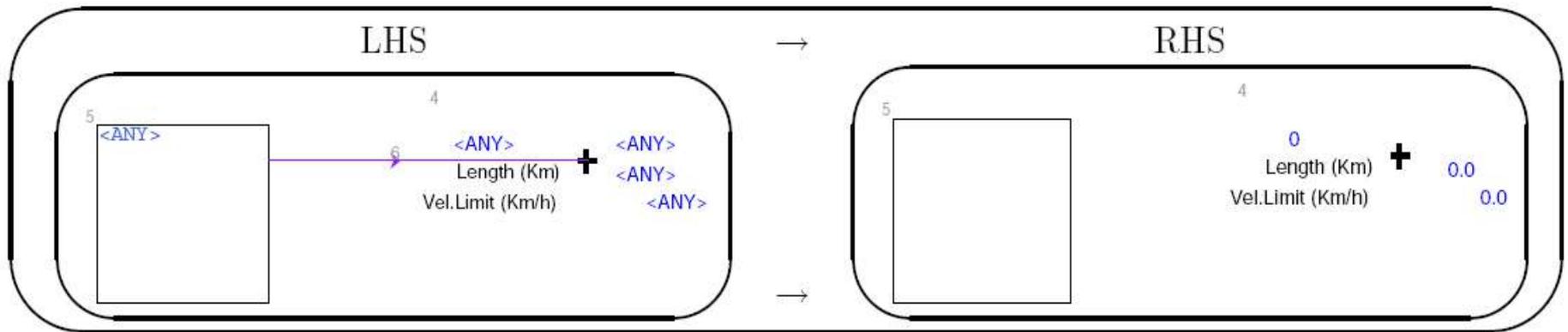
Rule 15 (Order 15): TrafficLightCleanup2



Rule 16: Remove

“RoadSection” (step 1)

Rule 16 (Order 16): RoadCleanup1



Rule 17: Remove

“RoadSection” (step 2)

Rule 17 (Order 17): RoadCleanup2

LHS

→

RHS

1

<ANY>
Length (Km)

+

<ANY>
<ANY>

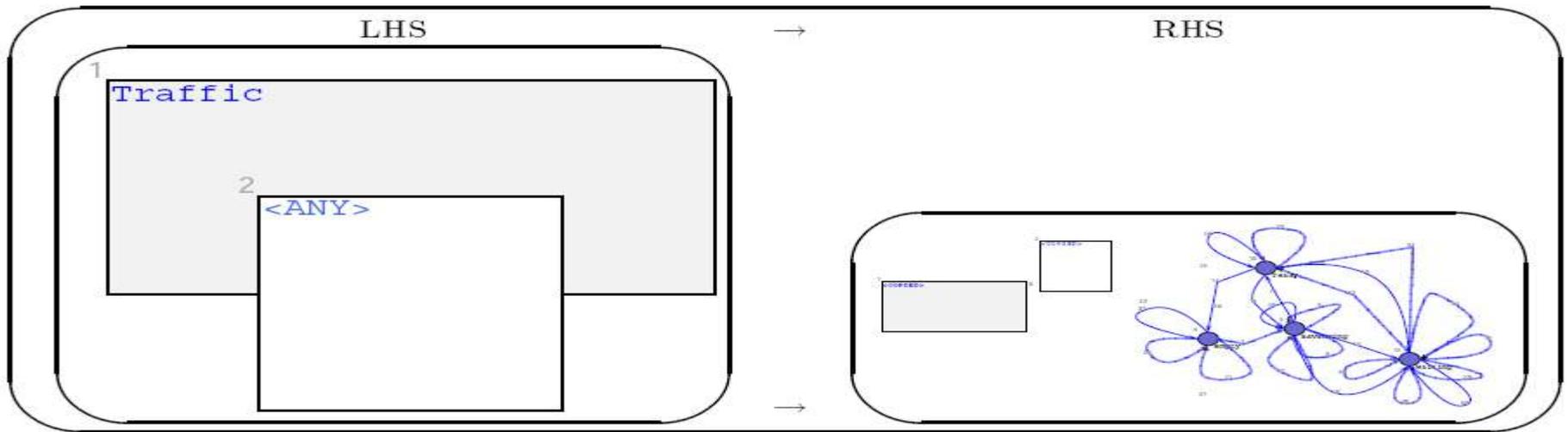
Vel.Limit (Km/h)

