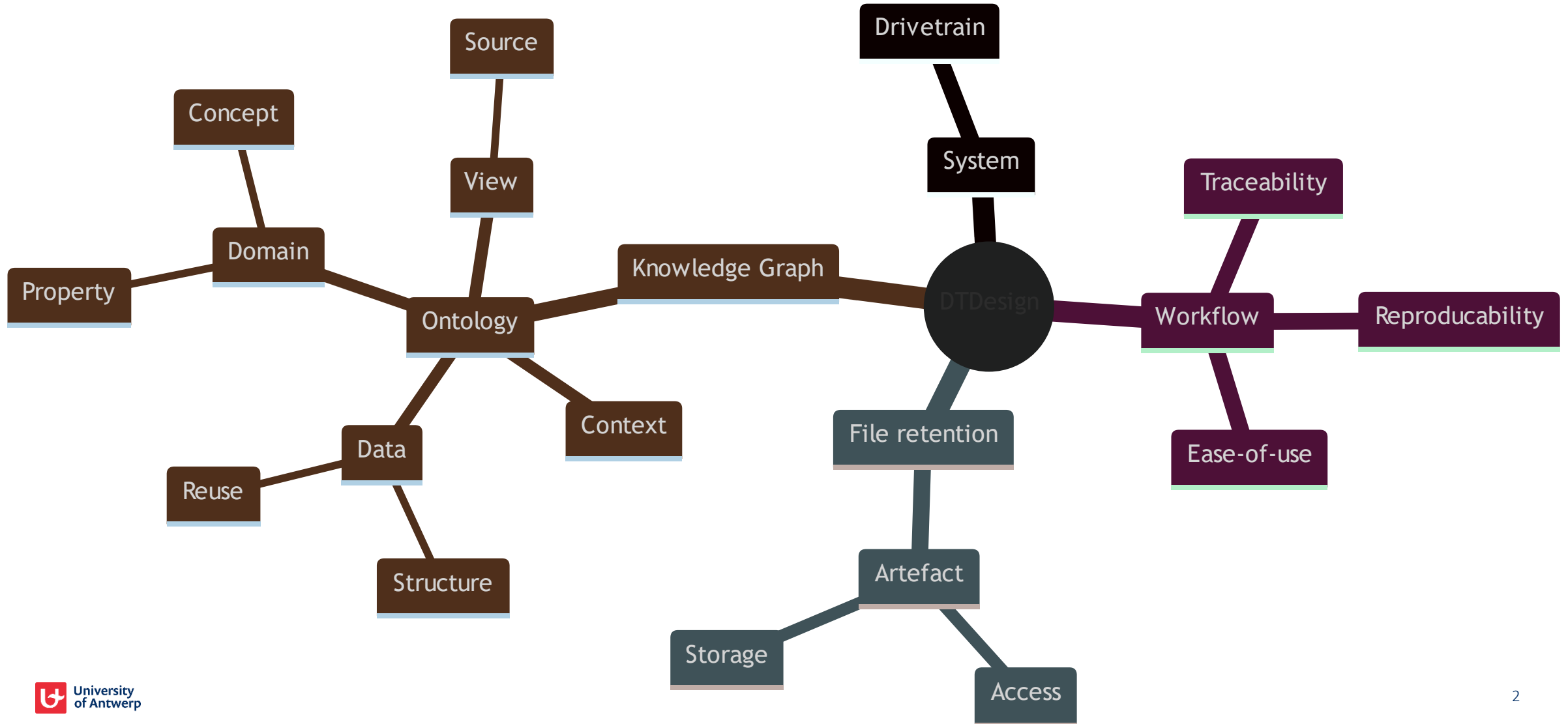


Digital Twin Design

Drivetrain workflow explained

What is Digital Twin Design about?



What are we using as the use case?





