



Valid deployment of Models-of-the-physics using Validity Frames

Bert Van Acker



02:40.33

CIRCUIT OF THE AMERICAS AUTONOMOUS LAP RECORD

AUSTIN, TX. FEB 23rd 2017

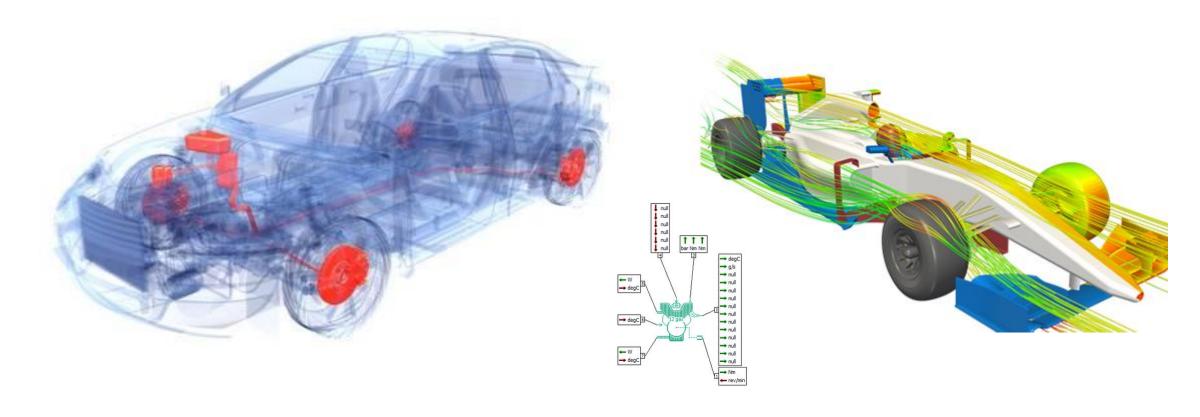
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NÜRBURGRING NORDSCHLEIFE LAP RECORD

GERMANY, MAY 12th 2017

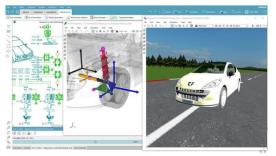


Pushing the boundaries of Cyber-physical systems









High-fidelity model

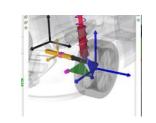
Reality

topia

$$m_1 \ddot{x}_1 = -b_1 \dot{x}_1 - k_1 x_1 + k_2 (x_2 - x_1)$$

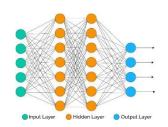
$$m_2 \ddot{x}_2 = -k_2 (x_2 - x_1) + k_3 (y - x_2) - b_2 \dot{x}_2$$

or



Reductions/approximations

or



Or ...

Constraint system

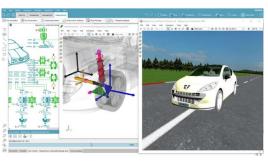
- -> [MEMmin, MEMmax]
- -> [COMPmin,COMPmax]
- -> Hard real-time!

-> ...



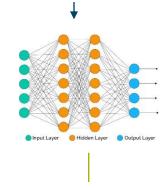






High-fidelity model

Reductions/approximations



Discretization/fixed-pointing/...

Constraint system

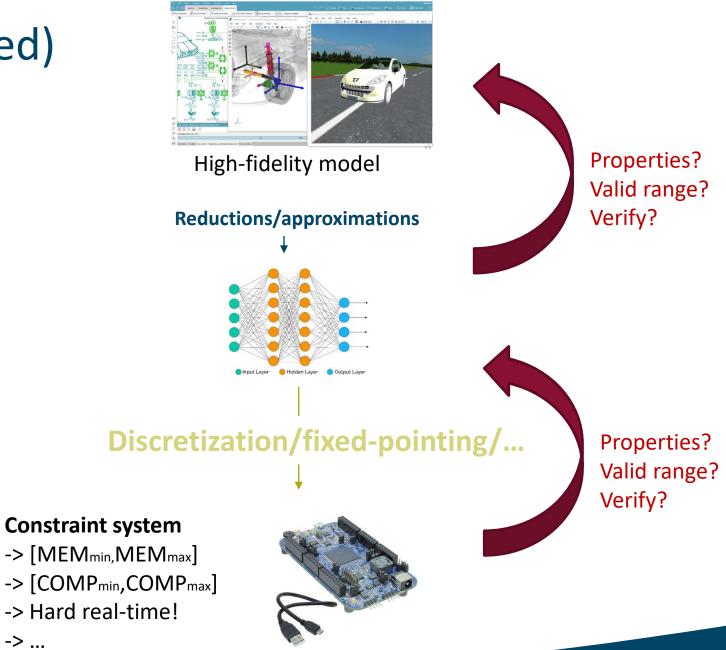
- \rightarrow [MEMmin,MEMmax]
- -> [COMPmin,COMPmax]
- -> Hard real-time!