<ANY>

→

Rule 18: Connect “Road” Atomic DEVS with “Traffic” Coupled DEVS

Rule 18 (Order 18): ConnectAtomic2Coupled1



Precondition:

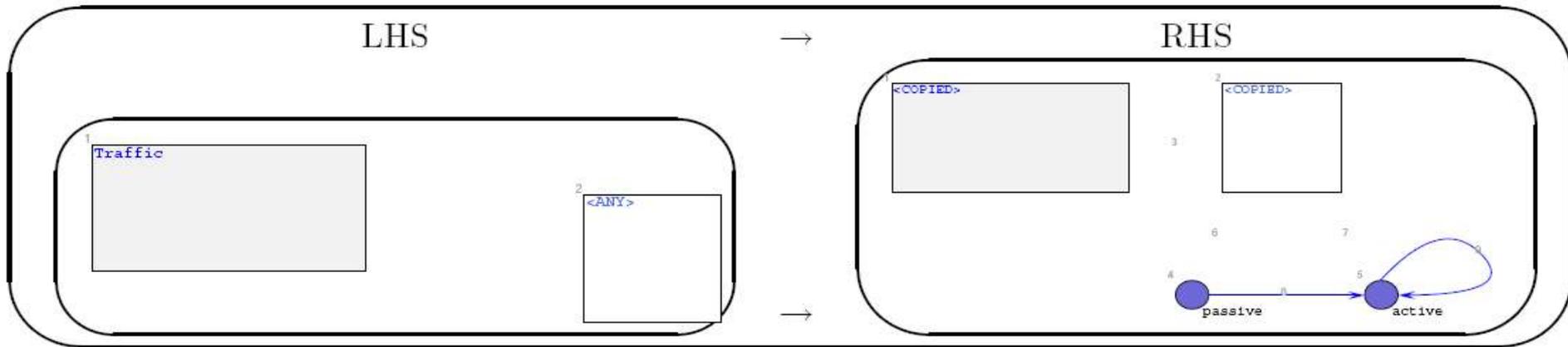
```
node = self.getMatched(graphID, self.LHS.nodeWithLabel(2))  
return (not node.connectedWithCoupled) and (node.model_type == "road")
```

Post action:

```
self.getMatched(graphID, self.LHS.nodeWithLabel(2)).connectedWithCoupled = True
```

Rule 19: Connect “TrafficLight” Atomic DEVS with “Traffic” Coupled DEVS

Rule 19 (Order 19): ConnectAtomic2Coupled2



Precondition:

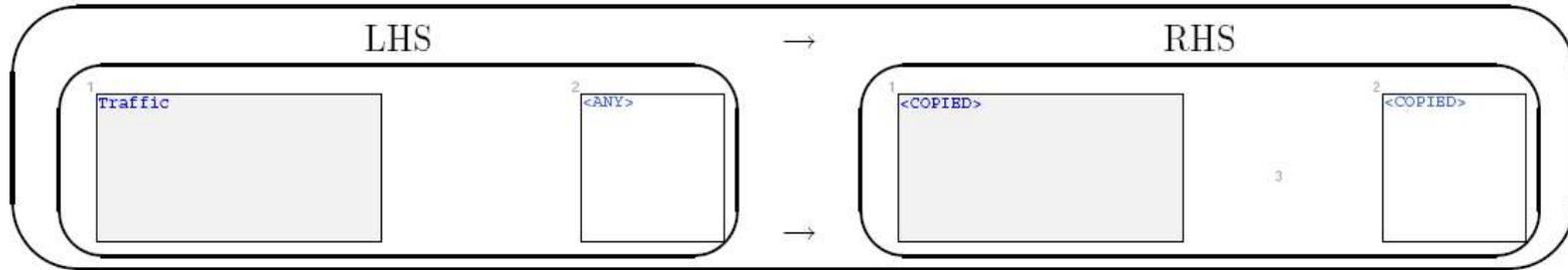
```
node = self.getMatched(graphID, self.LHS.nodeWithLabel(2))  
return (not node.connectedWithCoupled) and (node.model_type == "trafficLight")
```