Context is important

while managing data/information/knowledge

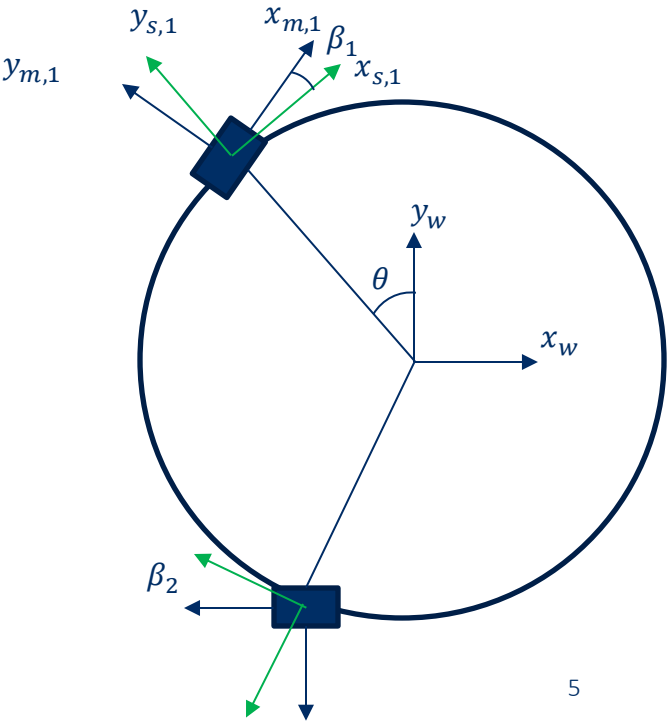
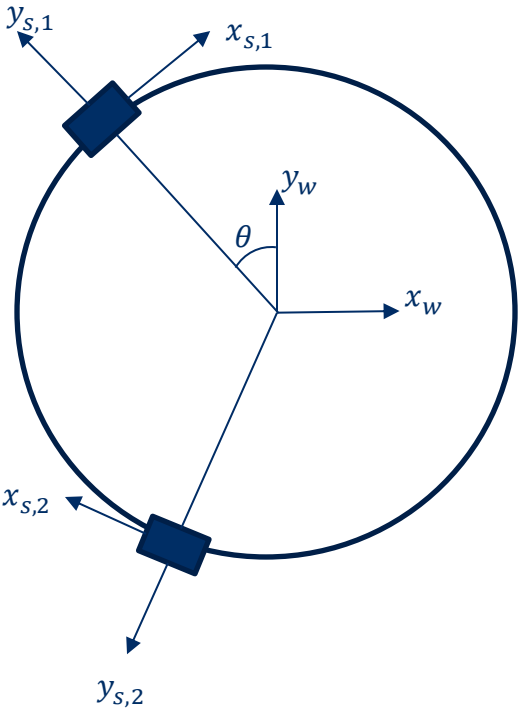
because it allows for more reproducible results

```

C:.\
├── 2D corrected x and y sensors
│   ├── codegen
│   │   └── mex
│   │       ├── kinematic_estimator_2D_original
│   │       │   └── interface
│   └── 2D lateral only cross coupling
│       ├── codegen
│       │   └── mex
│       │       ├── kinematic_estimator_2D_original
│       │       │   ├── interface
│       │       └── kinematic_estimator_2D_residual
│       │           └── interface
│   └── 2D only lateral acceleration
│       ├── codegen
│       │   └── mex
│       │       └── kinematic_estimator_2D_residual
│       │           └── interface
│   └── 2D only lateral acceleration updated
│       ├── codegen
│       │   └── mex
│       │       ├── kinematic_estimator_2D_original
│       │       │   ├── interface
│       │       └── kinematic_estimator_2D_residual
│       │           ├── html
│       │           └── interface
│   ├── codegen
│   │   └── mex
│   │       ├── kinematic_estimator_2D
│   │       │   └── interface
│   │       └── kinematic_estimator_2D_residual