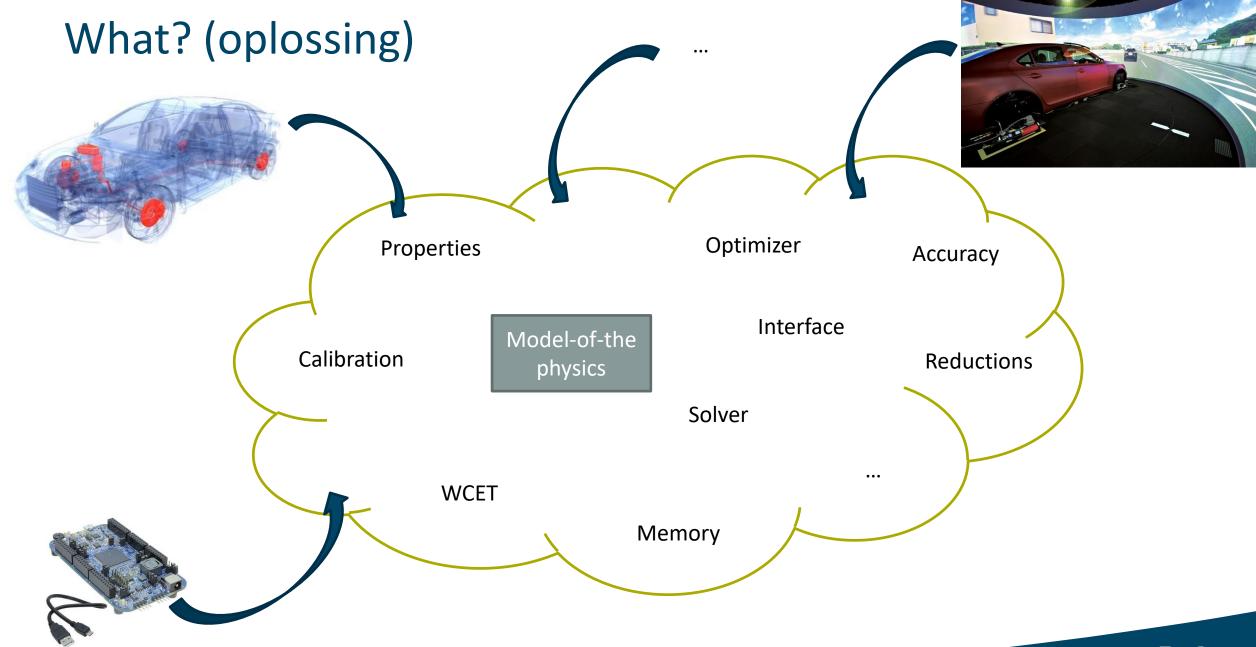
-> ...

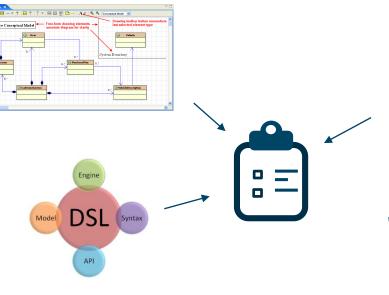


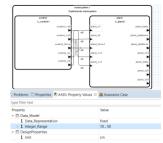
-> ...







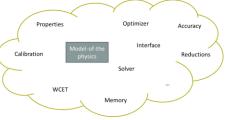




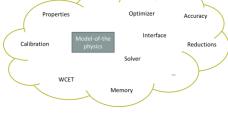


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Validity frame











Plant model

Plant model

Adaptive real-time control systems

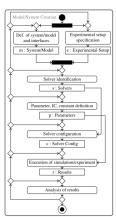


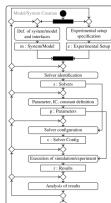
Component (re-)usability

Calibration processes

Experimenter processes

Integration processes





Roadmap (evolution 5j.)