Post action:

```
self.getMatched(graphID, self.LHS.nodeWithLabel(2)).connectedWithCoupled = True
```

Rule 20: Connect “Generator” and “Collector” Atomic DEVS with “Traffic” Coupled DEVS

Rule 20 (Order 20): ConnectAtomic2Coupled3

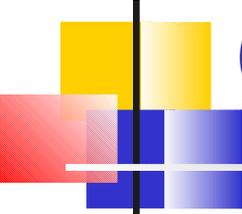


Precondition:

```
node = self.getMatched(graphID, self.LHS.nodeWithLabel(2))  
return (not node.connectedWithCoupled) and (node.model_type == "generator" or node.model_type == "collector")
```

Post action:

```
self.getMatched(graphID, self.LHS.nodeWithLabel(2)).connectedWithCoupled = True
```



Code Generation

■ Simulator in Python (PythonDEVS)

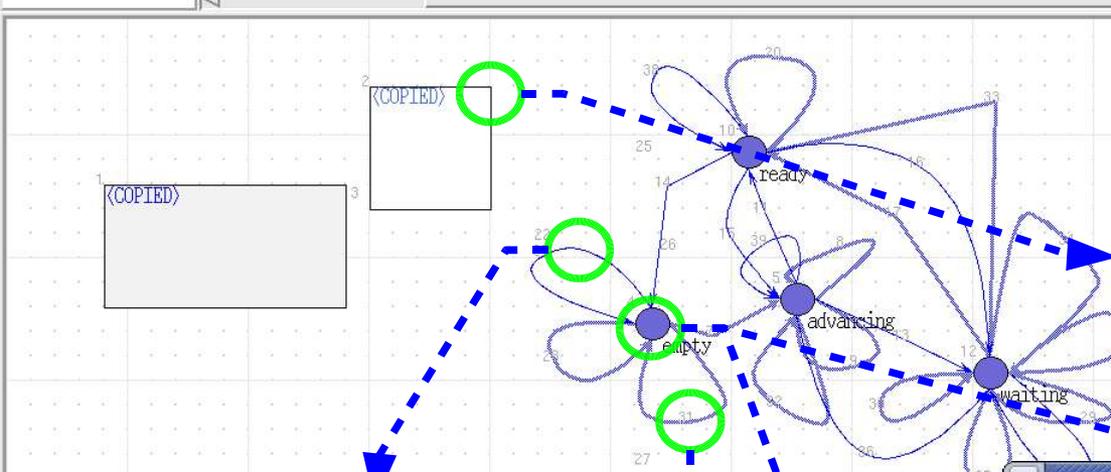
(Based on the work described in [3].)

- Write codes to specify initial parameters, time advance function, output function, and conditions for transitions
- Click “Gen” button in DEVS meta-model toolbar to generate simulators in Python
 - There will be three files at top level: *DEVS.py*, *Simulator.py*, *Traffic.py*
 - For each atomic model there will one sub-directory which contains one file, such as *University_Street.py*
- Run simulation
 - e.g., `$ python Traffic.py 10000`

■ Simulator in Java (DEVSSJAVA)



- New Edit
- New RoadSection
- New Source
- New Sink
- New Capacity
- New TrafficLight
- New Edit
- New atomicDevsV2
- New coupledDevsV2
- New portDevsV2
- New stateDevsV2
- Gen