```

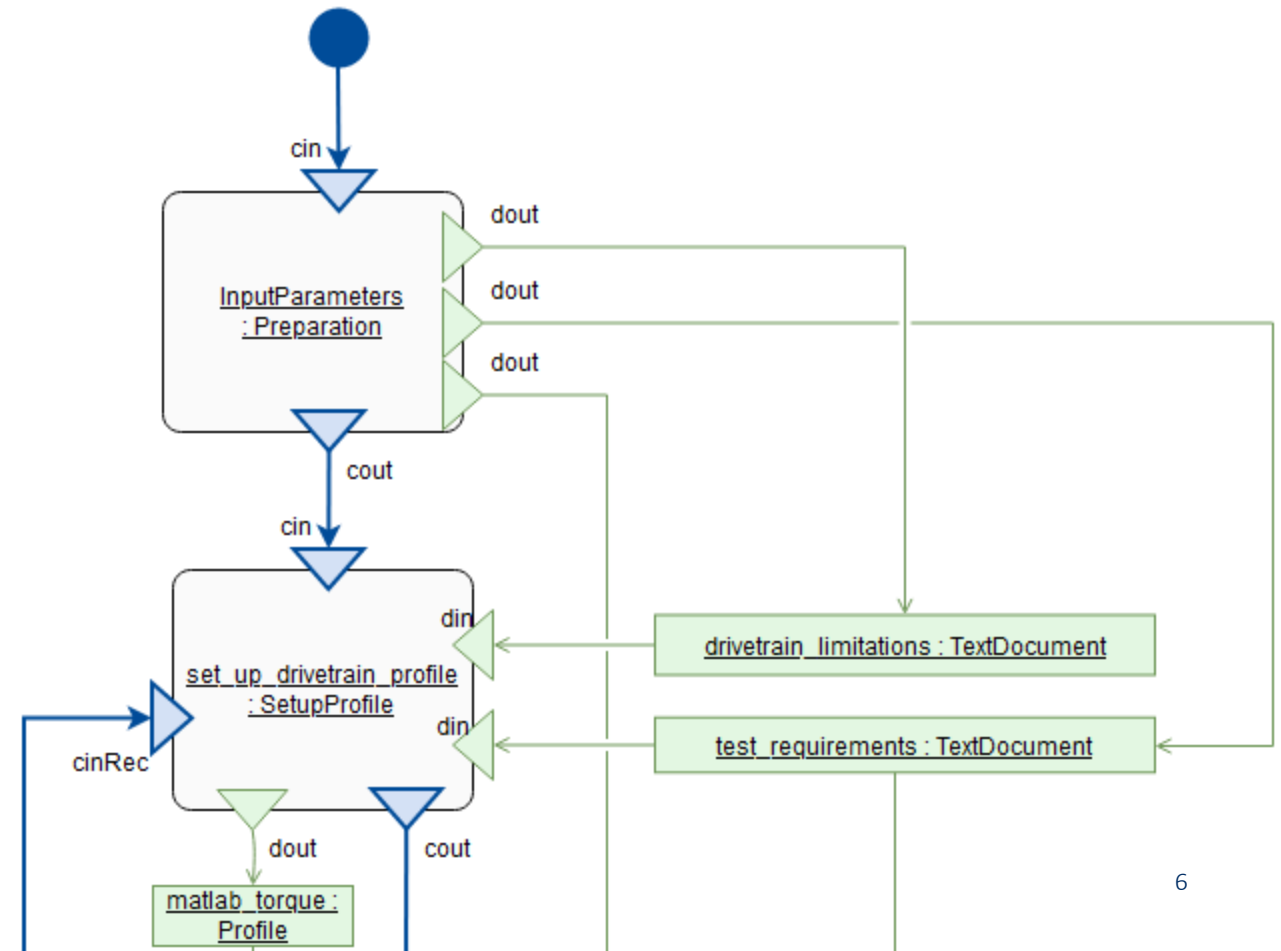
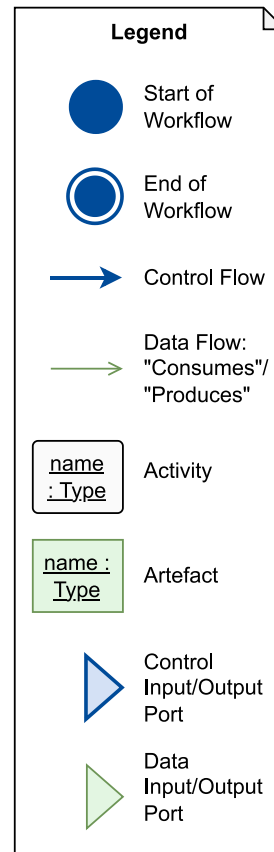
We have a problem...





A wild solution appears!

Virtual Knowledge Graph?



Answering the 3 'W'!

Why was an experiment performed?

What changed between design iterations?

~~W~~ **How** did a model perform?

Queries
Visual

A few tools

End user facing

- Drawio
- Graph Exploring Tool
- Workflow Enactment Engine

Backend

- Fuseki
- SpEndpoint
- Backend :)

Transient

- OML Tooling

+ A bunch more

Let's do a quick demo

Modelling Environment

Workflow Enactment Engine

Trace visualisation

Graph Exploring Tool

Search Shapes

Scratchpad

FTG+PM - Common

FTG+PM - FTG

FTG+PM - PM

FTG+PM - Trace

FTG+PM - S/S

General

+ More Shapes

Knowledge Graph...

Create traceability link to...

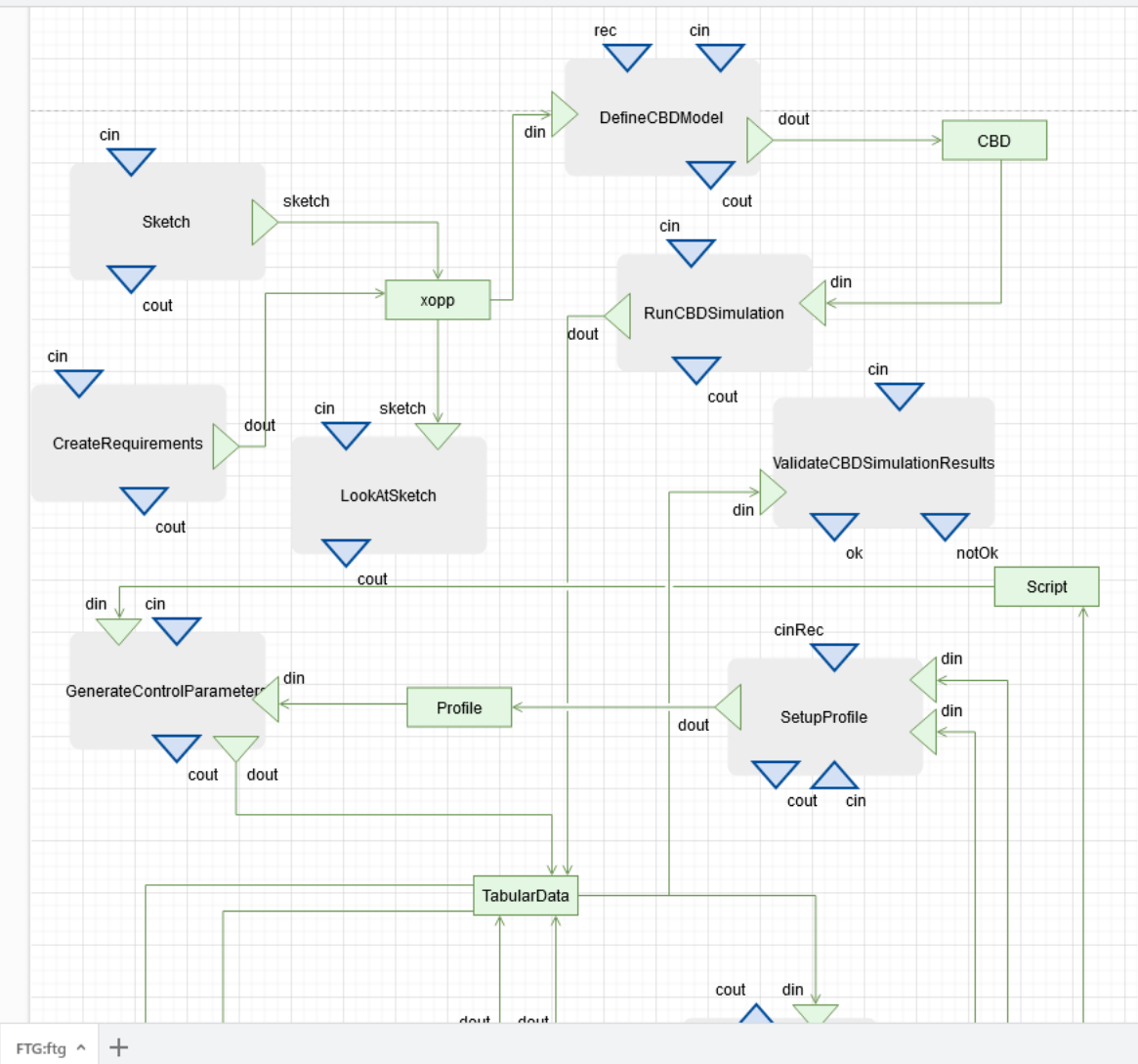
Undo

Clear Default Style

Select All

Select Vertices

Select Edges



ModelVerse

FTG.ftg Open

FTG.ftg Open

MinimalPM.pm Open

PM Enactment: Start New...

MyPM.pm Open

PM Enactment: Start New...

Open "pt_1" (ongoing)

Open "start_trace_event" (finished)

MyPMRec.pm Open

PM Enactment: Start New...

SpringDamperSimulation.pm Open

PM Enactment: Start New...

Open "pt_0" (ongoing)

drivetrain.pm Open

Diagram Style

View

Grid 10 pt

Page View

Background Change...

Background Color

Shadow Sketch

Options

Connection Arrows

Connection Points

Guides

Paper Size

US-Letter (8,5" x 11")

Portrait Landscape

Edit Data...