Editing ATOM3Constraint

Constraint name: PREcondition

timeAdvance

POSTcondition

```

node_1 = self.getMatched(graphID, self.LHS.nodeWithLabel(1))
node_2 = self.getMatched(graphID, self.RHS.nodeWithLabel(2))

str_return = " self.length = " + str(node_1.length.getValue(
) + chr(10) + " self.velocity_limit = " + str(node_1.velocity_
limit.getValue()) + chr(10) + " self.queue = []" + chr(10) + "
self.traffic_light = " + str(node_1.traffic_light.getValue()) + chr(10) + " self.ahead_st
atus = \"empty\"" + chr(10) + " self.changed = \"false\"" + ch
r(10) + " self.current_time = 0" + chr(10) + " self.time_l
ft = 99999" + chr(10) + " self.capacity = 99999" + chr(10)
return str_return
  
```

initParams

Editing internalTransitionV2

Constraint name: PREcondition

condition

POSTcondition

```

def min(a, b):
    if a > b:
        return b
    else:
        return a

if len(self.queue) > 1 and (self.changed == "false"):
    car_behind = self.queue[1]
    velocity = car_behind[1]
    entry_time = car_behind[2]
    time_left = min(car_behind[3], self.time_left)
    if time_left < self.time_left:
        self.queue = self.queue[1:]
        self.changed = "true"
        self.current_time = self.current_time + self.time_l
        self.time_left = time_left
        return True
    else:
        return False
  
```

internal transition

Editing ATOM3Constraint

Constraint name: PREcondition

timeAdvance

POSTcondition

```

# This is the time-advance function for this state.
# By default it returns INFINITY

if self.changed == "false":
    return self.time_left
elif self.changed == "true":
    return 0
else:
    return INFINITY
  
```

time advance

Editing externalTransitionV2

Constraint name: PREcondition

condition

POSTcondition

```

# This is an external transition.
# It should return a boolean, meaning whether the transition
# will take place or not depending on the input state, the
# elapsed time, and the inputs.
# The current state is accessed by the variable s.
# The elapsed time is accessed by the variable e.
# The inputs are accessed by the names of the corresponding input ports.

for input in imports_list:
    input_name = input[0]
    input_val = input[1]
    if input_val == "green":
        if (input_name[-8:] == "_str_in") and (input_value == "green") and (self.
ahead_status == "full") and (self.changed == "false"):
            self.traffic_light = input_value
            self.current_time = self.current_time + e
            self.time_left = 0
            return True
return False
  