Clear Default Style

Wee: Workflow Enactment Engine

Choose the Process Model to be enacted:

▾ [New Enactment](#)

Continue enactment: ▾ [Continue Enactment](#)

Workflow Enactment Engine

Enacting the Process Model: PM [drivetrain_pm](#)

Select activity to start:

 [Start Activity](#)

Trace: [pt_3](#)

Started at: 22/06/2023 11:27:00

Workflow Enactment Engine

Enacting the Process Model: PM **drivetrain_pm**

Select output port of Activity: ACTIVITY **InputParameters**

cout ▾

Artifacts

Name: [drivetrain_limitations](#)

Type: [TextDocument](#)

Choose a file... file.extension

Name: [test_requirements](#)

Type: [TextDocument](#)

Choose a file... file.extension

Name: [control_parameter_generator](#)

Type: [Script](#)

Choose a file... file.extension

End Activity

Trace: [pt_3](#)

Started at: 22/06/2023 11:27:00

Begin: [InputParameters](#)

Port: [cin](#)

Workflow Enactment Engine


Enacting the Process Model: PM drivetrain_pm


Select activity to start:

▼ Start Activity

Trace: [pt_3](#)
Started at: 22/06/2023 11:27:00
Begin: [InputParameters](#)
Port: [cin](#)
End: [InputParameters](#)
Port: [cout](#)

Artifacts

 **drivetrain_limitations** TextDocument
[Download](#)

 **test_requirements** TextDocument
[Download](#)

Workflow Enactment Engine

Enacting the Process Model: PM drivetrain_pm

Select activity to start:

END TRACE ▾ Start Activity

End Enactment

Trace: pt_3
Started at: 22/06/2023 11:27:00
Begin: InputParameters
Port: cin
End: InputParameters
Port: cout
Begin: set_up_drivetrain_profile
Port: cin
End: set_up_drivetrain_profile
Port: cout
Begin: Generate_matlab_control_parameters
Port: cin
End: Generate_matlab_control_parameters
Port: cout
Begin: Build_simulink_control_settings
Port: cin
End: Build_simulink_control_settings
Port: cout
Begin: run_experiment
Port: cin
End: run_experiment
Port: cout
Begin: check_properties
Port: cin
End: check_properties
Port: cout

Workflow Enactment Engine

Enactment of the Process Model: drivetrain_pm has ended!

[HOME](#)

Trace: pt_3

Started at: 22/06/2023 11:27:00

Begin:

InputParameters

port: cin

End:

InputParameters

port: cout

Begin:

set_up_drivetrain_profile

port: cin

End:

set_up_drivetrain_profile

port: cout

Begin:

Generate_matlab_control_parameters

port: cin

End:

Generate_matlab_control_parameters

port: cout

Begin:

Build_simulink_control_settings

port: cin

End:

Build_simulink_control_settings

port: cout

Begin:

run_experiment

port: cin

Scratchpad

Drag elements here

FTG+PM - Common

FTG+PM - FTG

FTG+PM - PM

FTG+PM - Trace

FTG+PM - S/S

General

+ More Shapes

Knowledge Graph...

Create traceability link to...