```

external transition

Editing ATOM3Action

Action name: lambda

PREAction

POSTAction

```

# This is the output function for this state.
# It should assign values to the output ports.
# By default the output ports are assigned None.
# Each output port can be accessed by its name.

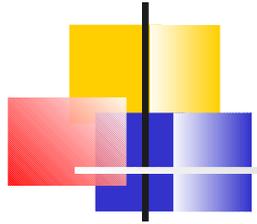
for output in self.outputs_list:
    output_name = output[0]
    output_handle = output[1]

    output_value = None
    if output_name[-9:] == "_info_out":
        if len(self.queue) == self.capacity:
            output_value = "full"
        elif len(self.queue) > 0:
            elif (len(self.queue) > 0) and (len(self.queue) < self.capacity):
                output_value = "neither"

    self.poke(output_handle, output_value)
    print "\n\n----- Local status changed " + str(output_value)

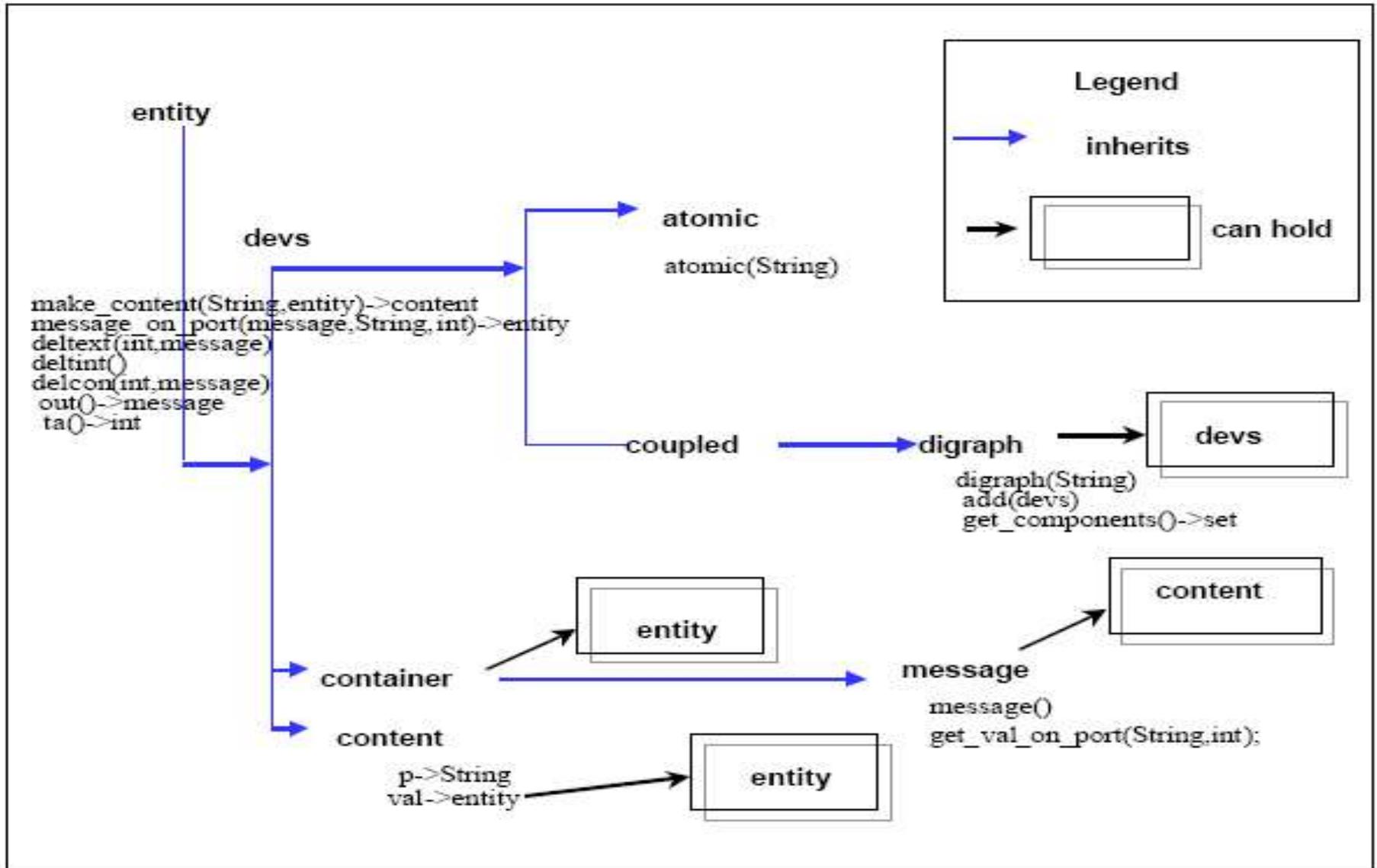
return
  
```

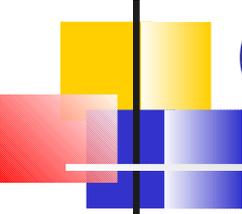
output function



- Introduction
 - TimedTraffic Formalism
 - DEVS Formalism
- Map TimedTraffic to DEVS
 - Meta-Modeling
 - TimedTraffic Meta-Model
 - DEVS Meta-model
 - Model Transformation
 - Code Generation
- Demo
- Conclusion

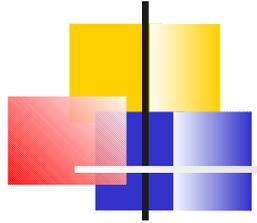
DEVSJAVA Class hierarchy of DEVS classes





Conclusion

- AToM3 is an amazing tool!
- Pure graphical translation from **DEVS** or other formalism to a real programming language such as **Python** or **Java**?
- Using neutral language to describe specific cases in transformation rules?



Thank you!