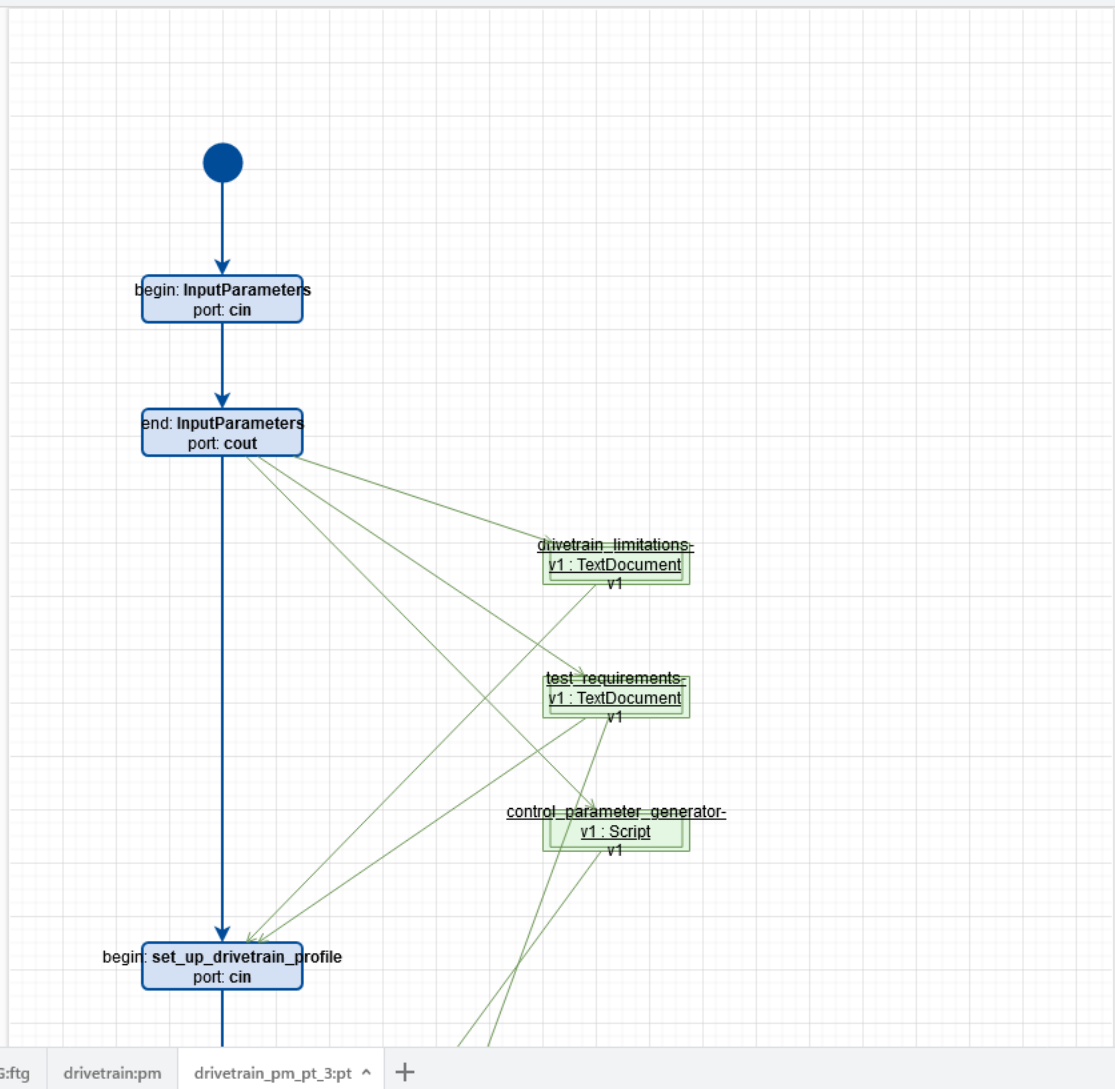
Undo

Clear Default Style

Select All

Select Vertices

Select Edges



ModelVerse

drivetrain.pm Open

PM Enactment: Start New...

Open "pt_0" (ongoing)

Open "pt_1" (ongoing)

Open "pt_2" (finished)

Open "pt_3" (finished)

drivetrain_pm_pt_0.pt Open

drivetrain_pm_pt_3.pt Open

imabox Open

Save Current Page

Models — xopp

SmallXournalFile.xopp Download

TwoHiddenLayers.xopp Download

Upload xopp:

Browse... No file selected.

Diagram Style

View

Grid 10 pt

Page View

Background Change...

Background Color

Shadow Sketch

Options

Connection Arrows

Connection Points

Guides

Paper Size

A4 (210 mm x 297 mm)

Portrait Landscape

Edit Data...

Clear Default Style

Search Shapes

Scratchpad

FTG+PM - Common

FTG+PM - FTG

FTG+PM - PM

FTG+PM - Trace

FTG+PM - S/S

General

+ More Shapes

```

sequenceDiagram
    participant A as begin: InputParameters  
port: cin
    participant B as end: InputParam  
port: cout
    participant C as begin: set_up_drivetr  
port: cin
    participant D as end: set_up_drivetr  
port: cout
    A-->>B
    B-->>C
    C-->>D
    
```

ModelVerse

Style

Text

Arrange

Is rendered as vertex "3ysiSsKd6ELKGWJQFr0aDdZ9ub4-2"

Enactment of ctrl import "cin"

Is rendered as vertex "3ysiSsKd6ELKGWJQFr0aDdZ9ub4-2"

Models — drawio

AnotherPM:pm Open

PM Enactment: Start New...

FTG:ftg Open

FTG:ftg Open

MinimalPM:pm Open

PM Enactment: Start New...

MyPM:pm Open

PM Enactment: Start New...

Open "pt_1" (ongoing)

Open "start_trace_event" (finished)

Property Value

▼ Individuals

Find Individuals

Find Properties

▼ Info

Get Class Label Descriptio

▼ Service

Conversion Function

Example Function

Outlier Function

▼ Traceability

Find Class Property

Find Older Versions

Find PM Relation

Match Artifact Formalism

▼ Types

Find Types

```
SELECT DISTINCT ?from ?output ?atname WHERE {  
  ?from a {{{ from_class }} .  
  ?from {{{ relation }}} ?output .  
  ?output a {{{ to_class }} .  
  ?output {{{ extra_relation }}} ?atname .  
}
```

ftg:Transformation

Which starting class?

ftg:outputs

Relation between the classes?

ftg:Formalism

The ending class?

base:hasName

End class relation?

Query

Save

Load

Using visual template 'Find PM Relation'.

- ▼ Individuals
 - Find Individuals
 - Find Properties
- ▼ Info
 - Get Class Label Descriptio
- ▼ Insert
 - Create Example
- ▼ Service
 - Conversion Function
 - Example Function
 - Outlier Function
- ▼ Traceability
 - Find Class Property
 - Find Older Versions
 - Find PM Relation
 - Match Artifact Formalism
- ▼ Types
 - Find Types

```
SELECT ?outlier ?outlier_relation ?outlier_value WHERE {
  SERVICE <http://127.0.0.1:8000/> {
    SELECT ?outlier ?outlier_relation ?outlier_value WHERE {
      BIND(dtf:outlier("rotation.csv", "2", "<http://ua.be/drivetrain/description/artifacts/artifacts#drivetrain-sensor-data-v1>") AS
    }
  }
}
```

▼ Individuals

Find Individuals

Find Properties

▼ Info

Get Class Label Descriptio

▼ Insert

Create Example

▼ Service

Conversion Function

Example Function

Outlier Function

▼ Traceability

Find Class Property

Find Older Versions

Find PM Relation

Match Artifact Formalism

▼ Types

Find Types

```

SELECT ?outlier ?outlier_relation ?outlier_value WHERE {
  SERVICE <{{ service_endpoint }}> {
    SELECT ?outlier ?outlier_relation ?outlier_value WHERE {
      BIND(dt:outlier("{{ outlier_file }}", "{{ outlier_column }}", "{{ outlier_artifact }}") AS ?outlier)
    }
  }
}

```

http://127.0.0.1:8000/

Which service do you want to use?

rotation.csv

In which file is the outlier located?

2

In which column?

<http://ua.be/drivetrain/description/artifacts/artifacts#drivetrain-sen

In which artifact?

Query Save Load

Query successful.

Results

dart:drivetrain-sensor-data-v1-cell-4	< http://ua.be/s	dart:drivetrain-sensor-data-v1-row-46782	
dart:drivetrain-sensor-data-v1-cell-3	owl:sameAs	dart:drivetrain-sensor-data-v1-cell-300662	
dart:drivetrain-sensor-data-v1-cell-4	owl:sameAs	dart:drivetrain-sensor-data-v1-cell-467822	
dart:drivetrain-sensor-data-v1-cell-4	rdf:type	owl:Thing	
dart:drivetrain-sensor-data-v1-cell-3	rdf:type	http://ua.be/sdo21/vocabulary/formalism/file#Data	
dart:drivetrain-sensor-data-v1-cell-3	http://ua.be/s	dart:drivetrain-sensor-data-v1-row-30066	
dart:drivetrain-sensor-data-v1-cell-4	http://ua.be/s	dart:drivetrain-sensor-data-v1	
dart:drivetrain-sensor-data-v1-cell-4	http://ua.be/s	2	
dart:drivetrain-sensor-data-v1-cell-3	http://ua.be/s	dart:drivetrain-sensor-data-v1	
dart:drivetrain-sensor-data-v1-cell-4	http://ua.be/s	dart:drivetrain-sensor-data-v1-column-2	
dart:drivetrain-sensor-data-v1-cell-4	rdf:type	http://ua.be/sdo21/vocabulary/formalism/tabular#Cell	
dart:drivetrain-sensor-data-v1-cell-3	rdf:type	owl:Thing	

We're currently looking into

Increasing the middleware transparency

Adding automated activities

Doing performance modelling



University
of Antwerp